The Lagrangian-Averaged Navier-Stokes alpha (LANS- α) Turbulence Model in Primitive Equation Ocean Modeling

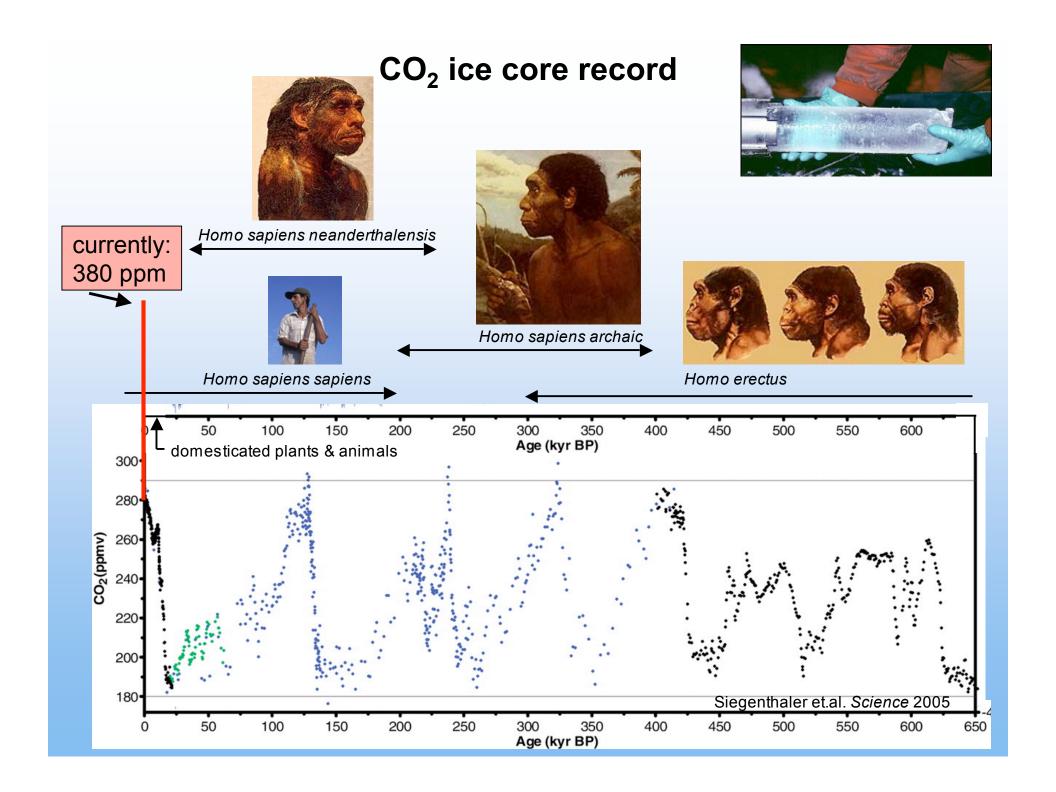
Mark R. Petersen

with Matthew W. Hecht, Darryl D. Holm, and Beth A. Wingate Los Alamos National Laboratory

Outline

- POP ocean model & climate change assessment
- LANS- α implementation in POP
- Idealized test case: the channel domain
- The real thing: the North Atlantic

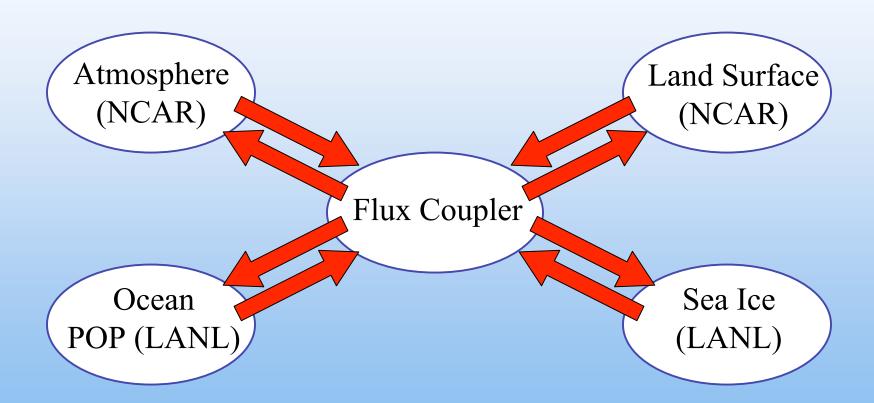
D2Hfest LA-UR-05-0887 July 24, 2007



Community Climate System Model

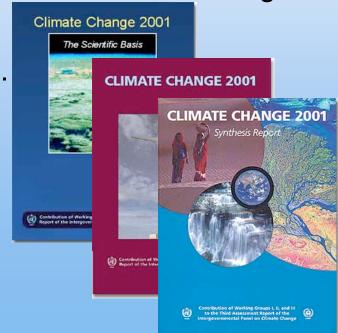
Collaboration of:

- National Center for Atmospheric Research (NCAR) in Boulder, CO
- Los Alamos National Laboratory (LANL)



IPCC - Intergovernmental Panel on Climate Change

- Created in 1988 by World Meteorological Organization (WMO) and United Nations Environment Programme (UNEP)
- Role of IPCC: assess on a comprehensive, objective, open and transparent basis the scientific, technical and socio-economic information relevant to understanding:
 - the scientific basis of risk of human-induced climate change
 - its potential impacts and
 - options for adaptation and mitigation.
- Main activity: Assessment reports
 - Third Assessment Report: 2001
 - Fourth Assessment Report: 2007
 - Fifth: planned for 2013

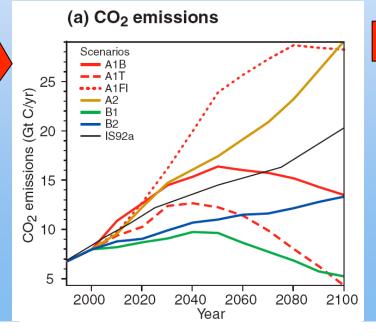


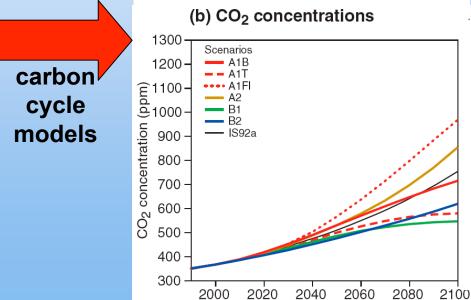
IPCC scenarios of future emissions

	A: slower conversion to clean & efficient technologies	B: faster conversion to clean & efficient technologies
1: global population levels off, declines after 2050	A1FI: fossil intensive A1T: non-fossil intensive A1B: balance of F&T	B1
2: continuously increasing population	A2	B2

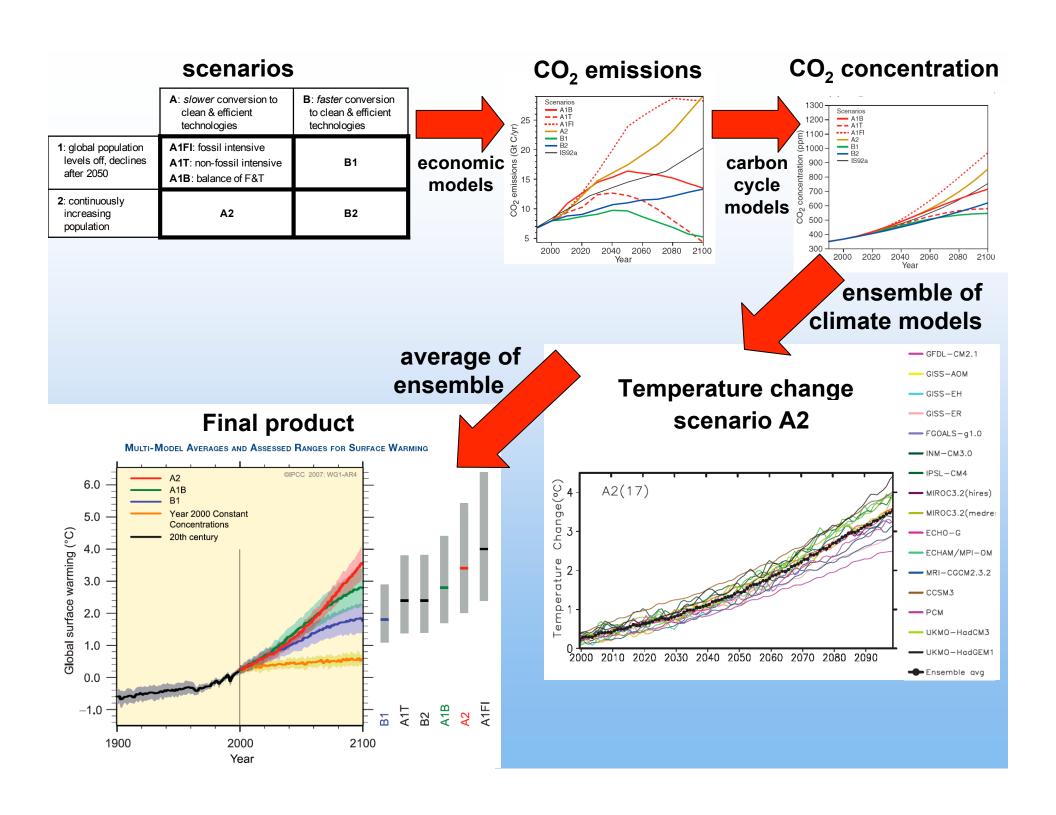
IS92a: business as usual (extrapolation from current rates of increase)

