

CALIFORNIA INSTITUTE OF TECHNOLOGY  
Control and Dynamical Systems

**ACM/CDS 202**

**Problem Set #1**

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Spring 2013

Issued: 15 Apr 2013  
Due: 24 Apr 2013

Reading: Abraham, Marsden, and Ratiu, Sections 2.3–2.4, 3.1–3.3

Problems:

1. [Guillemin and Pollack, page 5, #3]

Let  $M$ ,  $N$ , and  $P$  be smooth manifolds and let  $f : M \rightarrow N$  and  $g : N \rightarrow P$  be smooth maps.

- (a) Show that the composite map  $g \circ f : M \rightarrow P$  is smooth.  
(b) Show that if  $f$  and  $g$  are diffeomorphisms, so is  $g \circ f$ .

(You may use the fact that the composition of smooth functions between open subsets of Euclidean spaces are smooth.)

2. [Boothby II.1.2] Using stereographic projection from the north pole  $N(0, 0, +1)$  of all of the standard unit sphere in  $\mathbb{R}^3$  except  $(0, 0, +1)$  determine a coordinate neighborhood  $U_N, \phi_N$ . In the same way determine by projection from the south pole  $S(0, 0, -1)$  a neighborhood  $U_S, \phi_S$  (see figure in Boothby). Show that these two neighborhoods determine a  $C^\infty$  structure on  $S^2$ . Generalize to  $S^{n-1}$ .

3. MTA 3.1-4 (i) and (ii): Manifold structure of the Möbius band.

*Optional:* Try to use your intuition about Möbius band to answer the following questions (then try them to see if you are right):

- Consider a Möbius band of finite width, like the one shown in Figure 3.4.4. What happens is you cut it down the center with a pair of scissors? Is the resulting set a manifold? Is it connected?
- Repeat the experiment, but this time cutting the Möbius band one third of the distance from one of the edges.

4. MTA 3.2-4: Submanifolds are locally closed

5. MTA 3.3-1: Graphs of manifolds