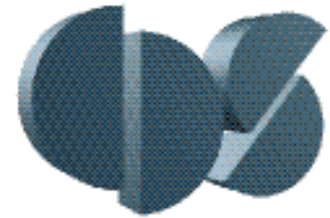




Lecture 3: Examples



Richard M. Murray
Caltech CDS/BE

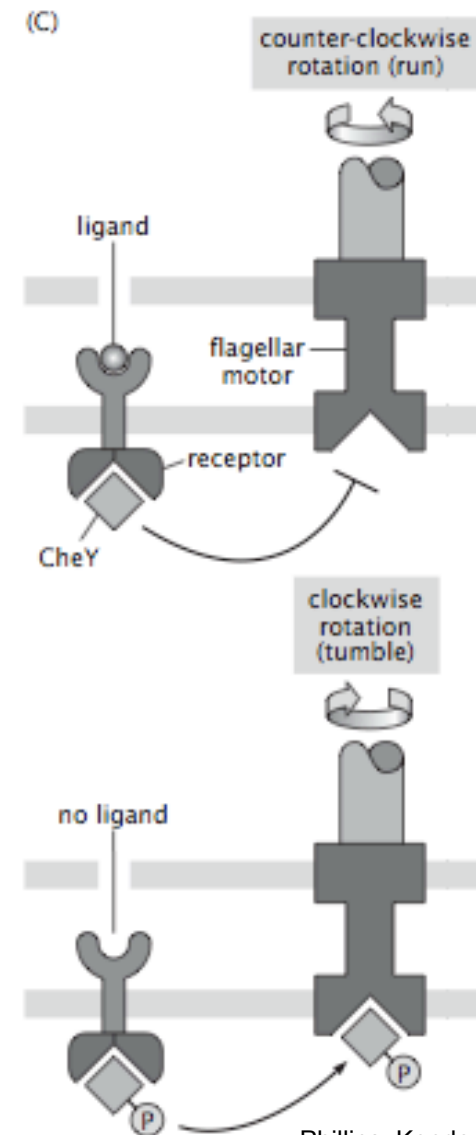
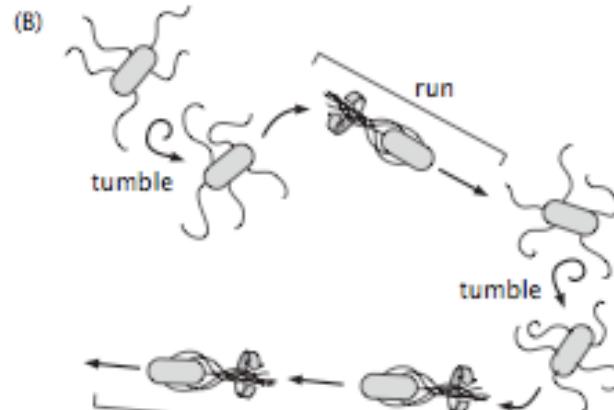
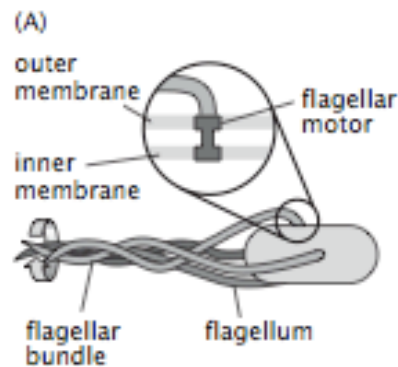
Goals:

- Describe some principles of biological circuits via specific examples
- Provide enough detail to be able to read through reference articles
- Describe modeling techniques, tools and challenges

Examples to be covered

- *Chemotaxis*: what are the sensing, actuation and feedback mechanisms that control movement of bacteria in the presence of nutrient gradients
- *Heat shock*: how does the cell protect itself against environmental disturbances
- *Yeast mating response*: how do yeast respond to pheromones and mate?

Example 1: Chemotaxis



Phillips, Kondev, Theriot (2008)

Basic mechanism

- When ligand (nutrient) is present, CheY protein is inactive and motor turns counter clockwise (run)
- When ligand is not present, CheY activated, binds to motor protein to give clockwise motion (tumble)
- Result: move toward nutrients (on average)
- Circuitry adapts to baseline stimulation level

References

- Barkai and Leibler, *Nature*, 1997
- Rao, Kirby and Arkin, *PLoS Biology*, 2004
<http://www.genomics.princeton.edu/ryulab>

Control Systems operation

Actuation

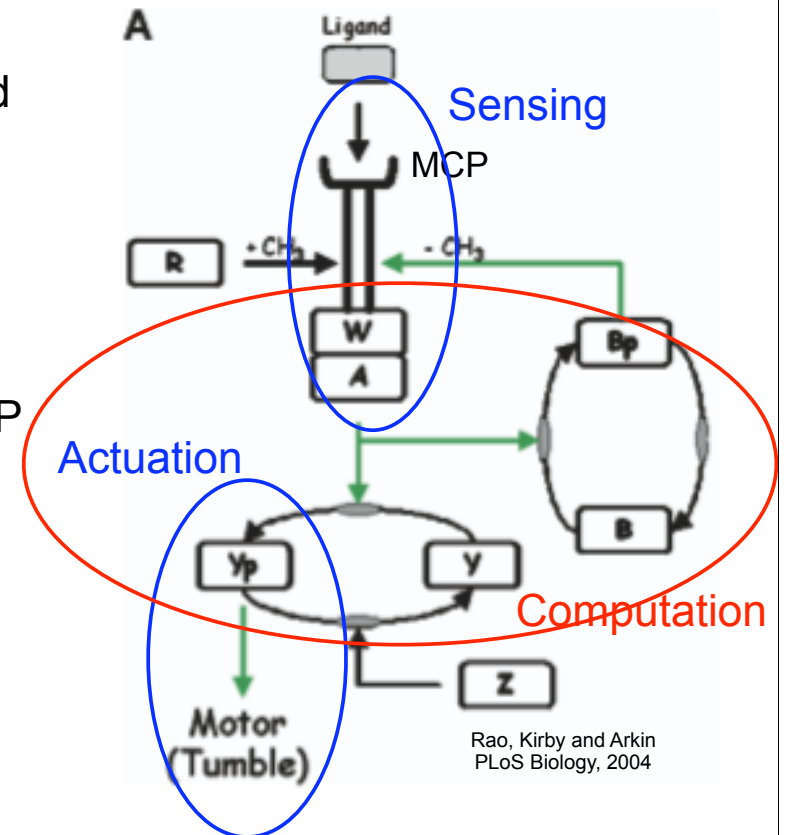
- Phosphorylated CheY (Yp) binds to motor (M) and increases the likelihood of tumbles (vs runs)

Sensing

- Ligand (L) binds to receptor complex (MCP:W:A)
 - MCP is membrane bound receptor
 - ChW (W) and CheA (A) form complex w/ MCP

Computation

- CheA phosphorylates (Ap) and transfers phosphate group to CheY (“kinase”)
 - CheA activity depends on methylation of receptor complex: more methylation => more activity
- CheR (R) methylates receptor complex
- CheBp (Bp) demethylates receptor complex
 - Amount of CheBp is affected by amount of active CheA (Ap) - negative feedback loop
- Additional effects: CheZ, motor binding (M:Yp), ...



Dynamics: Forward Information Processing

Motor dynamics controlled by receptor complex T

- Complex can be active or inactive, depending on both methylation and whether ligand is bound

$$T^A = \sum_{i=0}^4 \alpha_i(L) T_i, \quad \alpha_i(L) = \frac{a_i L}{K_L + L} + \frac{a_i^0 K_L}{K_L + L}$$

$$T^I = \sum_{i=0}^4 (1 - \alpha_i(L)) T_i$$

- T_i = concentration of receptor complex with i methylation sites occupied ($i \in \{0, 1, 2, 3, 4\}$)
- $\alpha_i(L)$ = probability that receptor complex with i methylation sites occupied is active; L = ligand concentration

Receptor complex drives CheY and CheB via Ap

- Use standard mass action to keep track of species:

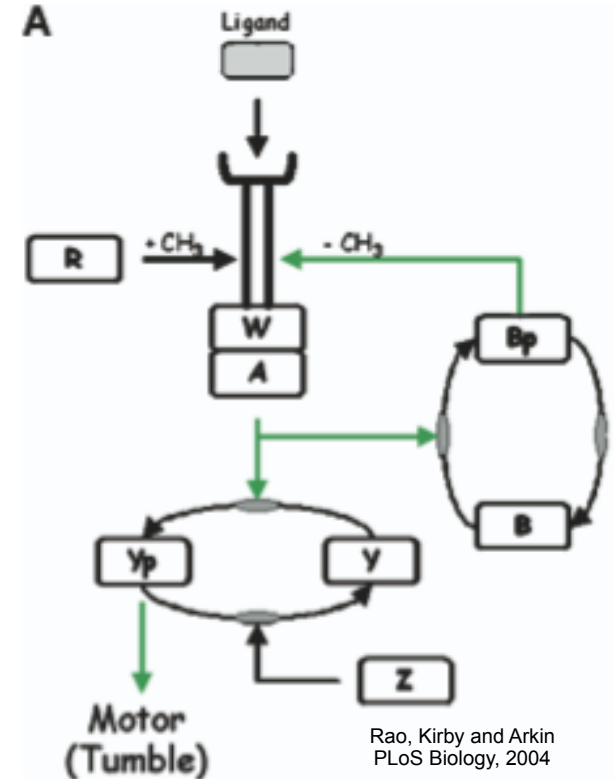
$$\frac{dA_p}{dt} = 50T^A A - 100A_p Y - 30A_p B,$$

$$\frac{d[MY_p]}{dt} = 5MY_p - 19[MY_p],$$

$$[MY_p] = M:Y_p$$

$$\frac{dY_p}{dt} = 100A_p Y - 0.1Y_p - 5MY_p + 19[MY_p] - 30Y_p,$$

$$\frac{dB_p}{dt} = 30A_p B - B_p.$$



Adaptation via Methylation

Keep track of occupied receptors w/
different numbers of methylated sites

- $E_i^u = i$ methylated sites, no ligand
- $E_i^o = i$ methylated sites, w/ ligand
- Transitions follow standard mass action kinetics
- Notational switch: $T_i = E_i^u + E_i^o$
- Use $\alpha_i(L)$ to capture aggregate effect of ligand binding