economic models

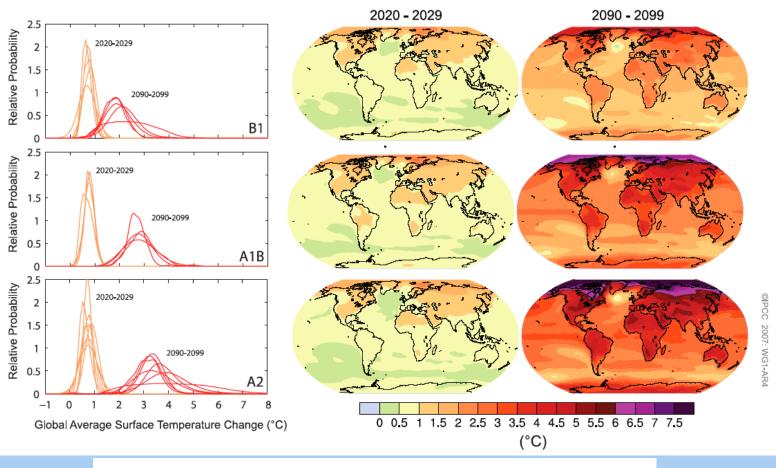


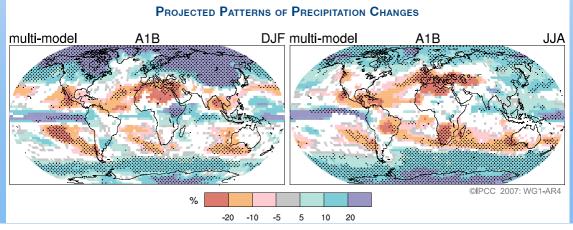


Year



PROJECTIONS OF SURFACE TEMPERATURES





IPCC: Estimates of confidence

Table 4: Estimates of confidence in observed and projected changes in extreme weather and climate events. The table depicts an assessment of confidence in observed changes in extremes of weather and climate during the latter half of the 20th century (left column) and in projected changes during the 21st century (right column)^a. This assessment relies on observational and modelling studies, as well as physical plausibility of future projections across all commonly used scenarios and is based on expert judgement (see Footnote 4). [Based upon Table 9.6]

Confidence in observed changes (latter half of the 20th century)	Changes in Phenomenon	Confidence in projected changes (during the 21st century)
Likely	Higher maximum temperatures and more hot days over nearly all land areas	Very likely
Very likely	Higher minimum temperatures, fewer cold days and frost days over nearly all land areas	Very likely
Very likely	Reduced diurnal temperature range over most land areas	Very likely
Likely, over many areas	Increase of heat index ⁸ over land areas	Very likely, over most areas
Likely, over many Northern Hemisphere mid- to high latitude land areas	More intense precipitation events ^b	Very likely, over many areas
Likely, in a few areas	Increased summer continental drying and associated risk of drought	Likely, over most mid-latitude continental interiors (Lack of consistent projections in other areas)
Not observed in the few analyses available	Increase in tropical cyclone peak wind intensities ^c	Likely, over some areas
Insufficient data for assessment	Increase in tropical cyclone mean and peak precipitation intensities°	Likely, over some areas

^{*} For more details see Chapter 2 (observations) and Chapters 9, 10 (projections).

^b For other areas there are either insufficient data of conflicting analyses.

^c Past and future changes in tropical cyclone location and frequency are uncertain.

⁸ Heat index: A combination of temperature and humidity that measures effects on human comfort

Parallel Ocean Program (POP)

Bryan-Cox type model, z-level vertical grid, finite difference model

conservation of momentum

$$\partial_t \mathbf{u} + \underbrace{\mathbf{u} \cdot \nabla \mathbf{u}}_{} - \underbrace{f \times \mathbf{u}}_{} = -\rho_0^{-1} \nabla p + \underbrace{A_M \nabla_h^2 \mathbf{u}}_{} + \partial_z \mu \partial_z \mathbf{u}$$
 advection Coriolis pressure gradient diffusion

conservation of mass for incompressible fluid

$$\nabla_h \cdot \mathbf{u} + \partial_z w = 0$$

conservation of tracers (temperature, salinity)

$$\partial_t \varphi + \mathbf{u} \cdot \nabla \varphi = A_H \nabla_h^2 \varphi + \partial_z \kappa \partial_z \varphi + Q$$
advection diffusion source/ sink

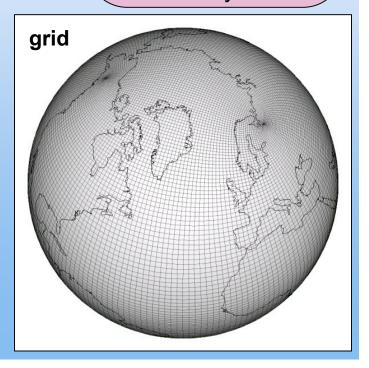
hydrostatic in the vertical

$$\frac{\partial p}{\partial z} = -\rho g$$

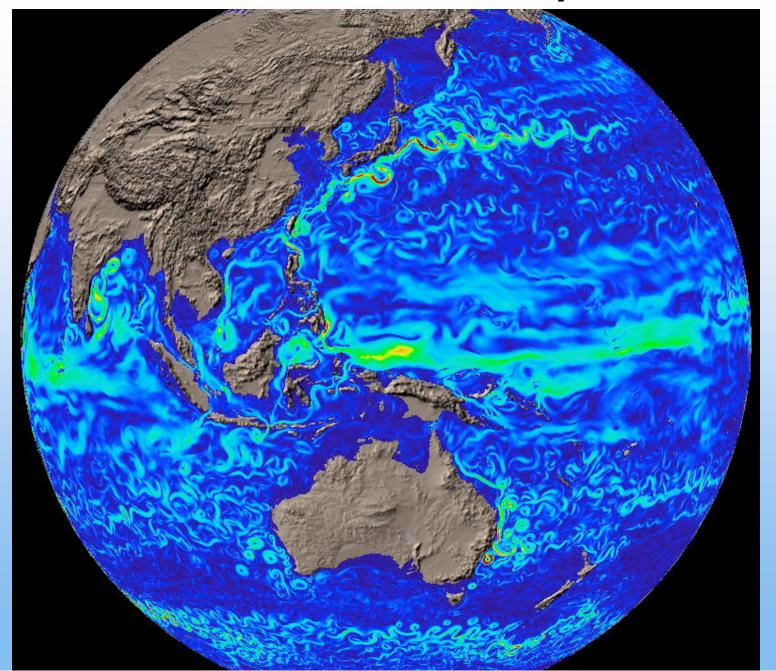
equation of state

$$\rho = \rho(T, S, p)$$

- u hor. velocity
- w vertical velocity
- φ tracer
- t time
- p pressure
- ho_0 density
- T temperature
- S salinity

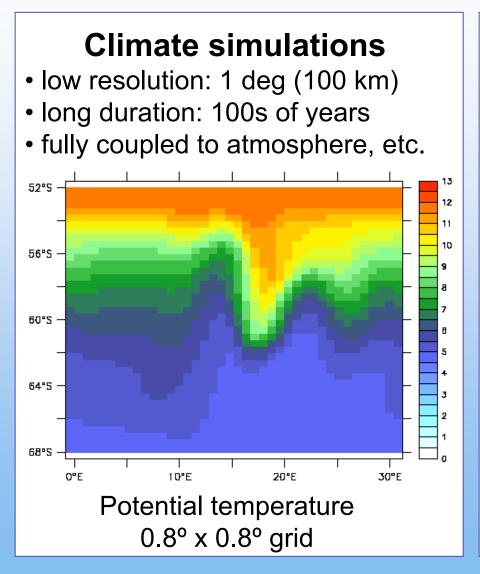


POP: 0.1° resolution, speed



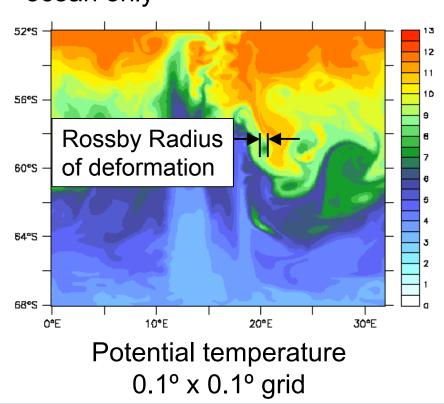
Parallel Ocean Program (POP)

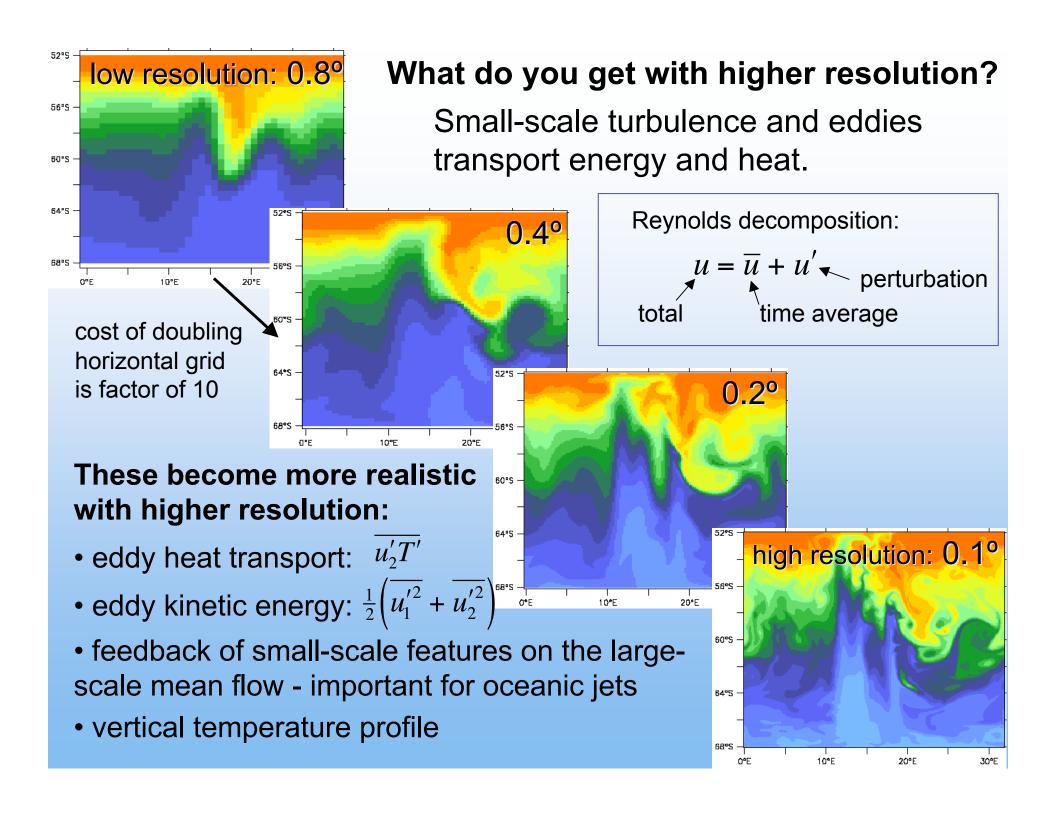
Resolution is costly, but critical to the physics



Eddy-resolving sim.

