

# CDS 140a Winter 2015 Homework 4

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CDS 140, Winter 2015

(PDF)

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In class or to box across 107 STL

**Note:** In the upper left hand corner of the *second* page of your homework set, please put the number of hours that you spent on this homework set (including reading).

1. **Perko, Section 2.9, problem 3** Use the Lyapunov function  $V(x) = x_1^2 + x_2^2 + x_3^2$  to show that the origin is an asymptotically stable equilibrium point of the system

$$\dot{x} = \begin{bmatrix} -x_2 - x_1x_2^2 + x_3^2 - x_1^3 \\ x_1 + x_3^3 - x_2^3 \\ -x_1x_3 - x_3x_1^2 - x_2x_3^2 - x_3^5 \end{bmatrix}$$

Show that the trajectories of the linearized system  $\dot{x} = Df(0)x$  for this problem lie on circles in planes parallel to the  $x_1, x_2$  plane; hence, the origin is stable, but not asymptotically stable for the linearized system.

2. Determine the stability of the system

$$\begin{aligned} \dot{x} &= -y - x^3 \\ \dot{y} &= x^5 \end{aligned}$$

Hint: motivated by the first equation, try a Lyapunov function of the form  $V(x, y) = \alpha x^6 + \beta y^2$ . Is the origin asymptotically stable? Is the origin globally asymptotically stable?

3. Definition: An equilibrium point is *exponentially stable* if  $\exists M, \alpha > 0$  and  $\epsilon > 0$  such that  $\|x(t)\| \leq Me^{-\alpha t} \|x(0)\|$ ,  $\forall \|x(0)\| \leq \epsilon, t \geq 0$ . Let  $\dot{x} = f(x)$  be a dynamical system with an equilibrium point at  $x_e = 0$ . Show that if there is a function  $V(x)$  satisfying  $k_1 \|x\|^2 \leq V(x) \leq k_2 \|x\|^2, \dot{V}(x) \leq -k_3 \|x\|^2$

for positive constants  $k_1, k_2$  and  $k_3$ , then the equilibrium point at the origin is exponentially stable.

4. **Perko, Section 2.12, problem 2** Use Theorem 1 [Center Manifold Theorem] to determine the qualitative behaviour near the non-hyperbolic critical point at the origin for the system

$$\begin{aligned} \dot{x} &= y \\ \dot{y} &= -y + \alpha x^2 + xy \end{aligned}$$

for  $\alpha \neq 0$  and for  $\alpha = 0$ ; i.e., follow the procedure in Example 1 after diagonalizing the system as in Example 3.

5. Consider the following system in  $\mathbb{R}^2$  :

$$\begin{aligned}\dot{x} &= -\frac{\alpha}{2}(x^2 + y^2) + \alpha(x + y) - \alpha \\ \dot{y} &= -\alpha xy + \alpha(x + y) - \alpha\end{aligned}$$

Determine the stable, unstable, and centre manifold of the equilibrium point at  $(x, y) = (1, 1)$  , and determine the stability of this equilibrium point for  $\alpha \neq 0$  . For determining stability, note that near the equilibrium point there are two 1-dimensional invariant linear manifolds of the form

$M = \{(a_1, a_2) \in \mathbb{R}^2 \mid a_2 = ka_1\}$  ; determine the flow on these invariant manifolds.

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