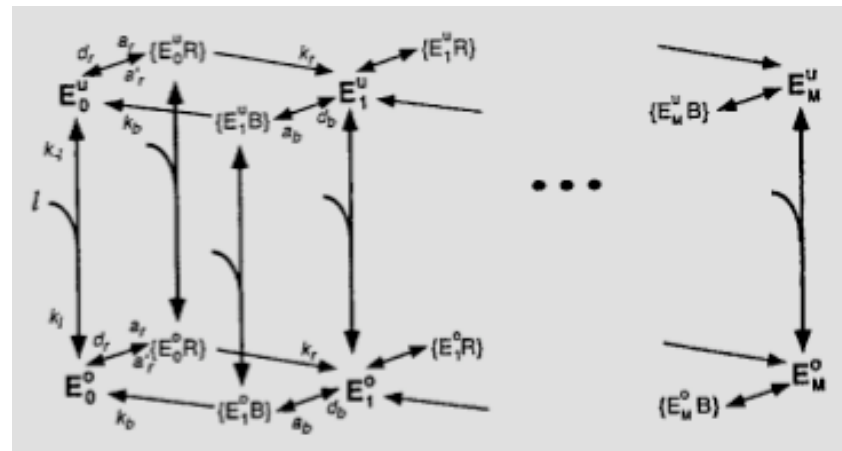
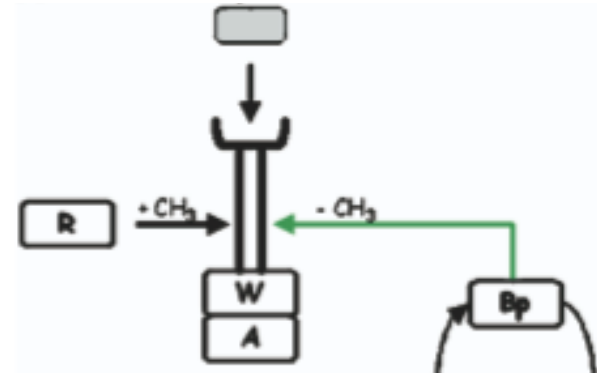
$$\alpha_i(L) = \frac{a_i L}{K_L + L} + \frac{a_i^0 K_L}{K_L + L}$$

- Additionally assume Michaelis-Menten kinetics for CheR, CheB actions

$$\frac{dT_0}{dt} = -r_R(1 - \alpha_0(L))T_0 + r_B\alpha_1(L)T_1,$$

$$\frac{dT_1}{dt} = -r_R(1 - \alpha_1(L))T_1 + r_B\alpha_2(L)T_2 + r_R(1 - \alpha_0(L))T_0 - r_B\alpha_1(L)T_1,$$

$$\frac{dT_2}{dt} = -r_R(1 - \alpha_2(L))T_2 + r_B\alpha_3(L)T_3 + r_R(1 - \alpha_1(L))T_1 - r_B\alpha_2(L)T_2,$$



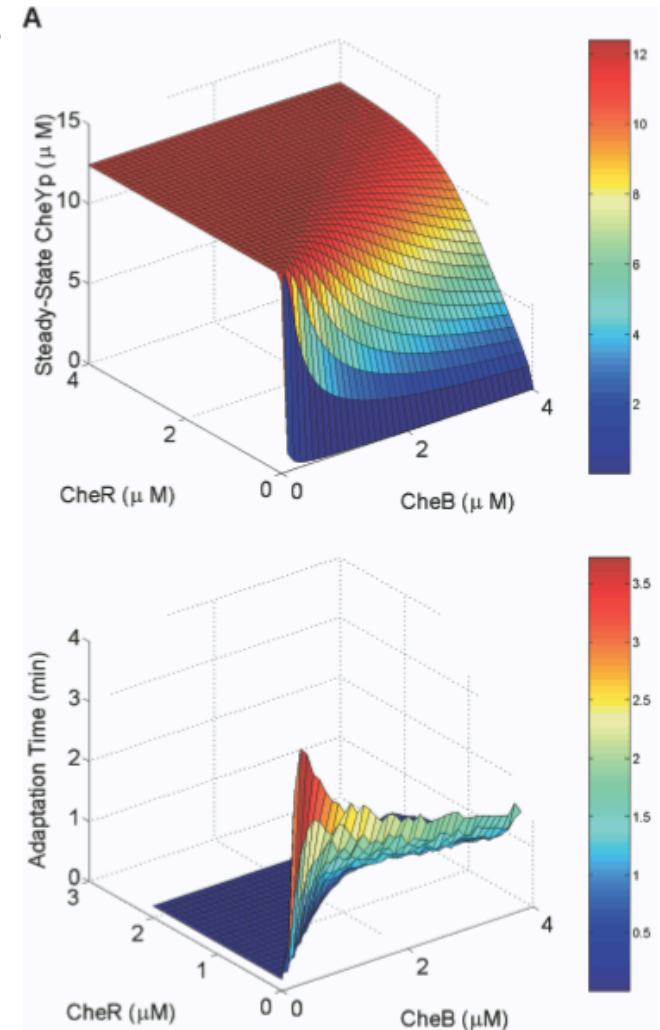
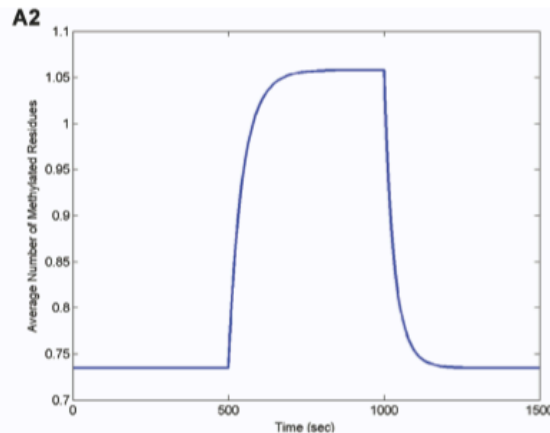
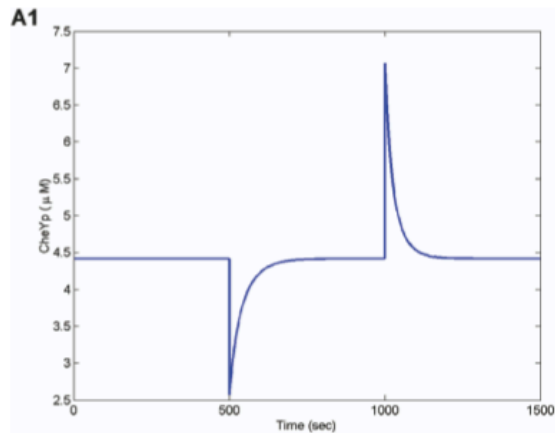
$$r_B = \frac{k_b B_p}{K_B + T^A}$$

$$r_R = \frac{k_r R}{K_R + T^I}$$

Simulations and Analysis

Model-based analysis to study robustness properties

- Deterministic ODE; 9 states, 19 parameters
- Simulations (below) show adaptive response
 - Pulse ligand concentration up and down
 - CheYp maintains constant value after transient
 - Average number of methylated receptors serves as integrator to keep track of disturbance level
- Parametric studies show the effects of CheR/CheB
 - Adaptation is relatively robust, but adaptation time can vary significantly



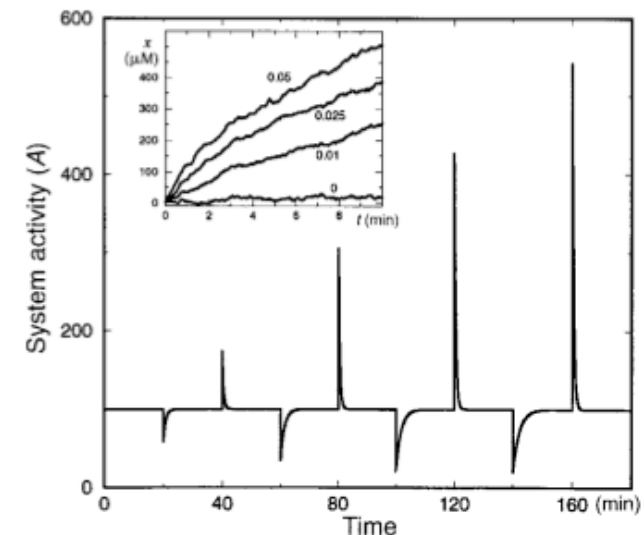
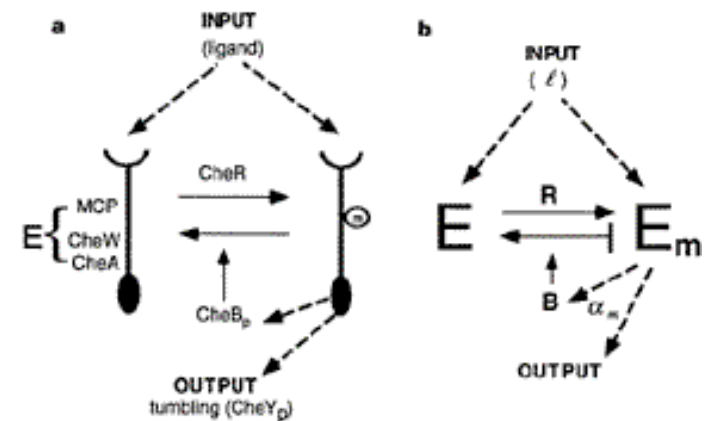
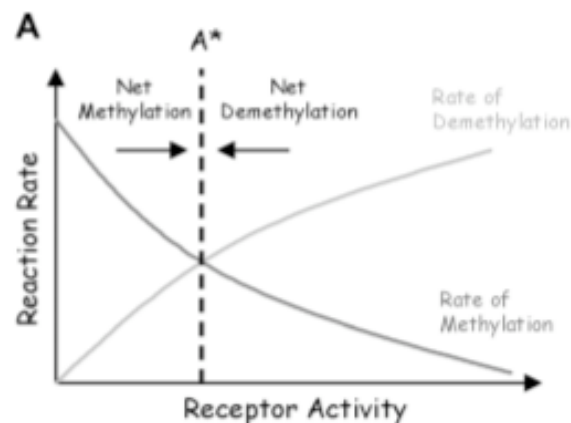
Reduced-Order Modeling (Barkai and Leibler)