- high resolution: 0.1 deg (10 km)
- short duration: 50-100 years
- ocean only



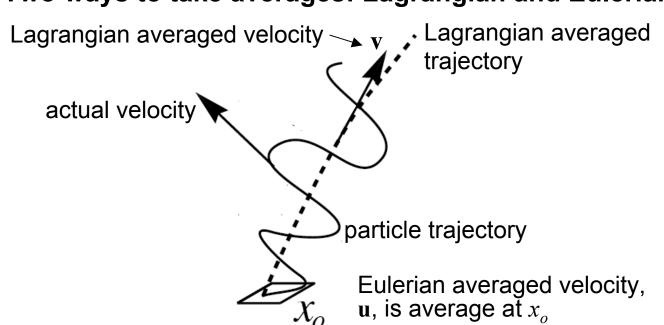


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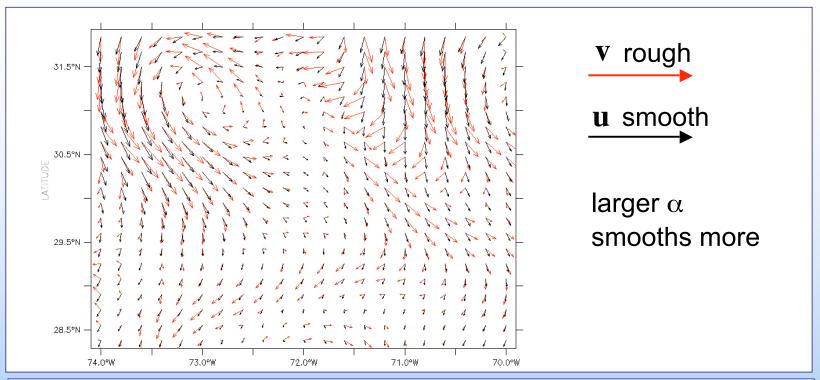
Lagrangian-Averaged Navier-Stokes Equation (LANS- α)

Two ways to take averages: Lagrangian and Eulerian



v Lagrangian averaged velocity $\mathbf{u} = (1 - \alpha^2 \nabla^2)^{-1} \mathbf{v}$ **u** Eulerian averaged velocity smooth Helmholtz operator rough

Lagrangian-Averaged Navier-Stokes Equation (LANS- α)



V Lagrangian averaged velocity $\mathbf{u} = (1 - \alpha^2 \nabla^2)^{-1} \mathbf{v}$ rough

$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{v} + \mathbf{v}_{j} \nabla \mathbf{u}_{j} - \mathbf{f} \times \mathbf{u} = -\frac{1}{\rho_{0}} \nabla p + \mathbf{v} \nabla^{2} \mathbf{v} + \mathbf{F}$$
advection extra Coriolis pressure nonlinear term gradient diffusion

Lagrangian-Averaged Navier-Stokes Equation (LANS- α)

$$\frac{\partial \mathbf{V}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{V} + v_j \nabla u_j - \mathbf{f} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla p + v \nabla^2 \mathbf{V} + \mathbf{F}$$
advection extra Coriolis pressure gradient diffusion



$$v_{j} \nabla u_{j} = \begin{pmatrix} v_{1} \partial_{x} u_{1} + v_{2} \partial_{x} u_{2} + v_{3} \partial_{x} u_{3} \\ v_{1} \partial_{y} u_{1} + v_{2} \partial_{y} u_{2} + v_{3} \partial_{y} u_{3} \\ v_{1} \partial_{z} u_{1} + v_{2} \partial_{z} u_{2} + v_{3} \partial_{z} u_{3} \end{pmatrix}$$

Extra nonlinear term is in alpha model, but not in Leray model. This term is required for conservation of PV.

Standard POP

tracer equation
$$\frac{\partial \varphi}{\partial t} + \underbrace{\mathbf{u} \cdot \nabla \varphi}_{\text{advection}} = \underbrace{D_H(\varphi) + D_V(\varphi)}_{\text{diffusion}}$$

momentum equation
$$\frac{\partial \mathbf{u}}{\partial t} + \underbrace{\mathbf{u} \cdot \nabla \mathbf{u} - \mathbf{f} \times \mathbf{u}}_{\text{advection Coriolis e.g. centrifugal}} + \underbrace{\mathbf{metric}(\mathbf{u})}_{\text{pressure qradient}} = \underbrace{-\rho_0^{-1} \nabla p}_{0} + \underbrace{F_H(\mathbf{u}) + F_V(\mathbf{u})}_{\text{diffusion}}$$

POP-alpha

rough velocity, V

smooth velocity, **U**

tracer equation
$$\frac{\partial \varphi}{\partial t} + \underbrace{\mathbf{u} \cdot \nabla \varphi}_{\text{advection}} = \underbrace{D_H(\varphi) + D_V(\varphi)}_{\text{diffusion}}$$

momentum equation

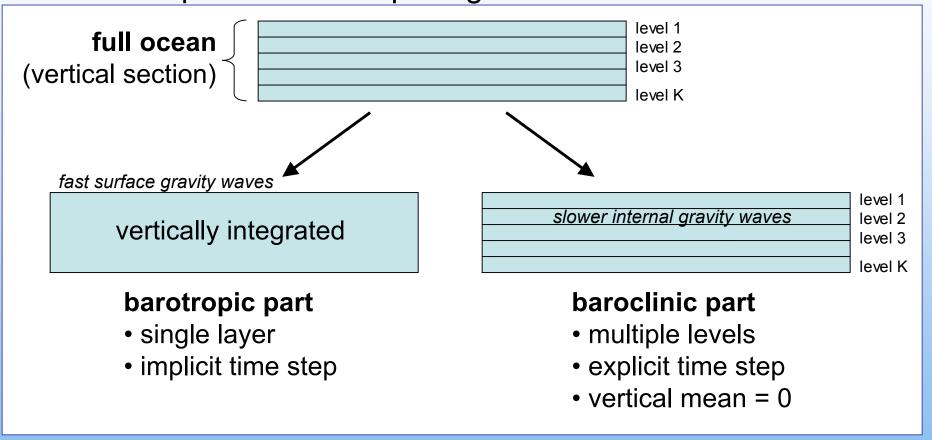
$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{v} + \mathbf{u}_j \nabla \mathbf{v}_j - \mathbf{f} \times \mathbf{u} + \text{metric}(\mathbf{u}) = -\rho_0^{-1} \nabla p + F_H(\mathbf{v}) + F_V(\mathbf{v})$$
advection extra Coriolis e.g. centrifugal pressure diffusion nonlinear term gradient

Helmholtz inversion
$$\mathbf{u} = (1 - \alpha^2 \nabla^2)^{-1} \mathbf{v}$$

The POP-alpha model

Issues:

1. How do we implement the alpha model within the barotropic/baroclinic splitting of POP?



Outline of algorithm - Standard POP

Start: variables known at step *n*+1

- temperature, salinity, density, pressure at n
- baroclinic velocities \mathbf{u}_k^n
- barotropic velocity \mathbf{U}^n

Baroclinic computations levels k = 1...km leap frog step:

$$\hat{\mathbf{u}}_k^{n+1} = \mathbf{u}_k^{n-1} + 2\Delta t R H S_k^n$$

where RHS contains:

- advection
- metric (centrifugal)
- Coriolis
- diffusion

subtract depth average:

$$\tilde{\mathbf{u}}_k^{n+1} = \hat{\mathbf{u}}_k^{n+1} - \frac{1}{H} \sum_{k=1}^{km} \hat{\mathbf{u}}_k^{n+1} dz_k$$

Barotropic computations

implicit solve for the free surface height η^{n+1}

new barotropic velocity:

$$\mathbf{U}^{n+1} = \mathbf{U}^{n-1} + 2\Delta t R H S$$

where RHS contains:

- vertically integrated forcing
- $\nabla \eta^{n-1}$, $\nabla \eta^n$, $\nabla \eta^{n+1}$

add barotropic velocity back to baroclinic:

$$\mathbf{u}_{k}^{n+1} = \tilde{\mathbf{u}}_{k}^{n+1} + \mathbf{U}^{n+1}$$

step n+1 complete

Outline of algorithm - POP-alpha

Start: variables known at step *n*+1

- temperature, salinity, density, pressure at n
- baroclinic *smooth* and rough velocities $\mathbf{u}_{k}^{n}, \mathbf{v}_{k}^{n}$
- barotropic *smooth* and *rough* velocities $\mathbf{U}^n, \mathbf{V}^n$

