## CALIFORNIA INSTITUTE OF TECHNOLOGY Control and Dynamical Systems

## CDS 101/110 Course Survey

R. Murray Fall 2004 Issued: 27 Sep 04 Due: 1 Oct 04

The purpose of this survey is to get a sense of the background and level of the students in the class. Please mark your answers in the space provided.

Please turn in this survey by Friday, 1 October, at 5 pm in the box outside of 109 Steele. You may also turn it in after lecture on Wednesday or Friday.

- 1. Which course are you taking (CDS 101, CDS 110a, undecided):
- 2. What is your current option (ME, ChE, CS, Bio, etc)? \_\_\_\_\_ Year (Jr, Sr, G1, G2, etc)? \_\_\_\_\_
- 3. Are you obtaining a minor in CDS (yes, no, maybe)?
- 4. How did you hear about this course? Put a check mark next to all that apply. If you heard about this course in more than one way, please circle the method that was most effective in your choice to attend the first lecture.

Caltech catalog	Faculty advisor	Other students
Option requirements	Option rep	E-mail list
Other faculty	CDS web page	Other:

5. Put a check mark next to any of the following courses that you have already taken. Put a 'C' if you are currently enrolled in the course:

$\_$ ACM 95/100 (complex variables, ODEs)	AM 125 (linear algebra, ODEs)
AM 35 (statics and mechanics)	$\_$ ME 18/ChE 63 (engineering thermo)
ChE 101 (kinetics, reactor design)	$\_$ ChE/BE 210 (cellular engineering)
EE 20 (circuit theory)	EE 111 (signals and systems)
EE 113 (feedback circuits)	$\_$ CS/EE 145ab (computer networking)
CDS 101 (feedback principles)	CDS 140 (dynamical systems)

6. Please rank your understanding of the following topics on a scale of 1 to 5, using the following classification:

1	2	3	4	5
never heard of topic		remember main ideas/concepts		very familiar with topic

Note: it is *completely OK* if you have not heard of many of these topics. The purpose of the survey is to understand that background of the class. We will cover all of the topics in the left two columns in CDS 101 and all of them in CDS 110ab.

<u>matrices</u> and vectors	transfer function	<u>Laplace transform</u>
eigenvalues and eigenvectors	asymptotic stability	sensitivity function
ordinary differential equations	<u></u> gain/phase margin	<u> </u>
frequency response	PID control	Kalman filter

7. Are there any specific applications of feedback and control concepts that you are interested in?