Construct reduced order model to explore adaptation mechanism

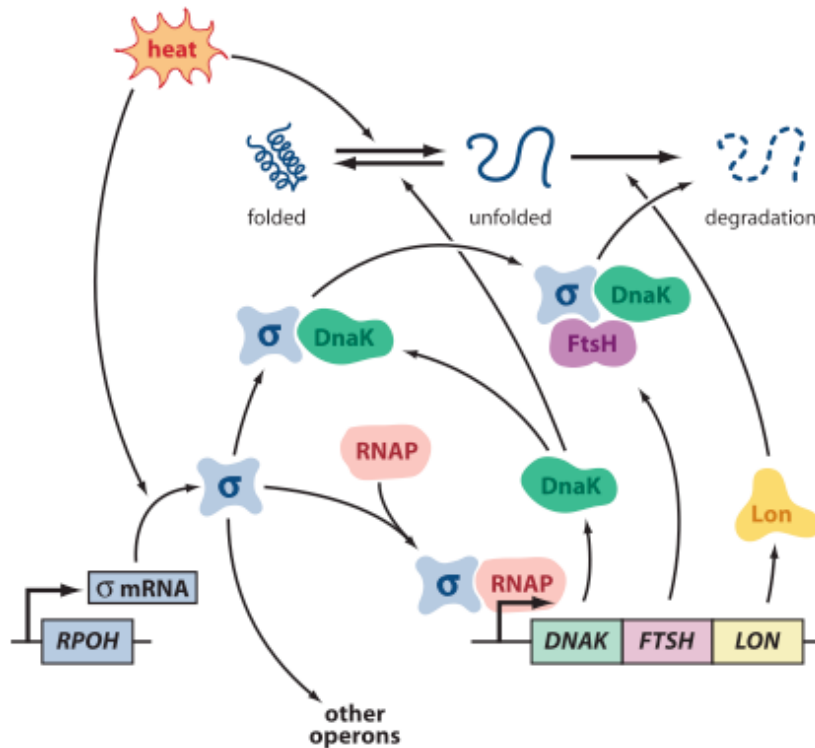
- Model entire receptor complex as a single complex (E) that can be modified (E_m) by enzymes R and B
- Can model the resulting amount of receptor methylation using a single ODE:

$$\frac{dm}{dt} = \frac{k_R R T^I}{K_R + T^I} - \frac{k_B B_p T^A}{K_B + T^A}$$

- Inactive complex increase rate of methylation, active complexes decrease rate of methylation
=> get balance based on activity level



Example #2: Heat Shock Response



El-Samad et al, 2005

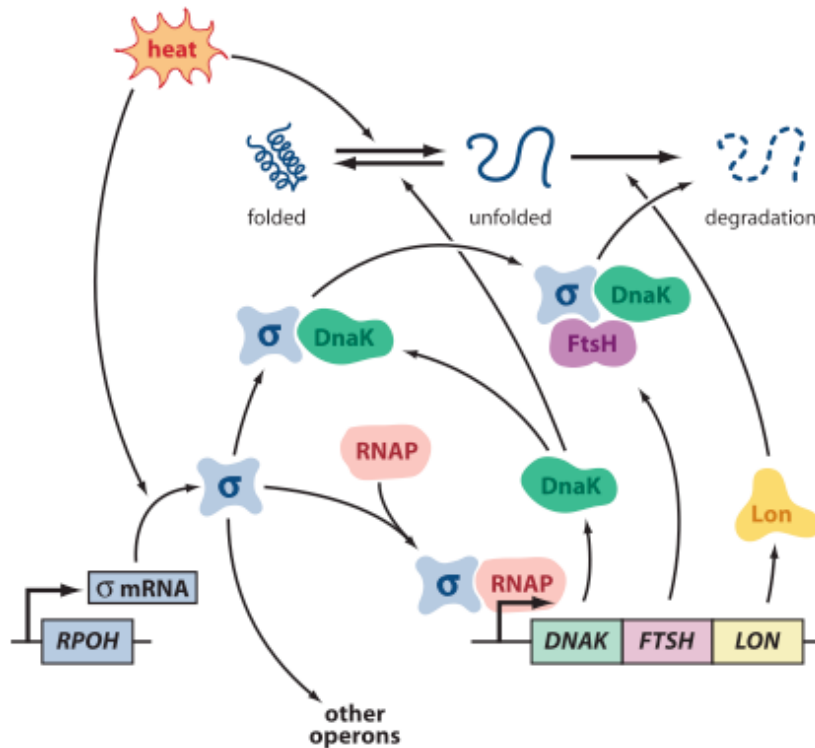
Heat Shock (HS) Response

- Heat causes proteins to become unfolded and lose function
- Cell responds in two ways
 - Creates “chaperone” proteins that refold denatured proteins
 - Creates “proteases” that degrade non-functional proteins
- Circuitry (right) contains a number of additional feedback loops that appear to play some role

References

- H. El-Samad, Kurata, Doyle, Gross, Khammash, “Surviving heat shock: Control strategies for robustness and performance”. PNAS, 2005.

Heat Shock Response Components



El-Samad et al, 2005

Sigma factors

- In bacteria, RNAP requires “sigma factors” to bind to DNA
- σ^{70} is sigma factor for standard proteins
- σ^{32} is sigma factor for HS proteins

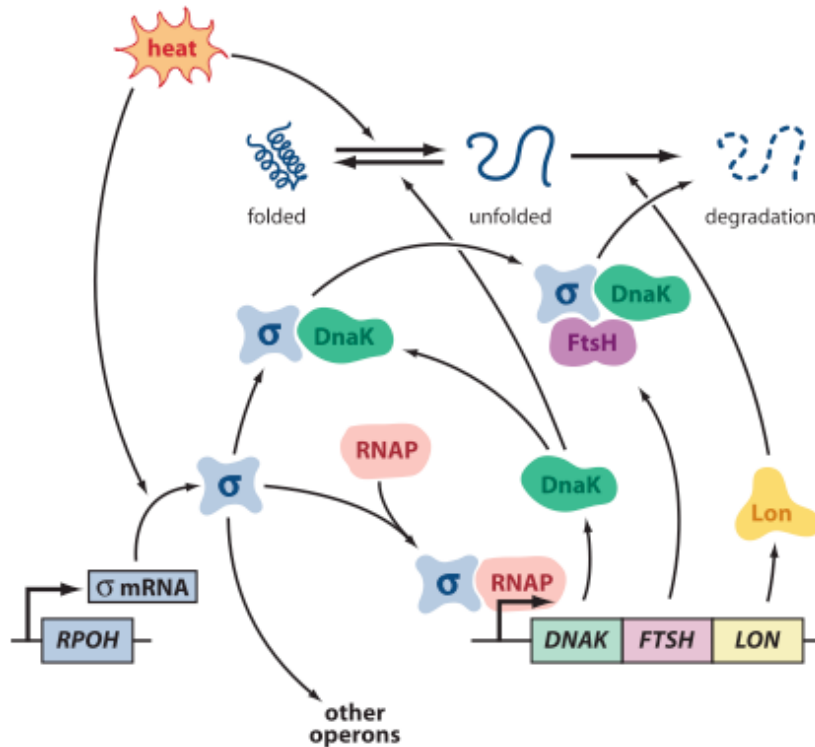
Post-translational regulation

- σ^{32} mRNA is always present in cell, but folds so that ribosome can't translate
- Heat unfolds σ^{32} & activates translation

Heat shock proteins

- DnaK = chaperone protein + sequesters σ^{32} (providing negative feedback)
- FtsH = degrades bound σ^{32} , providing finer control
- Lon = protease (degrades unfolded proteins)