Baroclinic computations levels k = 1...km leap frog step:

$$\hat{\mathbf{v}}_k^{n+1} = \mathbf{v}_k^{n-1} + 2\Delta t R H S_k^n$$

where RHS contains:

- advection
- metric (centrifugal)
- Coriolis
- diffusion
- extra nonlinear term, $\nabla \mathbf{u}^{\mathrm{T}} \cdot \mathbf{v}$

subtract depth average:

$$\tilde{\mathbf{v}}_k^{n+1} = \hat{\mathbf{v}}_k^{n+1} - \frac{1}{H} \sum_{k=1}^{km} \hat{\mathbf{v}}_k^{n+1} dz_k$$

$$\tilde{\mathbf{u}}_{k}^{n+1} = smooth(\hat{\mathbf{v}}_{k}^{n+1})$$

$$\tilde{\mathbf{u}}_k^{n+1} = \hat{\mathbf{u}}_k^{n+1} - \frac{1}{H} \sum_{k=1}^{m} \hat{\mathbf{u}}_k^{n+1} dz_k$$

Barotropic computations

implicit solve for the free surface height η^{n+1}

new barotropic velocity:

$$\mathbf{V}^{n+1} = \mathbf{V}^{n-1} + 2\Delta t R H S$$

where RHS contains:

- vertically integrated forcing
- $\nabla \eta^{n-1}$, $\nabla \eta^n$, $\nabla \eta^{n+1}$

$$\mathbf{U}^{n+1} = smooth(\mathbf{V}^{n+1})$$

add barotropic velocity back to baroclinic:

$$\mathbf{u}_k^{n+1} = \tilde{\mathbf{u}}_k^{n+1} + \mathbf{U}^{n+1}$$

$$\mathbf{V}_{k}^{n+1} = \widetilde{\mathbf{V}}_{k}^{n+1} + \mathbf{V}^{n+1}$$

step n+1 complete

Barotropic Algorithm - Pop-alpha

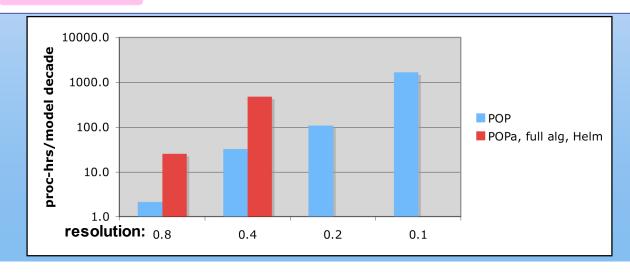
Simultaneously solve for: free surface height η^{n+1} and both velocities, $\mathbf{U}^{n+1}, \mathbf{V}^{n+1}$

Invert using iterative CG routine smoothing within each iteration is too costly!

$$\frac{1}{\tau \gamma g} \nabla \cdot H \mathbf{U}^{n-1} - \frac{2}{\gamma g \tau^2} \boldsymbol{\eta}^n + \frac{1}{\gamma g} \nabla \cdot H \mathbf{I} - \alpha^2 \nabla^2 \right)^{-1} \left[\mathbf{G}^n - \mathbf{B} \mathbf{U}^n - \gamma g \nabla (\boldsymbol{\eta}^{n-1} + \boldsymbol{\eta}^n) \right]$$
momentum forcing terms

$$\mathbf{V}^{n+1} = \mathbf{V}^{n-1} + 2\Delta t \left[\mathbf{G}^{n} - \mathbf{B}\mathbf{U}^{n} - \gamma g \nabla \left(\eta^{n-1} + \eta^{n} + \eta^{n+1} \right) \right]$$

$$\mathbf{U}^{n+1} = (1 - \alpha^{2} \nabla^{2})^{-1} \mathbf{V}^{n+1}$$
momentum forcing terms



Barotropic Algorithm - Pop-alpha

Simultaneously solve for: free surface height η^{n+1} and both velocities, $\mathbf{U}^{n+1}, \mathbf{V}^{n+1}$

Invert using iterative CG routine smoothing within each iteration is too costly!

What if we eliminate just this one smoothing step?

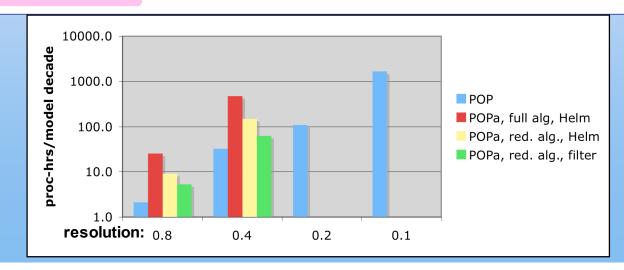
$$\left(\nabla \cdot H(1-\alpha^2\nabla^2)^{-1}\nabla - \frac{2}{\gamma g\tau^2}\right)\eta^{n+1} =$$

$$\frac{1}{\tau \gamma g} \nabla \cdot H \mathbf{U}^{n-1} - \frac{2}{\gamma g \tau^2} \eta^n + \frac{1}{\gamma g} \nabla \cdot H (1 - \alpha^2 \nabla^2)^{-1} \left[\mathbf{G}^n - \mathbf{B} \mathbf{U}^n - \gamma g \nabla (\eta^{n-1} + \eta^n) \right]$$

momentum forcing terms

$$\mathbf{V}^{n+1} = \mathbf{V}^{n-1} + 2\Delta t \left[\mathbf{G}^{n} - \mathbf{B}\mathbf{U}^{n} - \gamma g \nabla (\eta^{n-1} + \eta^{n} + \eta^{n+1}) \right]$$

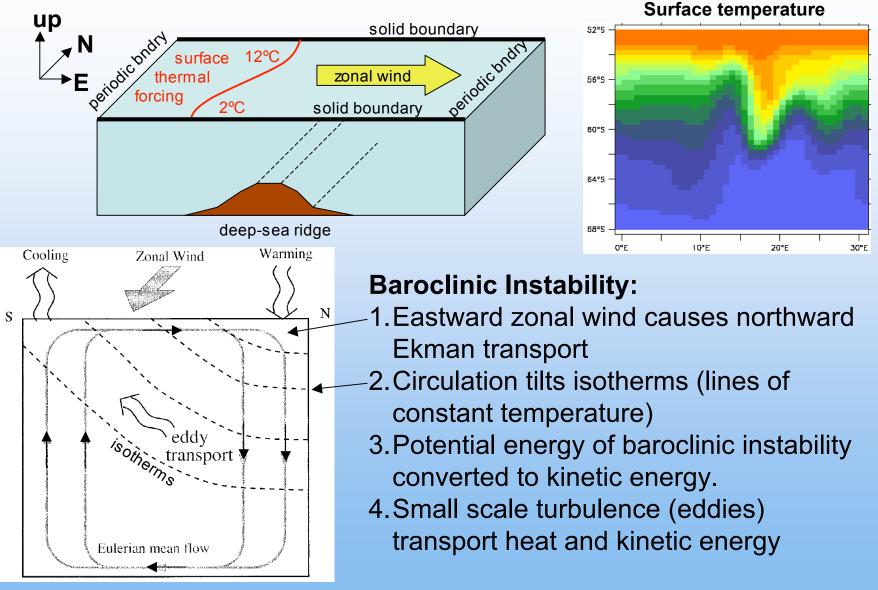
$$\mathbf{U}^{n+1} = (1 - \alpha^2 \nabla^2)^{-1} \mathbf{V}^{n+1}$$
 momentum forcing terms



Outline

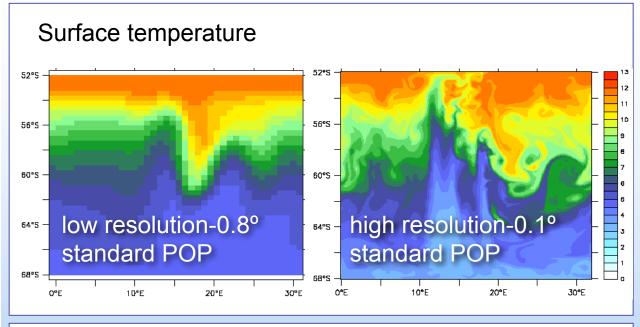
- POP ocean model & climate change assessment
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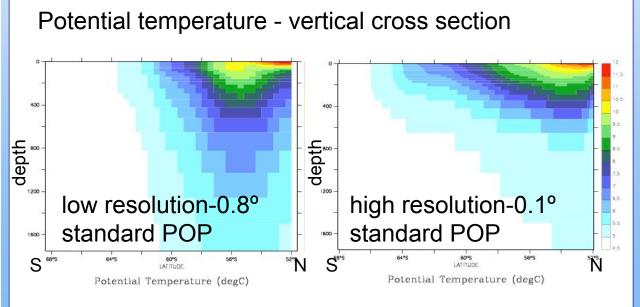
The test problem: Idealization of Antarctic Circumpolar Current

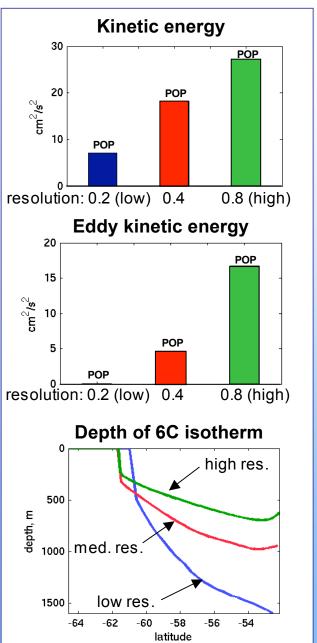


Thermocline depth is determined by the eddy transport quantities.

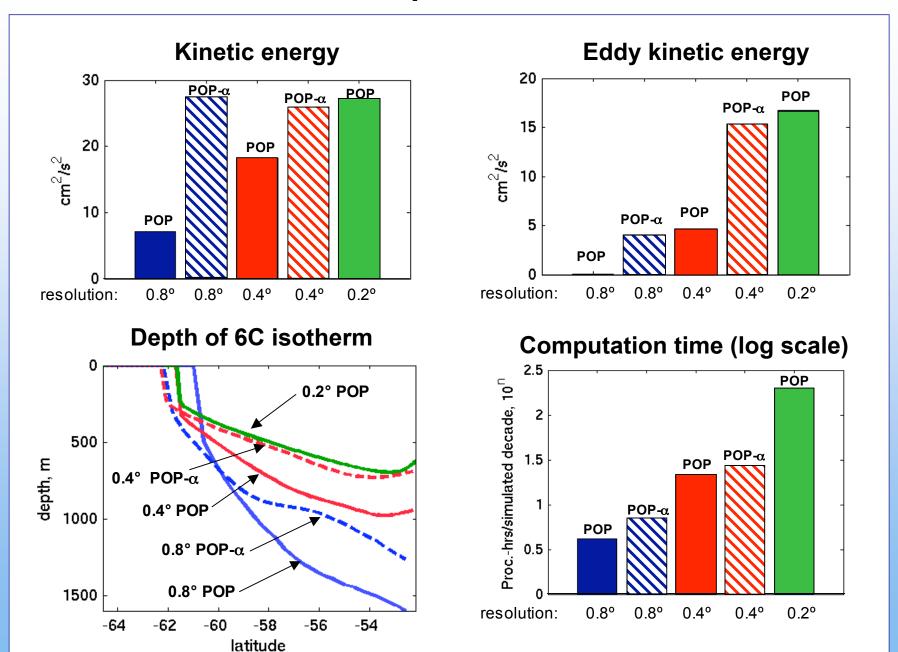
The Baroclinic Instability



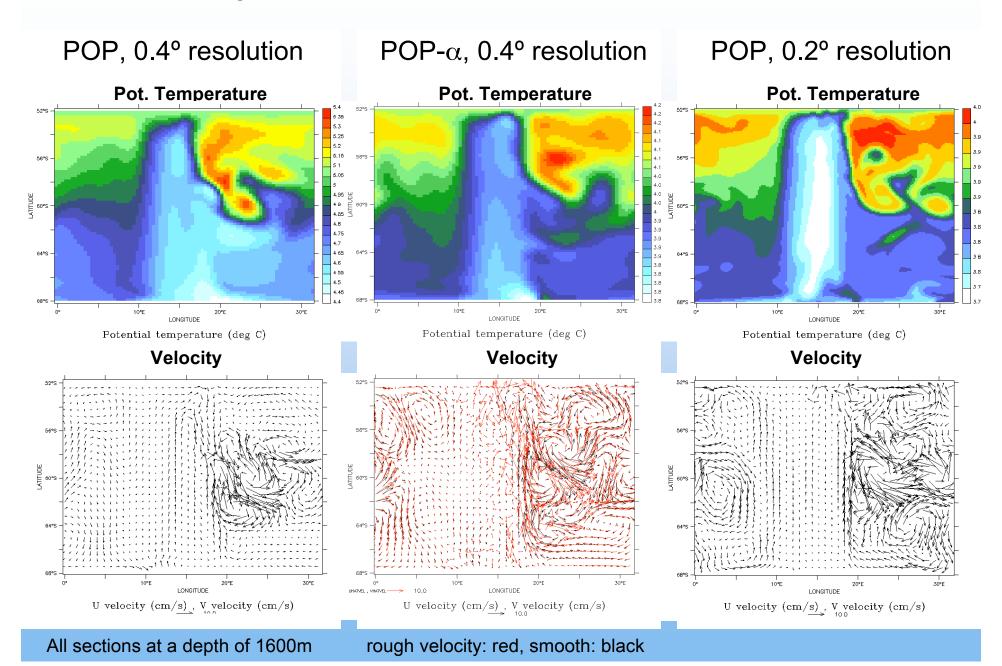




POP-alpha Results



Can you see more eddies with LANS-alpha?



Dispersion Relation for LANS- α using linearized shallow water equations

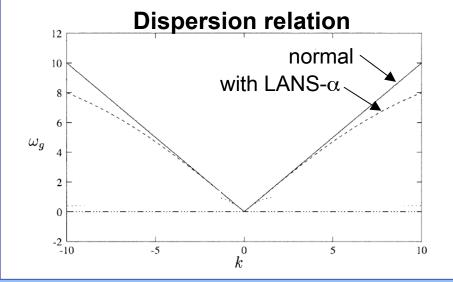
Gravity waves

normally:

$$\omega^2 = k^2 g H$$

with LANS-
$$\alpha$$
: $\omega^2 = \frac{k^2 g H}{1 + \alpha^2 k^2}$

frequency ω , wavenumber k, gravity g, height H



Rossby waves

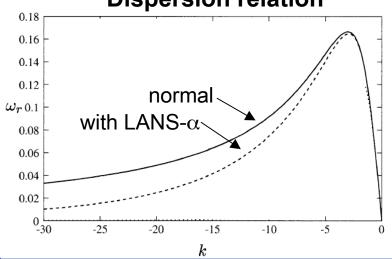
normally:
$$\omega = \frac{-k\beta}{k^2 + 1/R^2}$$

LANS-
$$\alpha$$
: $\omega = \frac{-k\beta}{k^2(1+\alpha^2k^2)+1/R^2}$

Rossby radius
$$R = \sqrt{gH}/f_0$$
 beta $\beta = \partial_y f$

beta
$$\beta = \partial_{v} f$$

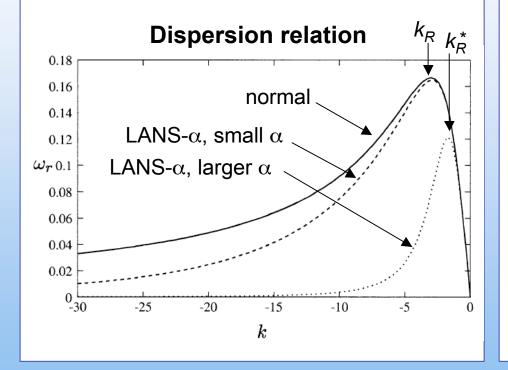
Dispersion relation



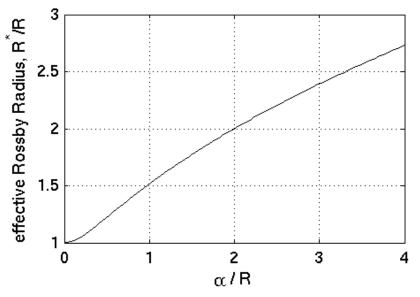
LANS- α slows down gravity and Rossby waves at high wave number.

What does LANS- α do to the Rossby Radius?

Solve for k_R , the wavenumber of the Rossby Radius:



Use that to find R^* , the effective Rossby Radius, as a function of α :

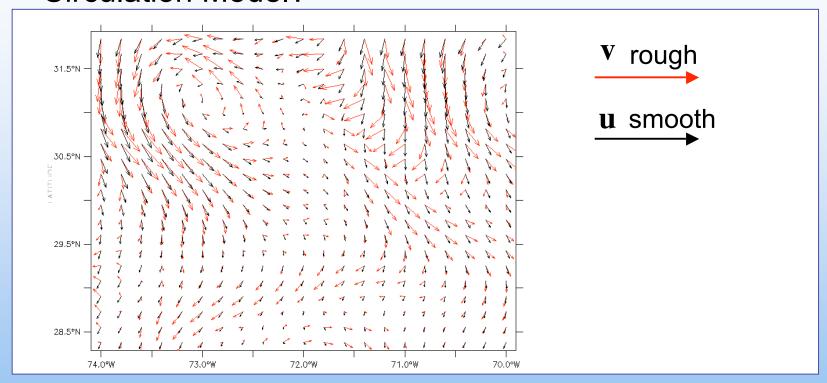


LANS- α makes the Rossby Radius effectively larger.

The POP-alpha model

Issues:

3. How do we smooth the velocity in an Ocean General Circulation Model?



Helmholtz inversion

$$\mathbf{u} = \left(1 - \alpha^2 \nabla^2\right)^{-1} \mathbf{v}$$

is costly!

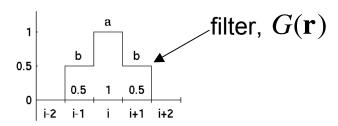
or: use a filter

$$\mathbf{u}(\mathbf{x}) = \int G(\mathbf{r})\mathbf{v}(\mathbf{x} - \mathbf{r})d\mathbf{r}$$

for example, a top-hat filter

Filter Instabilities

1D



filter,
$$G(\mathbf{r})$$

$$\mathbf{u}_i = \frac{b\mathbf{v}_{i-1} + \mathbf{v}_i + b\mathbf{v}_{i+1}}{1 + 2b}$$

If b = 0.5, smoothing filters out the Nyquist frequency.

gridpoints







v rough

u smooth

$$\mathbf{u}_{i} = \frac{b\mathbf{v}_{i-1} + \mathbf{v}_{i} + b\mathbf{v}_{i+1}}{1 + 2b} = \frac{\frac{1}{2}(-1) + 1 + \frac{1}{2}(-1)}{1 + 2\frac{1}{2}} = 0$$

The smooth velocity ${\bf u}$ is blind to this oscillation. Therefore, the free surface height η cannot counter it!