Heat Shock Modeling



El-Samad et al, 2005

$$d[\text{mDnaK}]/dt = k_{\text{tr1}}[\sigma^{32} : \text{RNAP}] - \alpha_m[\text{mDnaK}]$$

$$d[\text{DnaK}_t]/dt = k_{\text{tl}}[\text{mDnaK}] - \alpha_p[\text{DnaK}_t]$$

$$d[\text{mFtsH}]/dt = k_{\text{tr2}}[\sigma^{32} : \text{RNAP}] - \alpha_m[\text{mFtsH}]$$

$$d[\text{FtsH}_t]/dt = k_{\text{tl}}[\text{mFtsH}] - \alpha_p[\text{FtsH}_t]$$

$$d[\text{mLon}]/dt = k_{\text{tr3}}[\sigma^{32} : \text{RNAP}] - \alpha_m[\text{mLon}]$$

$$d[\text{Lon}_t]/dt = k_{\text{tl}}[\text{mLon}] - \alpha_p[\text{Lon}_t]$$

$$d[\text{m}\sigma^{32}]/dt = k_{\text{tr4}}[\sigma^{32} : \text{RNAP}] - \alpha_m[\text{m}\sigma^{32}]$$

$$d[\sigma_t^{32}]/dt = k_{\text{tl}}\eta(T)[\text{m}\sigma^{32}] - \alpha_p[\text{m}\sigma_f^{32}]$$

$$- \alpha_{\text{FtsH}}[\sigma^{32}:\text{DnaK}:\text{FtsH}]$$

$$- \alpha_{\text{Lon}}(T)[\sigma^{32}:\text{DnaK}:\text{FtsH}]$$

$$d[\text{P}_{\text{fold}}] = k_{\text{fold}}[\text{P}_{\text{unfold}}:\text{DnaK}] - K(T)[\text{P}_{\text{fold}}]$$

Algebraic binding equations

- Model remaining reactions assuming they reach steady state quickly

$$[\sigma^{32}:\text{DnaK}] = k_1[\sigma_f^{32}] \cdot [\text{DnaK}_f]$$

$$[\sigma^{32}:\text{DnaK}:\text{FtsH}] = k_2[\sigma^{32}:\text{DnaK}] \cdot [\text{FtsH}]$$

Mass balance equations

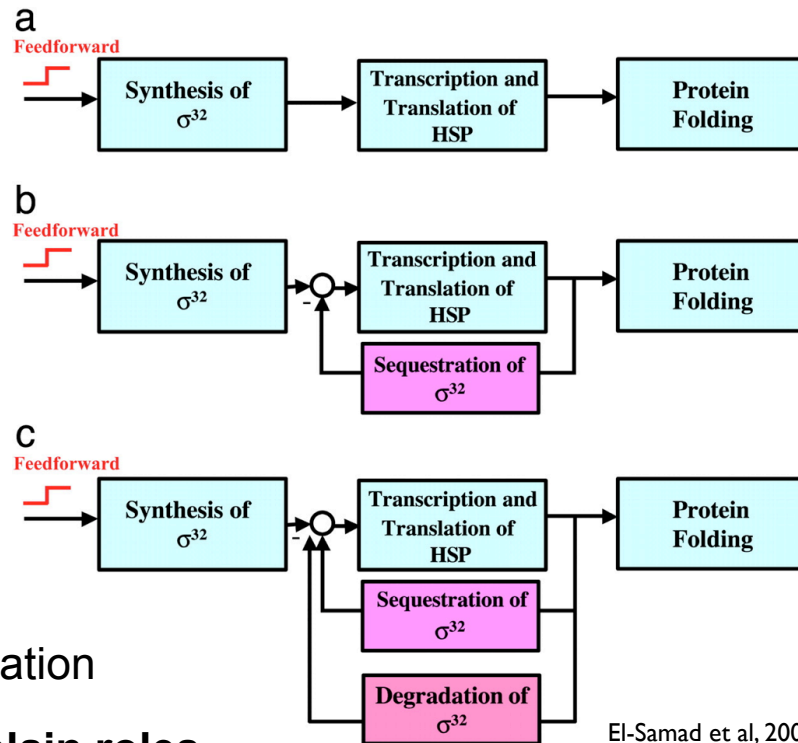
- Total protein concentration = sum of concentrations of all compounds containing that protein

$$[\text{FtsH}_t] = [\text{FtsH}_f] + [\sigma^{32} : \text{DnaK} : \text{FtsH}]$$

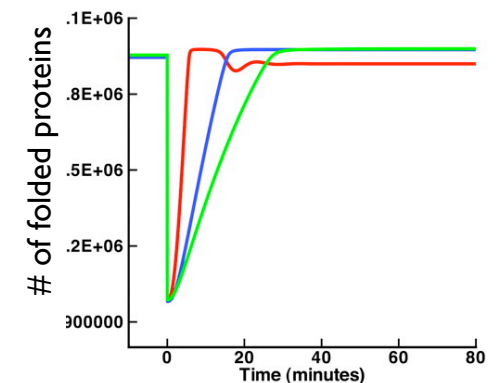
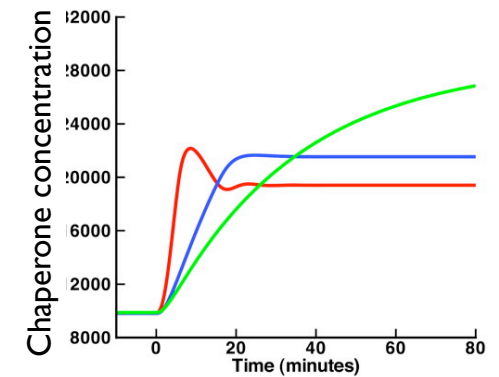
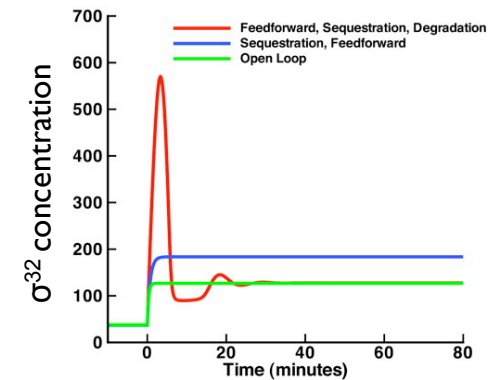
Role of Feedback

Question: what is the role of the additional feedback in heat shock circuit?

- Option a: feed-forward circuit, w/ tuned params
- Option b: neg fbk via sequestration
- Option c: add'l neg fbk via degradation



El-Samad et al, 2005



Simulations help explain roles

- Use step input of heat and examine how system responses
- σ^{32} able to act more quickly with neg fbk to tune response
- Chaperone concentrations have much faster rise time
- Net result: very fast disturbance rejection in folded proteins

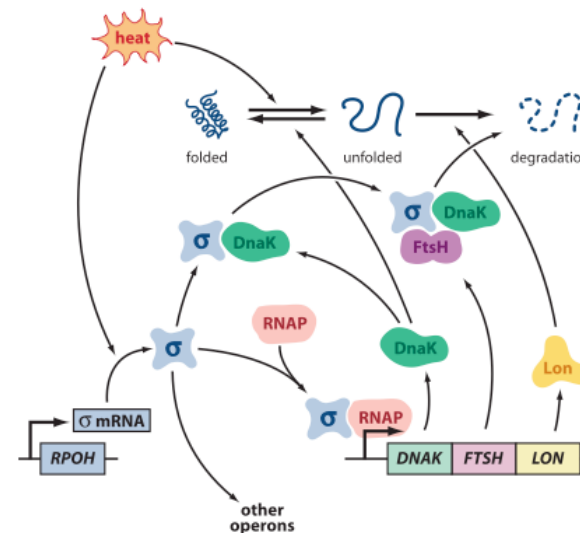
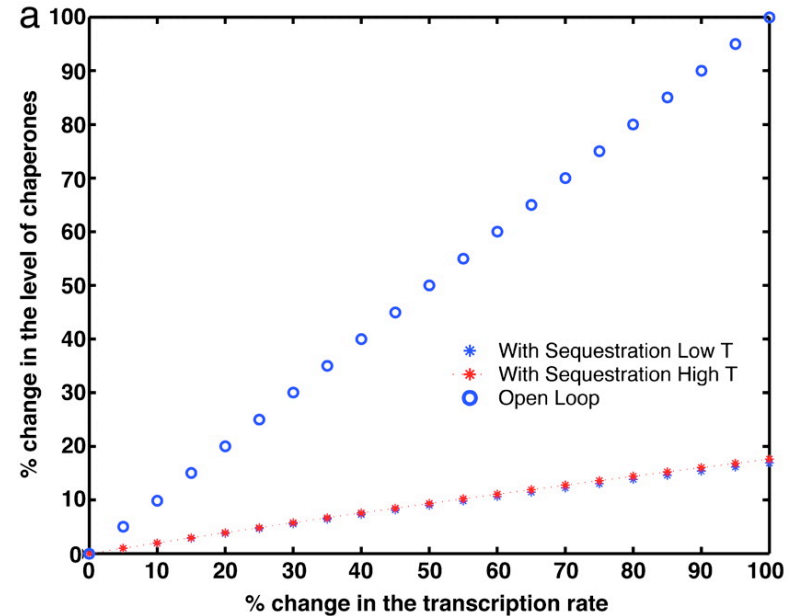
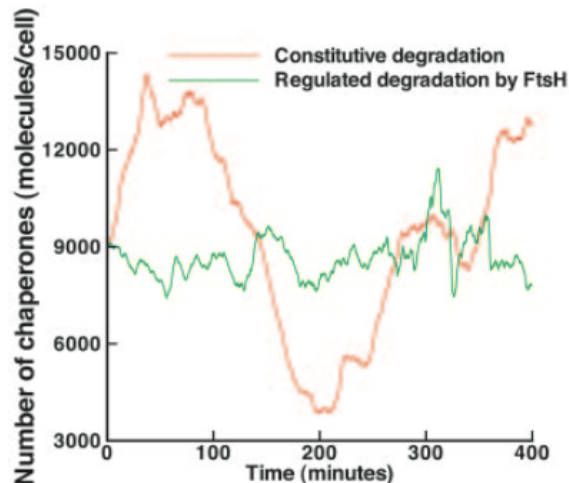
Additional Analyses