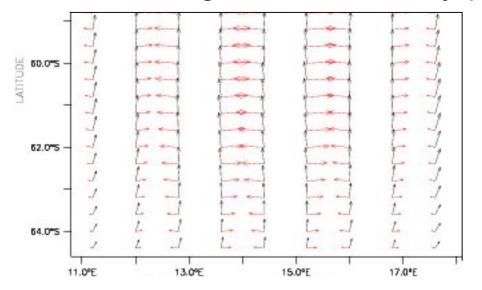
Filter Instabilities

1D

filter,
$$G(\mathbf{r})$$

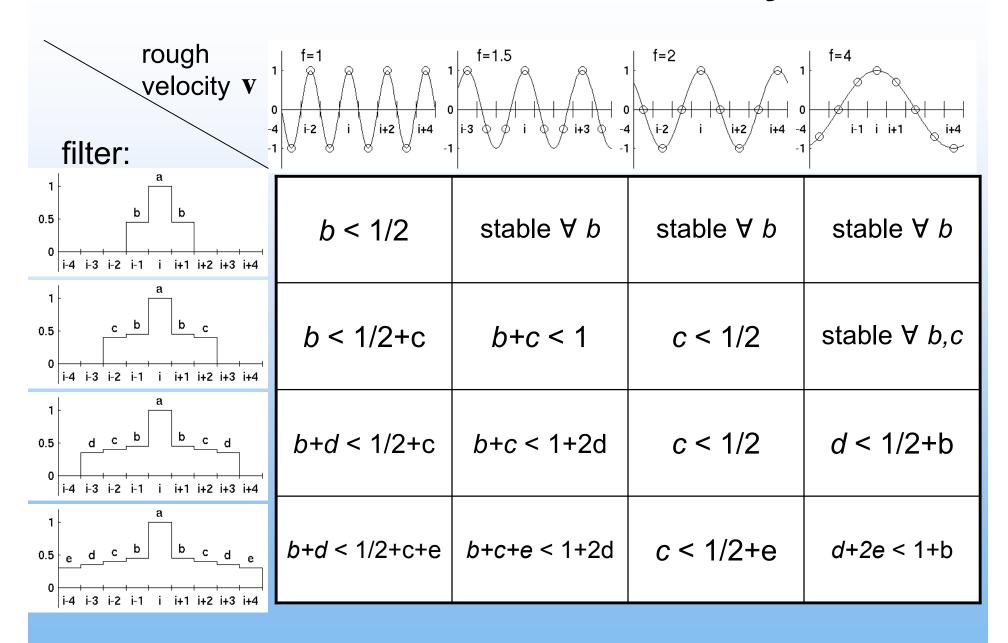
$$\mathbf{u}_i = \frac{b\mathbf{v}_{i-1} + \mathbf{v}_i + b\mathbf{v}_{i+1}}{1 + 2b}$$

If b = 0.5, smoothing filters out the Nyquist frequency.



Condition for stability is b < 0.5

Filter: Conditions for stability

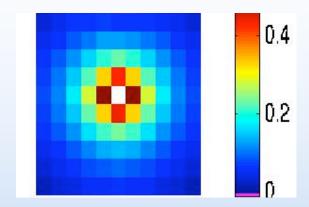


Filter analysis: Helmholtz inversion Green's function

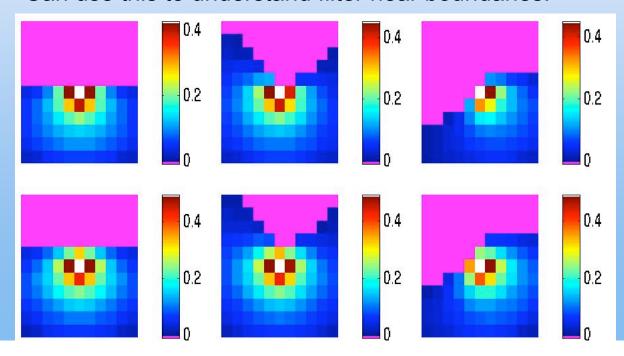
Take **v** to be a point source:

0	0	0	0	0
0	0	0	0	0
0	0	1	0	0
0	0	0	0	0
0	0	0	0	0

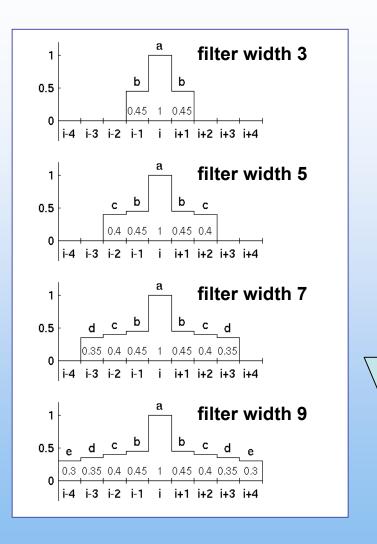
Then compute $\mathbf{u} = (1 - \alpha^2 \nabla^2)^{-1} \mathbf{v}$



Can use this to understand filter near boundaries:

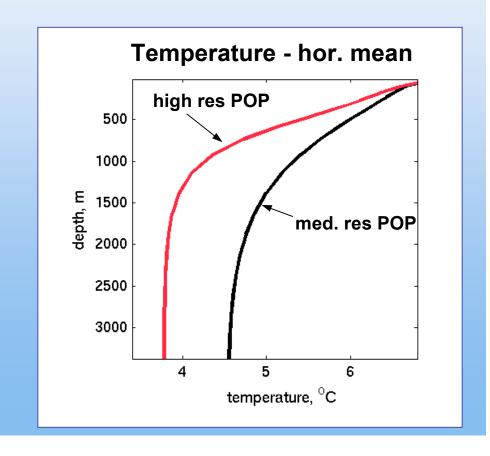


Filters

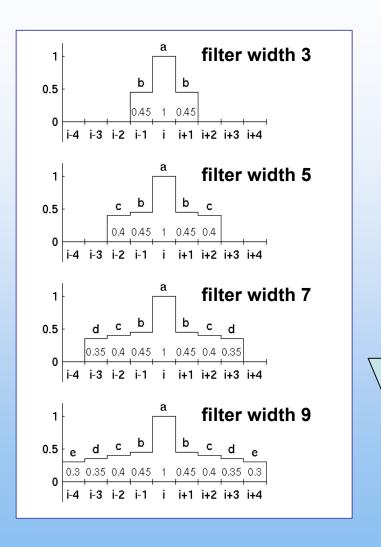


Wider filters result in:

- Stronger smoothing
- Effects are like larger α
- More computation
- More ghostcells

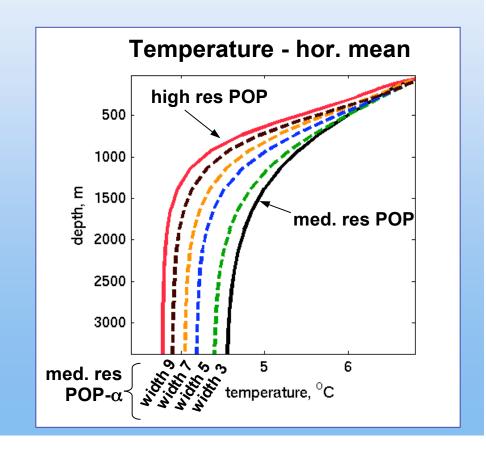


Filters



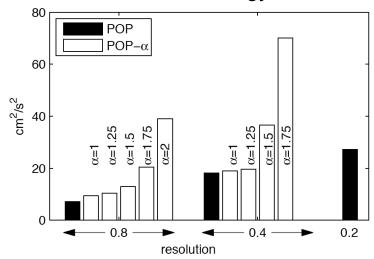
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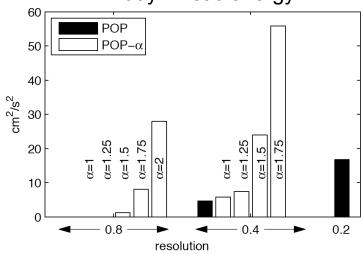


Helmholtz inversion: vary alpha...

Kinetic energy

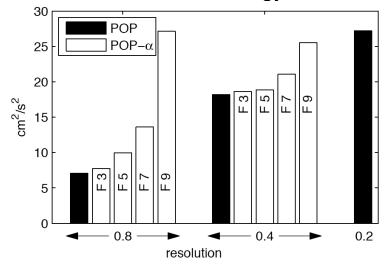


Eddy kinetic energy

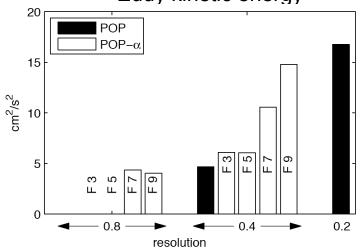


Filters: vary the filter width...

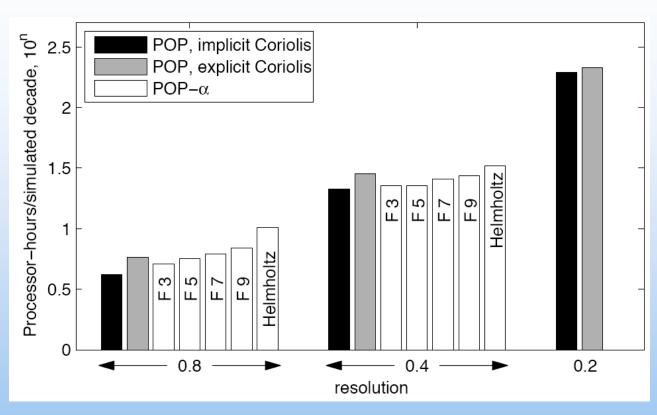
Kinetic energy



Eddy kinetic energy



Adding LANS- α increases computation time by <30%



We can take *smaller* timesteps with LANS- α

How does LANS- α compare with other turbulence models?

POP Hypervisc. only

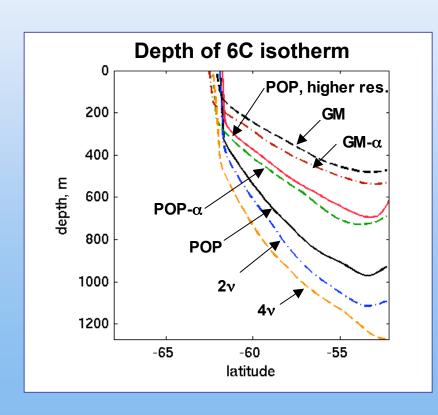
POP- α Hypervisc, LANS- α

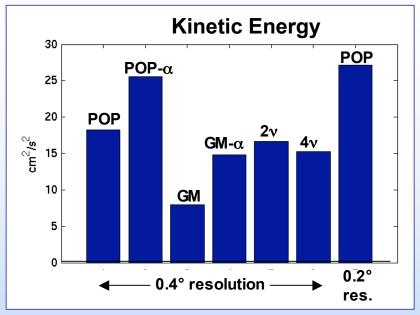
GM Hypervisc, Gent-McW.

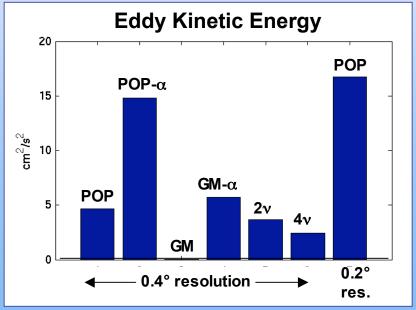
GM- α Hypervisc, Gent-McW, LANS- α

2v Hypervisc, 2x viscosity coef.

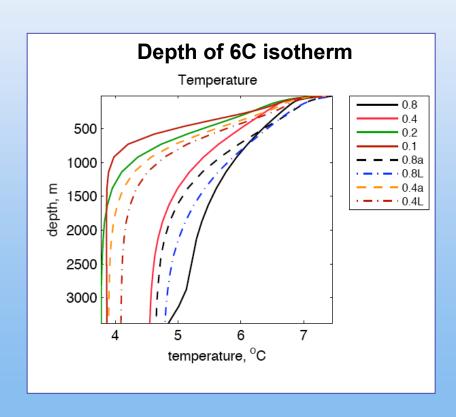
4v Hypervisc, 4x viscosity coef.

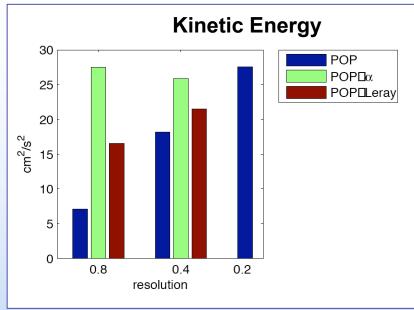


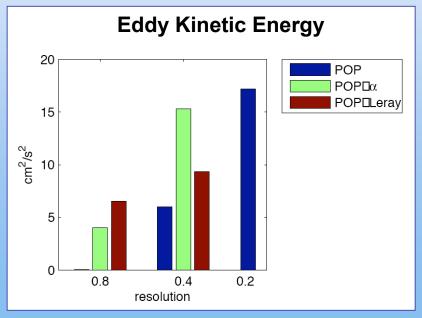




Leray Model is about half as strong as LANS- α





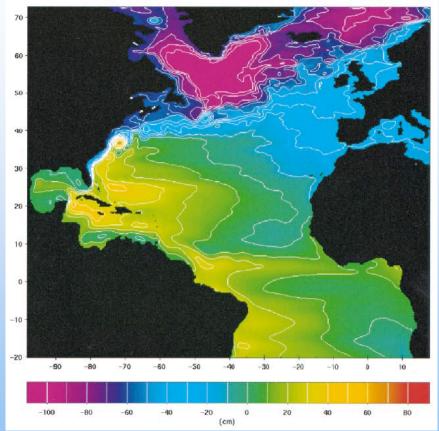


Outline

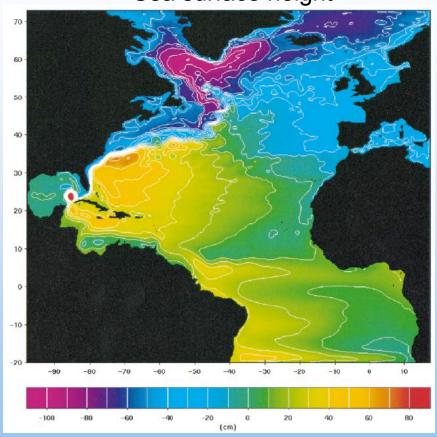
- POP ocean model & climate change assessment
- LANS- α implementation in POP
- Idealized test case: the channel domain
- The real thing: the North Atlantic

POP simulations of the North Atlantic

POP, 0.28° resolution Sea surface height



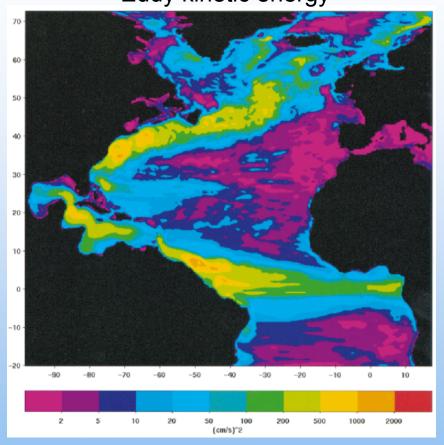
POP, 0.1° resolution Sea surface height



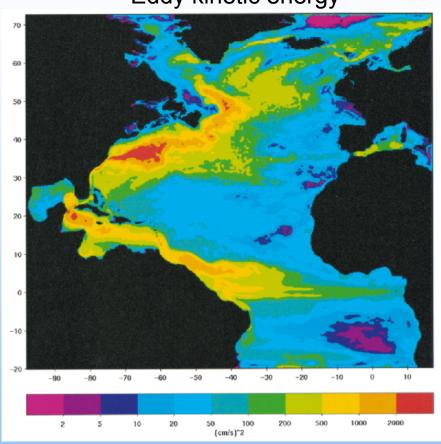
More realistic Gulf Stream and Northwest corner at high resolution

POP simulations of the North Atlantic

POP, 0.28° resolution Eddy kinetic energy



POP, 0.1° resolution Eddy kinetic energy

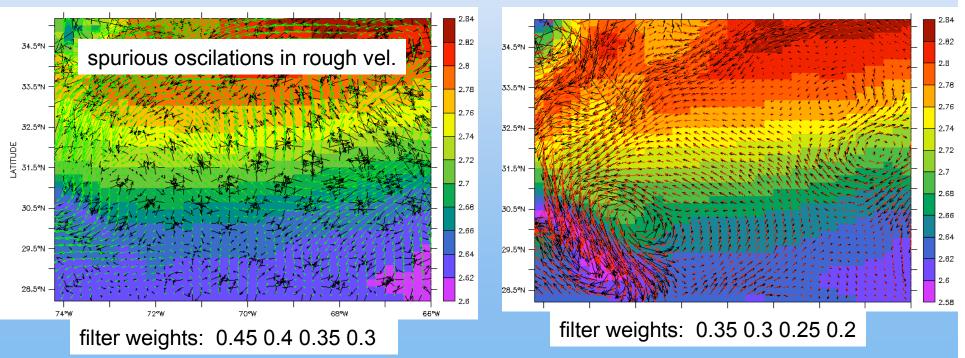


Higher eddy kinetic energy at high res.

LANS- α in POP: North Atlantic simulations

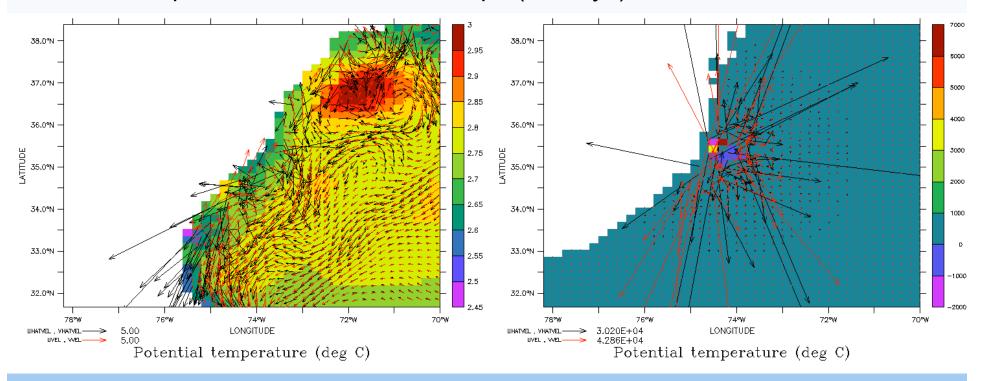
The punch lines:

- 1. Due to rough boundaries and fast jets in realistic domains, both POP- α and Leray have numerical instabilities in the North Atlantic, particularly at boundaries.
- The Leray Model runs longer in the North Atlantic, and has higher EKE and visibly more vortices (but still boundary issues).
- 3. The key is to use the right boundary conditions for the smoothing step (Helmholtz or filter).