System robustness

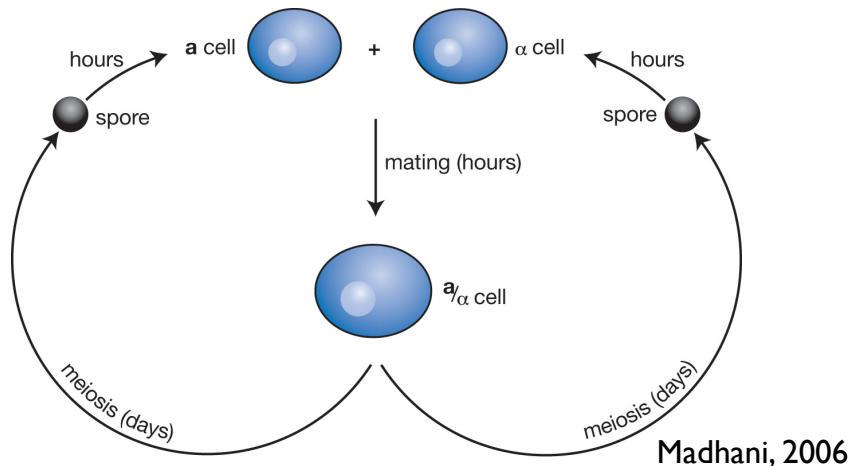
- Feedback provides additional robustness with respect to changes in parameters
- Figure: modification of transcription rate (global parameter) on level of chaperones
- With feedback, much less sensitivity

Noise response

- Stochastic simulation (SSA) of system
- Degradation by FtsH shows less noisy response in chaperone count



Example #3: Yeast Pheromone Mating Response



http://www.youtube.com/watch?v=dcNEfUnEt_g

References

- H. Madhani, *From a to α*. CSHL Press, 2006
- Kofahl and Klipp, *Yeast*, 2004
- Bardwell, *Peptides*, 2005

Yeast cells exist in four basic phenotypes:

- Haploid a: contains a single set of chromosomes with MATa locus
- Haploid α: contains a single set of chromosomes with MATα locus
- Diploid a/α: contains two copies of each chromosome
- Spore: under stress, diploid cell can form spores of types a and α; these become haploid cells when environment improves
- Haploid and diploid cells are both capable of cell division (cell type is preserved)

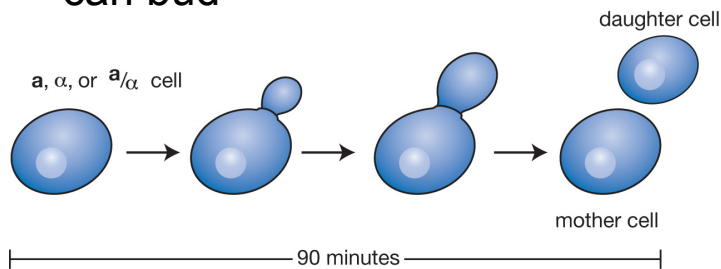
Yeast cells “mate” via “shmooing”

- Cells of type a detect pheromone secreted by α cells and extend shmoo
- Cells of type α do the same the converse
- Shmoos join and form diploid cell type
- Haploid cells that mate stop dividing (and die if shmooing doesn't succeed)

Yeast Phenotypes

Budding

- Primary mechanism for cell replication (mitosis)
- Both haploid and diploid cells can bud

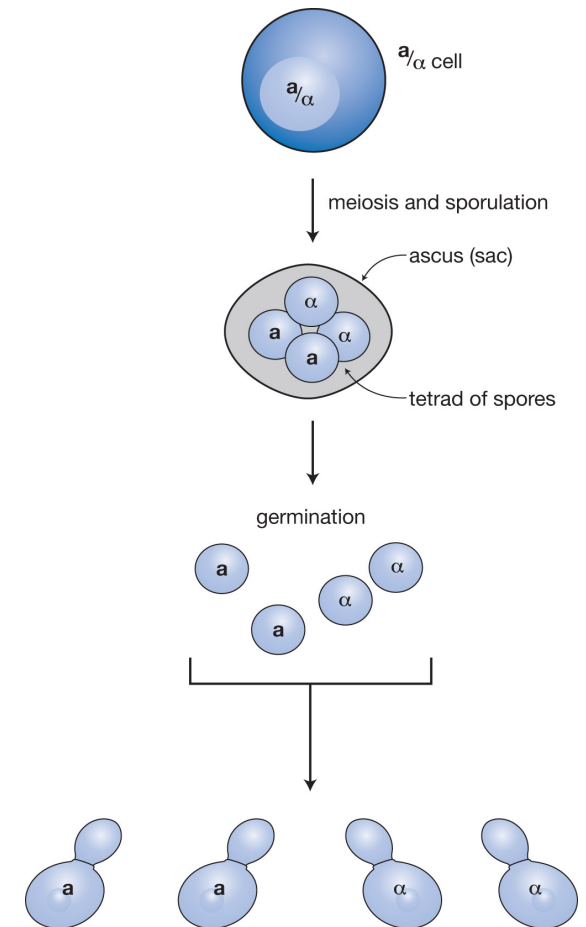
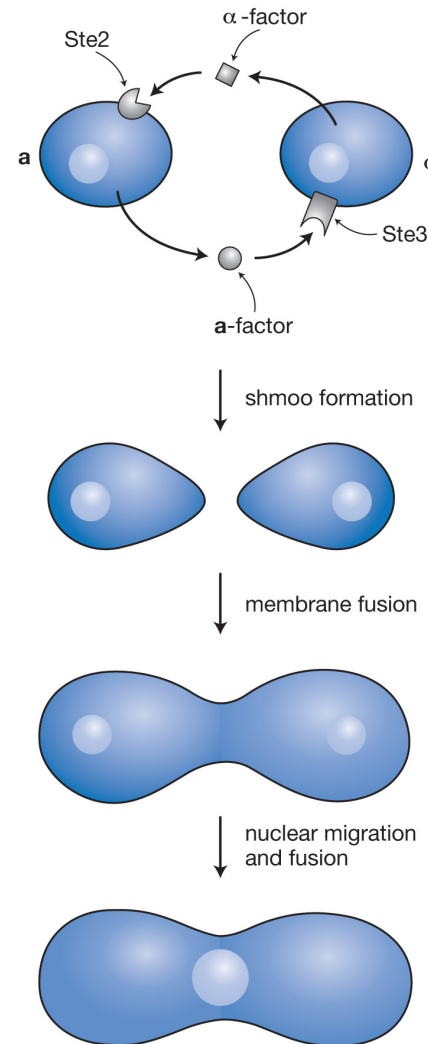


Mating response

- Haploid cells detect pheromones from complementary type and send “schmoos” toward other cell
- Diploid cell results

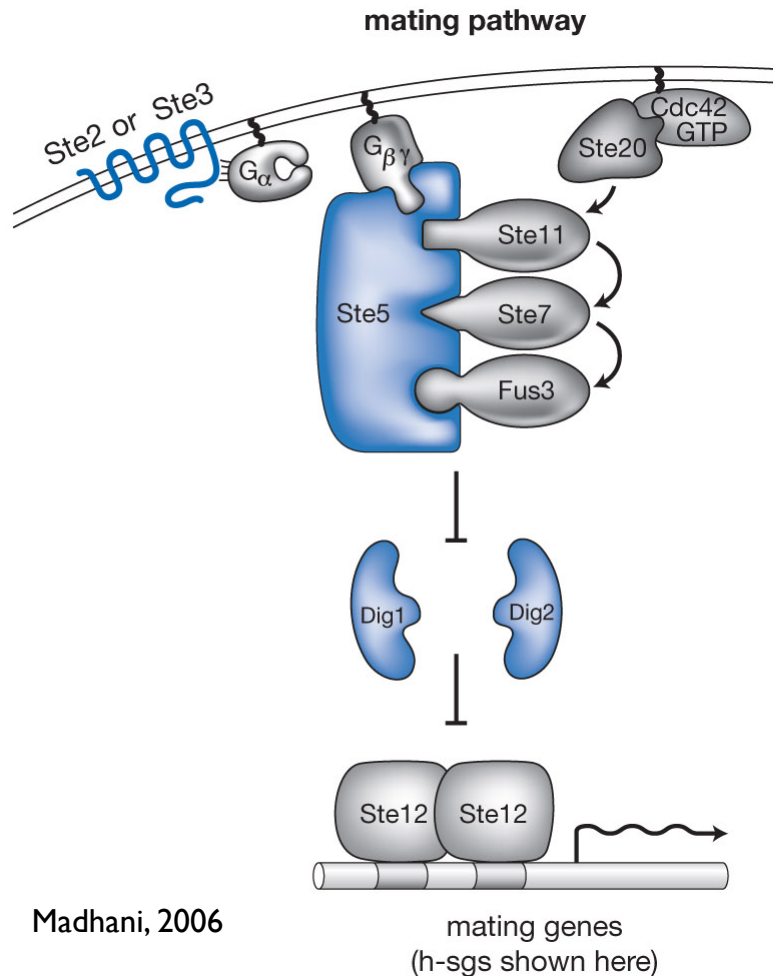
Sporulation

- Diploid cells can form spores under environmental stress
- Spores grow when environment stabilizes



Madhani, 2006

Mating Response: Phenomenological Description



Madhani, 2006

Sensor: G-protein

- Ste2/Ste3 protein binds in cell membrane
- Pheromone from opposite cell type causes conformational change
- G-protein is used to dock scaffold protein

Computation: MAP kinase + double repression

- Cdc42/Ste20 bound to membrane
- Sequence of phosphorylations occurs between proteins linked to scaffold
- Fus3 breaks free when active, causes activation (via double repression with Dig)

Actuation: transcriptional regulation

- Ste12 binds to DNA as transcriptional co-factor; Dig1/Dig2 bind to Ste12 and repress gene expression
- Downstream genes encode for proteins required to arrest cell cycle and form shmoo