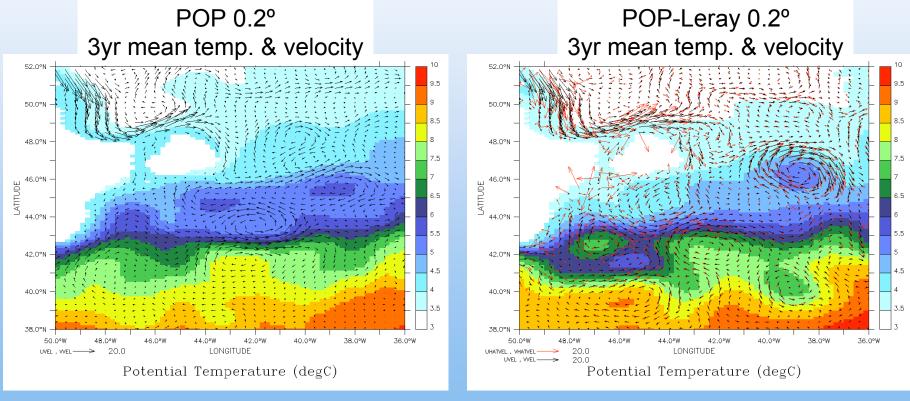
LANS- α in POP: North Atlantic simulations

Even with lower filter weights, numerical instabilities at boundary stop code after 6000 time steps (70 days):



Leray Model runs stably in North Atlantic

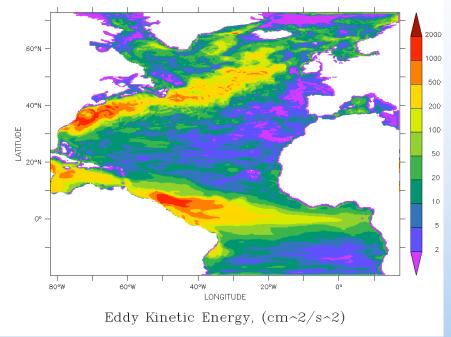
$$\frac{\partial \mathbf{v}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{v} + \underbrace{v_j \nabla u_j}_{-\mathbf{f}} - \mathbf{f} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla p + v \nabla^2 \mathbf{v} + \mathbf{F}$$
extra nonlinear term not in Leray model



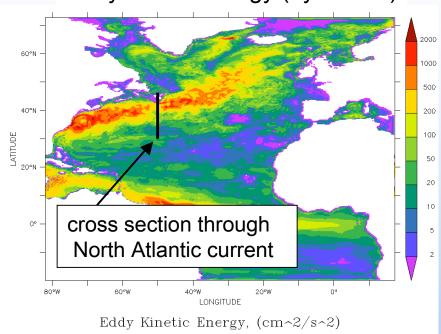
Leray Model has visibly more vortices, but still boundary issues.

POP-Leray has higher KE and EKE than POP

POP 0.2° Eddy kinetic energy (3yr mean)



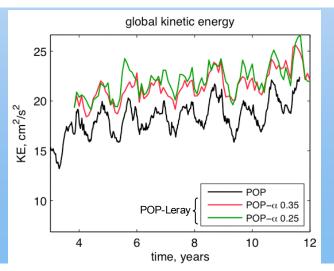
POP-Leray 0.2° Eddy kinetic energy (3yr mean)



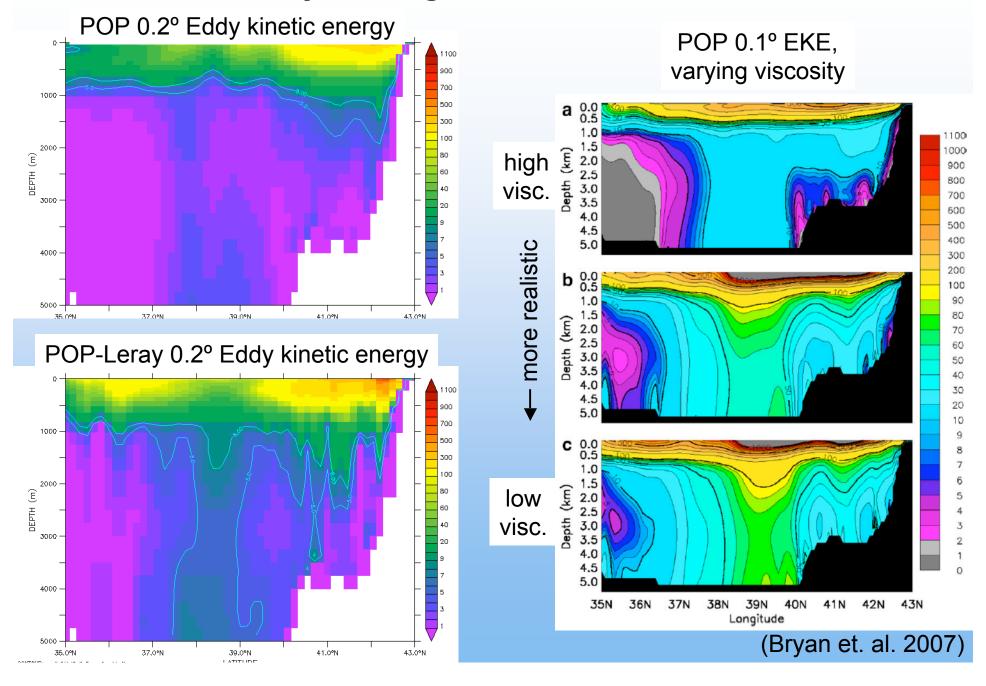
Globally averaged EKE (3 yr mean):

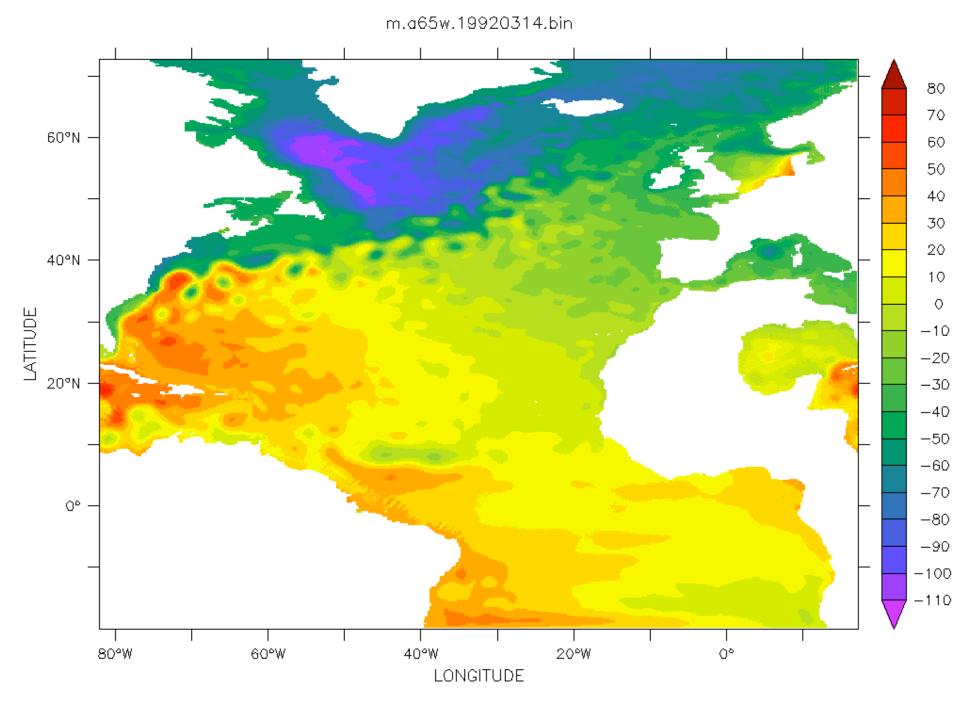
POP 0.2°: 11.1 POP-Leray 0.2°: 13.1

POP 0.1°: 29.4 (Smith et. al. 2000)



POP-Leray has higher KE and EKE that POP



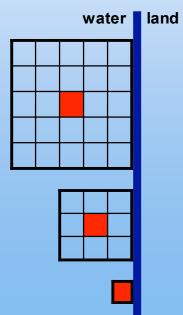


Sea surface height (cm)

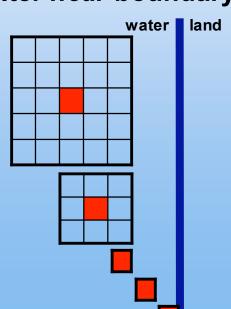
What are my boundary conditions?

B.C.	Equation
$\mathbf{v} = 0$	$\partial_t \mathbf{v} + \mathbf{u} \cdot \nabla \mathbf{v} + v_j \nabla u_j - \mathbf{f} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla p + v \nabla^2 \mathbf{v} + \mathbf{F}$
$\mathbf{u} = 0$	$\mathbf{u} = \left(1 - \alpha^2 \nabla^2\right)^{-1} \mathbf{v}$
I've tried many!	$\mathbf{u} = filter(\mathbf{v})$

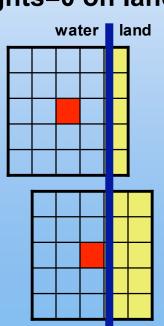
Option 1: shrink filter at boundary



Option 2: shrink filter *near* boundary



Option 3: make filter weights=0 on land



A Possibility: Use variable alpha

$$\begin{cases} \partial_t \mathbf{v} + \mathbf{u} \cdot \nabla \mathbf{v} + |\nabla \mathbf{u}|^2 \nabla \alpha^2(\mathbf{x}) + v_j \nabla u_j - \mathbf{f} \times \mathbf{u} = -\frac{1}{\rho_0} \nabla p + v \nabla^2 \mathbf{v} + \mathbf{F} \\ \mathbf{u} = \left(1 - 2\alpha(\mathbf{x}) \nabla \alpha(\mathbf{x}) \cdot \nabla - \alpha^2 \nabla^2\right)^{-1} \mathbf{v} \end{cases}$$

We are thinking about this...

Summary

- Higher resolution can solve all of your problems.
- You can't possibly have high enough resolution to solve your problems.
- The LANS-alpha model captures higher-resolution effects in our test problem, where eddies near the grid-scale are important.
- POP-Leray runs longer than POP- α in the North Atlantic domain, and shows promising signs, like higher eddy activity
- Both POP-α and POP-Leray have problems with the rough boundaries and topography of the North Atlantic.
- Further work on boundary conditions for LANS-alpha, with Helmholtz or filter smoothing, is required.