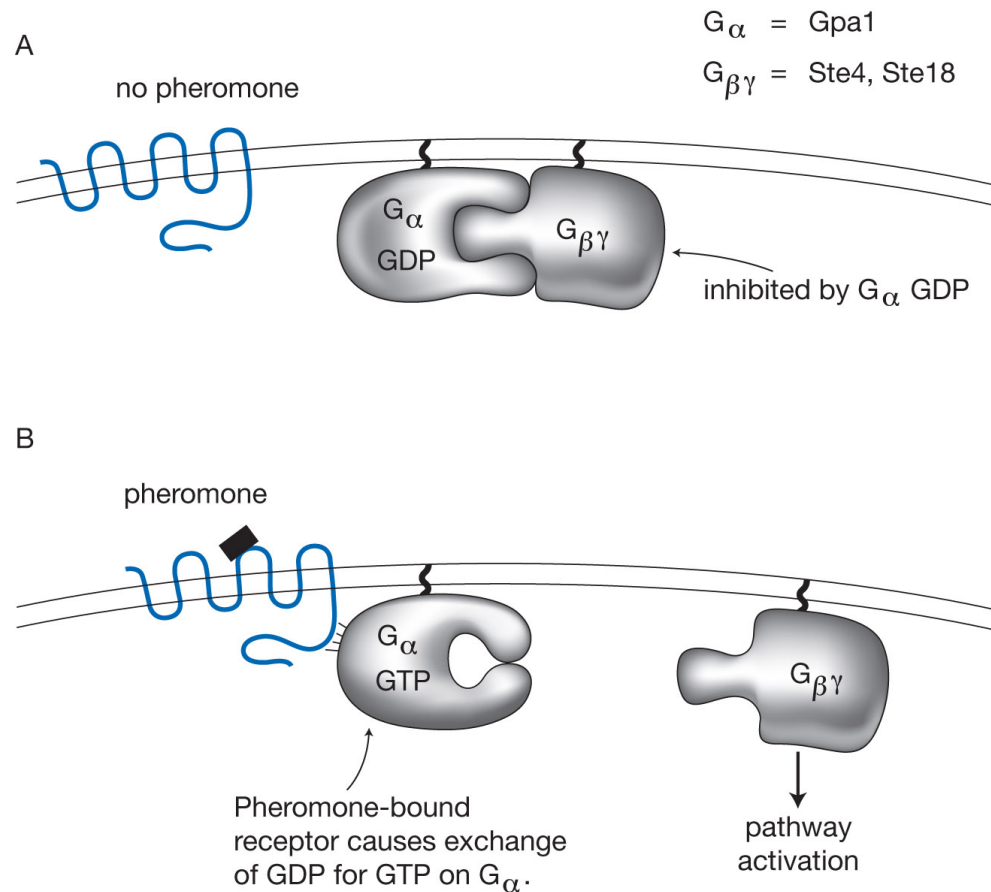
G-protein signal transduction

Common mechanism for signal transduction in eukaryotes

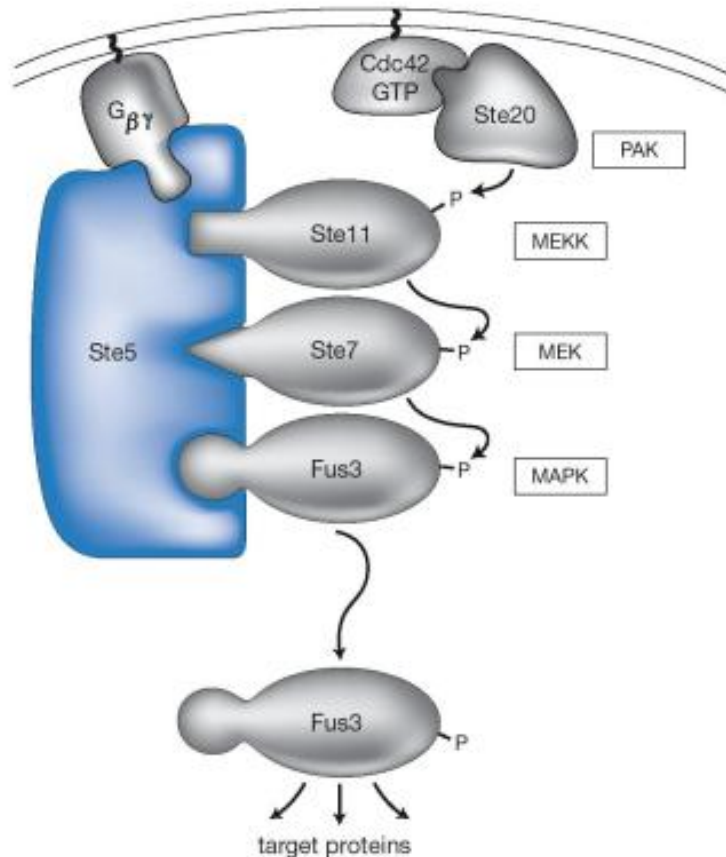
- Membrane-linked protein with seven membrane crossings
- Protein complex with α , β and γ units (specific proteins change)
- α unit binds to GDP

Signal triggers release of subunits

- Pheromone binds to receptor & causes conformational change
- Active receptor protein causes exchange of GTP for GDP on α unit
- GTP causes conformational change $G_{\beta\gamma}$ separate from G_{α}
- Individual subunits now available to interact with other proteins



MAP kinase cascade



Madhani, 2006

Add definitions of PAK,
MEKK, MEK, MAPK

Common mechanism for signal propagation

- Found in many eukaryotes including yeast
- Proteins vary, but function is preserved
- MAP = mitogen activated protein (from originally discovered function - external signal that causes mitosis)

Sequence of phosphorylation reactions

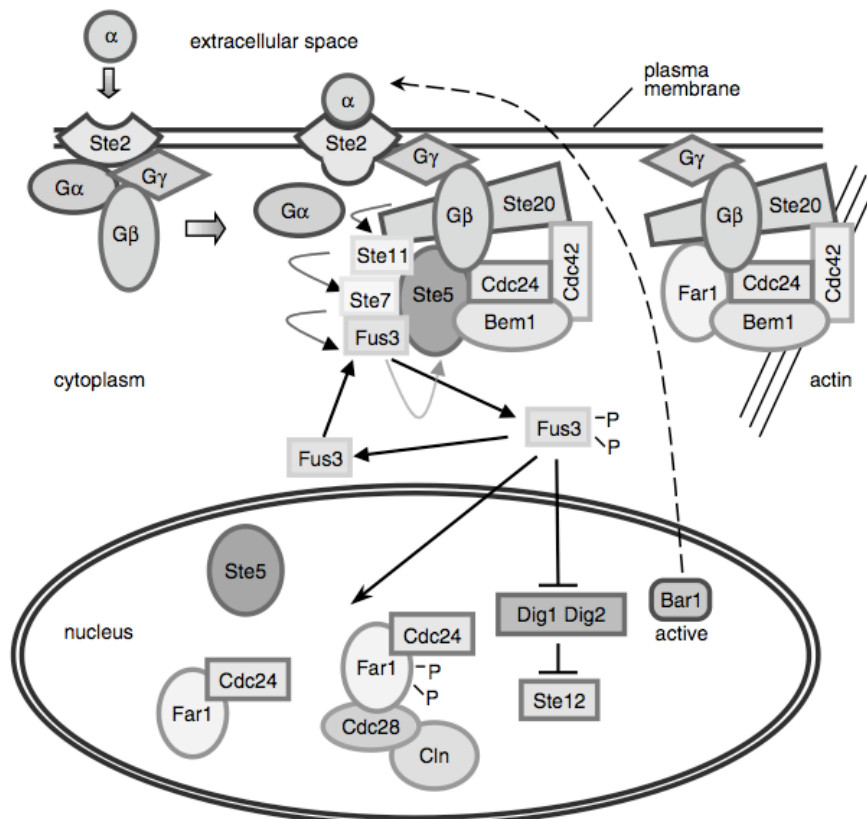
- Ste20 is activated by binding to membrane protein
- Activated Ste20 phosphorylates Ste 11, causing Ste 11 to become active
- Activated Ste 11 phosphorylates Ste 7
- Activated Ste 7 phosphorylates Fus3
- Activated Fus3 undocks and activates proteins

Why a cascade: not completely known

- In some systems (eg, w/out scaffold) there may be an amplification factor

Modeling the Pheromone Response

Each component can be modeled using basic mechanisms described earlier



- B. Kofahl and E. Klipp, Modelling the dynamics of the yeast pheromone pathway. *Yeast*, 21(10):831-850, 2004

Table 1. Equations governing the dynamics of the pheromone pathway (mathematical model)

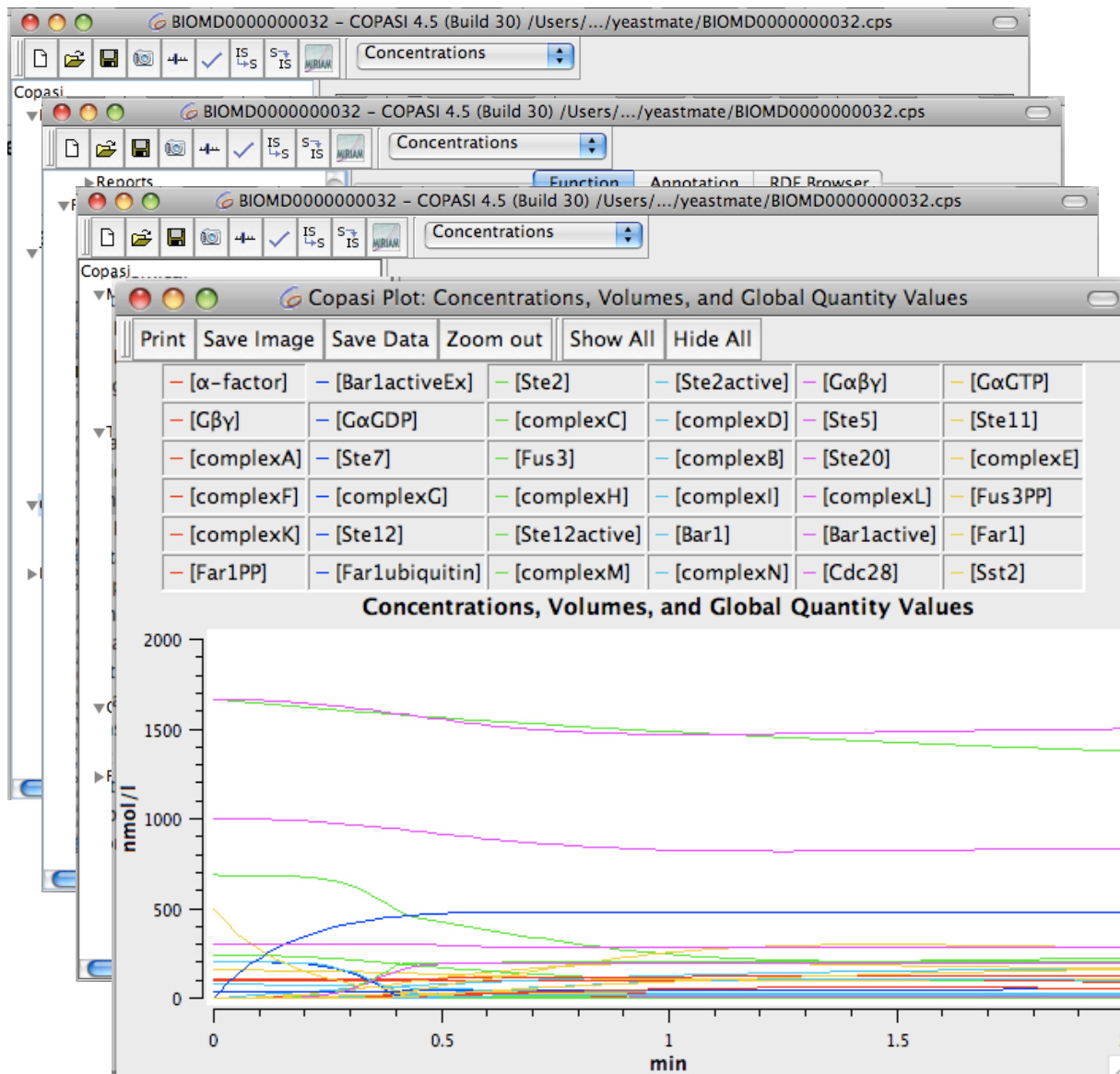
Ordinary differential equations

$$\begin{aligned}
\frac{d\alpha}{dt} &= -v_1 \\
\frac{dSte2}{dt} &= -v_2 + v_3 - v_5 \\
\frac{dSte2_{active}}{dt} &= v_2 - v_3 - v_4 \\
\frac{dSte2_{inactive}}{dt} &= v_46 - v_47 \\
\frac{dGaby}{dt} &= -v_6 + v_9 \\
\frac{dGatP}{dt} &= v_6 - v_7 - v_8 \\
\frac{dGatDP}{dt} &= v_7 + v_8 - v_9 \\
\frac{dGby}{dt} &= v_6 - v_9 - v_{10} + v_{11} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
&\quad - v_{42} + v_{43} \\
\frac{dSte5}{dt} &= -v_{12} + v_{13} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
\frac{dSte11}{dt} &= -v_{12} + v_{13} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
\frac{dSte7}{dt} &= -v_{14} + v_{15} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
\frac{dSte3}{dt} &= -v_{14} + v_{15} + v_{17} + v_{21} + v_{23} + v_{25} + v_{27} - v_{29} \\
&\quad + v_{30} + v_{33} \\
\frac{dSte20}{dt} &= -v_{18} + v_{19} + v_{21} + v_{23} + v_{25} + v_{27} + v_{32} \\
\frac{dA}{dt} &= v_{12} - v_{13} - v_{16} \\
\frac{dG}{dt} &= v_{14} - v_{15} - v_{16} \\
\frac{dC}{dt} &= -v_{10} + v_{11} + v_{16} - v_{17} \\
\frac{dD}{dt} &= v_{10} - v_{11} - v_{18} + v_{19} \\
\frac{dE}{dt} &= v_{18} - v_{19} - v_{20} - v_{21} \\
\frac{dF}{dt} &= v_{20} - v_{22} - v_{23} \\
\frac{dG}{dt} &= v_{22} - v_{24} - v_{25} \\
\frac{dH}{dt} &= v_{24} - v_{26} - v_{27} \\
\frac{dI}{dt} &= v_{26} - v_{28} + v_{31} \\
\frac{dJ}{dt} &= v_{28} - v_{29} + v_{30} - v_{32} \\
\frac{dK}{dt} &= v_{29} - v_{30} - v_{31} \\
\frac{dLus3PP}{dt} &= v_{28} - v_{33} - v_{34} + v_{35} \\
\frac{dSte12}{dt} &= -v_{34} + v_{35} \\
\frac{dSte12_{active}}{dt} &= v_{34} - v_{35} \\
\frac{dBar1}{dt} &= -v_{36} + v_{37} \\
\frac{dBar1_{active}}{dt} &= v_{36} - v_{37} - v_{38} \\
\frac{dFar1}{dt} &= -v_{39} + v_{40} - v_{41} \\
\frac{dFar1PP}{dt} &= v_{39} - v_{40} - v_{42} + v_{43} + v_{44} - v_{45} \\
\frac{dM}{dt} &= v_{42} - v_{43} \\
\frac{dFar1Ubiquitin}{dt} &= v_{41} \\
\frac{dCdc28}{dt} &= v_{44} - v_{45}
\end{aligned}$$

Rate equations

$$\begin{aligned}
V_1 &= \alpha[t] \cdot \text{Bar}l_{\text{active}}[t] \cdot k_1 \\
V_2 &= \text{Ste}2[t] \cdot \alpha[t] \cdot k_2 \\
V_3 &= \text{Ste}2_{\text{active}}[t] \cdot k_3 \\
V_4 &= \text{Ste}2_{\text{active}}[t] \cdot k_4 \\
V_5 &= \text{Ste}2[t] \cdot k_5 \\
V_6 &= \text{Ste}2_{\text{active}}[t] \cdot G\alpha\beta\gamma[t] \cdot k_6 \\
V_7 &= G\alpha GTP[t] \cdot k_7 \\
V_8 &= G\alpha GTP[t] \cdot \text{Sst}2_{\text{active}}[t] \cdot k_8 \\
V_9 &= G\alpha GDP[t] \cdot G\beta\gamma[t] \cdot k_9 \\
V_{10} &= G\beta\gamma[t] \cdot C[t] \cdot k_{10} \\
V_{11} &= D[t] \cdot k_{11} \\
V_{12} &= \text{Ste}5[t] \cdot \text{Ste}11[t] \cdot k_{12} \\
V_{13} &= A[t] \cdot k_{13} \\
V_{14} &= \text{Ste}7[t] \cdot \text{Fus}3[t] \cdot k_{14} \\
V_{15} &= B[t] \cdot k_{15} \\
V_{16} &= A[t] \cdot B[t] \cdot k_{16} \\
V_{17} &= C[t] \cdot k_{17} \\
V_{18} &= D[t] \cdot \text{Ste}20[t] \cdot k_{18} \\
V_{19} &= E[t] \cdot k_{19} \\
V_{20} &= E[t] \cdot k_{20} \\
V_{21} &= E[t] \cdot k_{21} \\
V_{22} &= F[t] \cdot k_{22} \\
V_{23} &= F[t] \cdot k_{23} \\
V_{24} &= G[t] \cdot k_{24} \\
V_{25} &= G[t] \cdot k_{25} \\
V_{26} &= H[t] \cdot k_{26} \\
V_{27} &= H[t] \cdot k_{27} \\
V_{28} &= I[t] \cdot k_{28} \\
V_{29} &= L[t] \cdot \text{Fus}3[t] \cdot k_{29} \\
V_{30} &= K[t] \cdot k_{30} \\
V_{31} &= K[t] \cdot k_{31} \\
V_{32} &= L[t] \cdot k_{32} \\
V_{33} &= \text{Fus}3PP[t] \cdot k_{33} \\
V_{34} &= \text{Ste}12[t] \cdot \text{Fus}3PP[t] \cdot k_{34} \\
V_{35} &= \text{Ste}12_{\text{active}}[t] \cdot k_{35} \\
V_{36} &= \text{Ste}12_{\text{active}}[t] \cdot \text{Bar}l[t] \cdot k_{36} \\
V_{37} &= \text{Bar}l_{\text{active}}[t] \cdot k_{37} \\
V_{38} &= \text{Bar}l_{\text{active}}[t] \cdot k_{38} \\
V_{39} &= \text{Far}1[t] \cdot \frac{\text{Fus}3PP[t]^2}{K} \cdot k_{39}
\end{aligned}$$

Interlude: SBML and Associated Software



Building models

- Supports arbitrary rate expressions
- Allows multiple compartments (eg, cytoplasm, nucleus, ...)

Many standard reactions

- Has built in reactions for Michaelis-Menten, Hill functions, etc

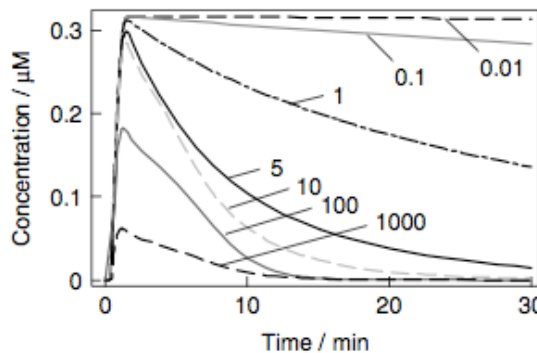
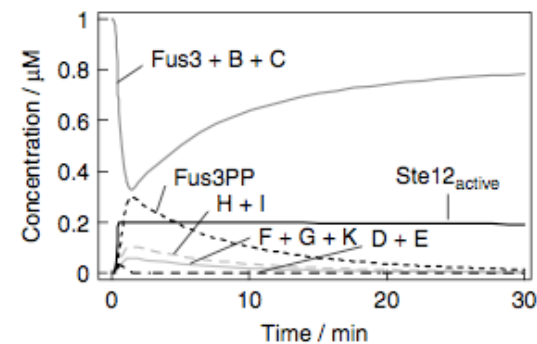
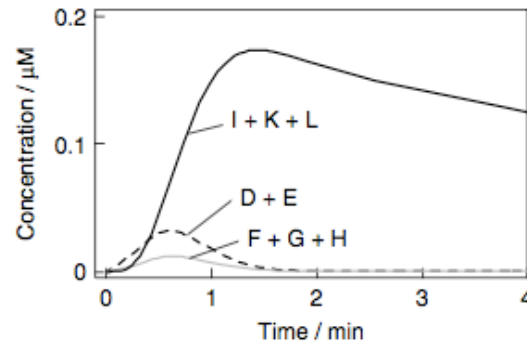
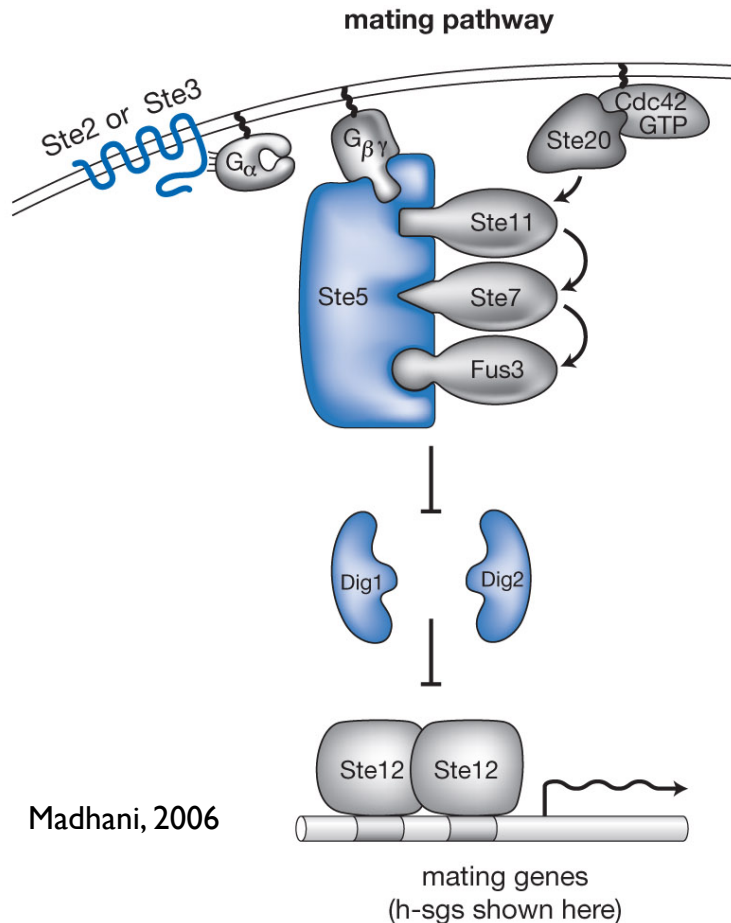
Analysis capabilities

- Simulate either deterministically or stochastically (SSA)
- Also supports sensitivity analysis, parameter estimation, etc

Output

- Interactive selection

Sample Simulation Results



MAPK activity

- $D+E$ = unphosphorylated complex
- $F+G+H$ = partially phosphorylated
- $I+J+K$ = active complex

Free/bound Fus3

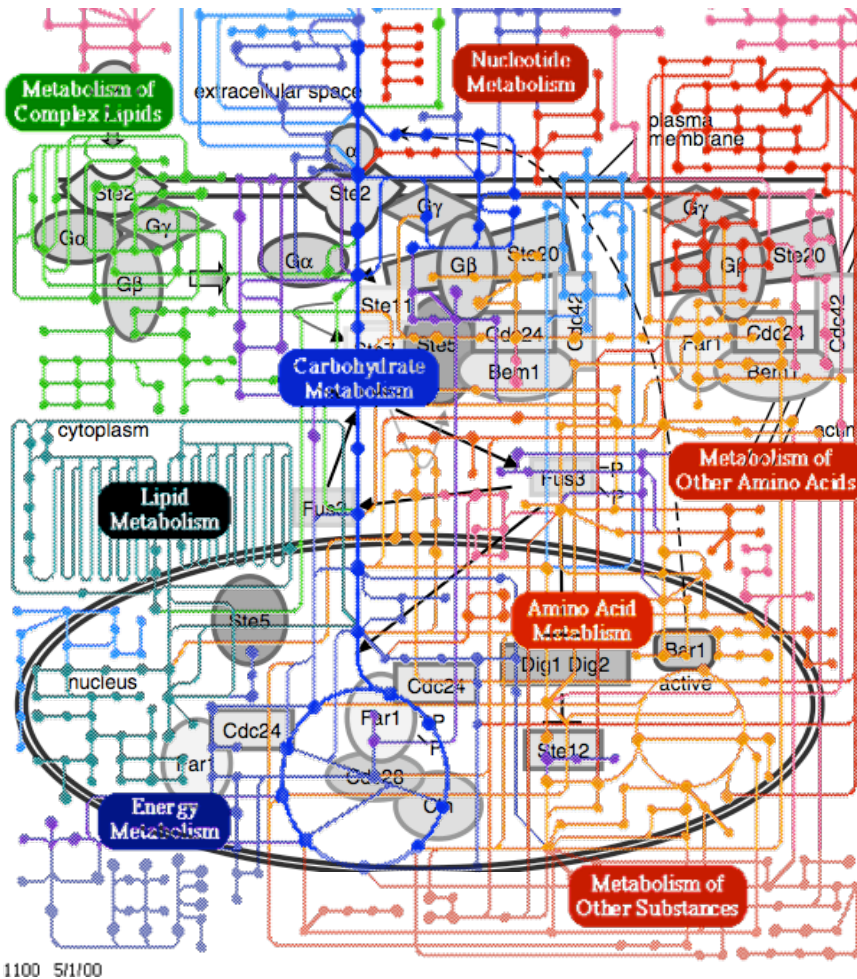
- $Fus3 + B + C$ = free Fus3
- $Fus3PP$ = activated Fus3 (binds to Dig)

Parametric changes

- Effect of increasing scaffold degradation on $Fus3PP$

Kofahl and Klipp, 2004

Some Open Questions



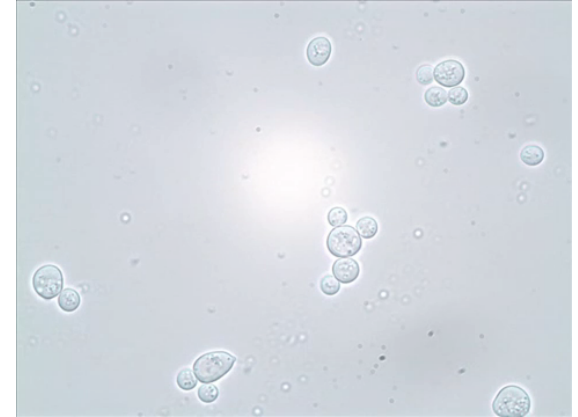
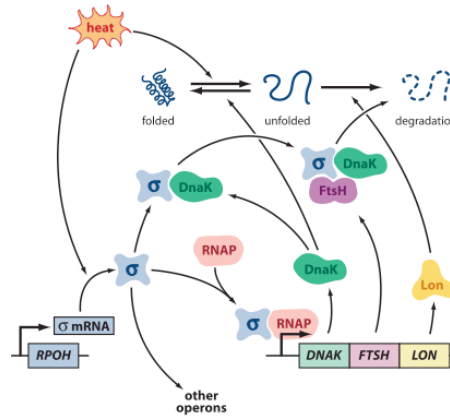
What's different about biological systems

- *Complexity* - biological systems are *much* more complicated than engineered systems
- *Communications* - signal representations are very different (spikes, proteins, etc)
- *Uncertainty* - very large uncertainty in components; don't match current tools
- *Evolvability* - mutation, selection, etc

Potential application areas for control tools

- *System ID* - what are the appropriate component abstractions and models?
- *Analysis* - what are key biological feedback mechanisms that lead to robust behavior?
- *Design* - how to we (re-)design biological systems to provided desired function?
- *Fundamental limits* - what are the limits of performance and robustness for a given biological network topology?

Summary



Chemotaxis

- Regulate the rate of runs versus tumbles to move along increasing gradients
- Methylation provides adaptation (integral feedback) to constant biases

Heat shock

- Turn on refolding machinery when proteins begin to denature due to heat
- Feedback mechanisms: sequestration, degradation, post-transcriptional modifications

Yeast mating response

- Detect presence of opposite cell type and generate a shmoo for possible mating
- Molecular machinery: G-proteins, phosphorylation, MAP kinases