

Errata: Mechanics and Symmetry

Jerrold E. Marsden and Tudor Ratiu

December 11, 1996

We appreciate being informed about additional corrections. We do not include all stylistic or spelling corrections in this list. Additional corrections can be sent to marsden@cds.caltech.edu. We are especially grateful to Anthony Bloch, Hermann Flaschka, Meinhard Mayer, Peter Mucha, Juan-Pablo Ortega, and other readers for notifying us of corrections.

Errata

Chapter 1—Introduction and Overview

- Page 2, 4 lines before equation (1.1.1): the second L should have a dependence on t included.
- Page 4, In equation (1.1.14): the ∂ in the denominators of the right hand sides of equations should be δ .
- Page 9, the equation displayed after equation (1.3.2): the c should be C .
- Page 13, In the third paragraph: delete the reference to Chapter 13 (this chapter will appear in a future volume).
- Page 14, line 1: add a question mark at the end of the line.
- Page 20, the line after (1.6.6) should read: “where $\delta F/\delta \mathbf{E}$ and $\delta F/\delta \mathbf{B}$ are vector fields with $\delta F/\delta \mathbf{B}$ divergence free defined in the” and two lines after (1.6.7), delete the “div”.
- Page 34, on the bottom line: **1.10-3** should be **1.10-4**.
- Page 36, line 4↑: φ should be θ .

Chapter 2—Hamiltonian Systems on Linear Symplectic Spaces

- Page 52, line 7: Crough should be Crouch.
- Page 61: (2.4.10) should be to the preceding display.
- Page 62, in the line right after the box: the first Ω should be Ω_z .
- Page 67, in 2.6-1(b): omit the part of the first sentence preceding “show that”.
- Page 68, line following equation (2.7.7): the reference to 3.1 should be to 3.2.
- Page 69, line 7↑: omit the first (.
- Page 70, in Exercise 2.7-3: ϕ should be assumed to be a linear symplectic map.
- Page 74, on line 6↑: insert a minus sign after the last equals sign.
- Page 78, line 8: insert] before the }.
- Page 81, in the lower part of Figure 2.10.4: the arrows on the right hand side are going in the wrong direction.
- Page 83, the line after (2.11.4) should read: “From this point of view, θ gets identified with time and the curve”, two lines below this, (2.11.2) should be (2.11.4) and on line 5↑, $\bar{x}_0(0)$ should be $\bar{x}(0)$.
- Page 83 The proof of Theorem 2.11.1 requires corrections: please request the corrected file if needed.
- Page 86, Example C(iii): add a (before “transversal”.

Chapter 3—An Introduction to Infinite-Dimensional Systems

- Page 99, in line 5: the H should be H_1 and in line 4↑, H should be h .
- Page 100, in line 2↑: $u_t d^3 x$ should be $u_t dx$.
- Page 104, in (3.3.6): $P_x(\varphi)$ should be $P_x(\varphi, \pi)$.
- Page 105, on line 3: §3.3 should be §3.2. In (3.3.11) delete the period.
- Page 107, in F_1 : the u^3 should be u^2 and in F_3 the first plus should be a minus, and there should be a factor of $\frac{1}{2}$ in front of the $(u_{xx})^2$ term.

Chapter 4—Interlude: Manifolds, Vector Fields, Differential Forms

- Page 117, line 7: 4.2.4ii should be 4.2.4iv.
- Page 119, last line of 1(a) in the box: e^3 should be e_3 .
- Page 121, in (4.3.5) : add (x) at the end of the equation.
- Page 122, in line 7↑: μ should be μ_2 and in the next line, Q should be a zero.

Chapter 5—Hamiltonian Systems on Symplectic Manifolds

- Page 133, in line 2↑ and in (5.1.3): replace $[n/2]$ by $n(n-1)/2$.
- Page 134, In the line following (5.2.1): P should be P_1 .
- Page 143, Just below the middle of the page, in the last line of the display: Ω_z^* should be Ω_z^b .
- Page 146, At the end: **5.4-2** should be **5.4-3**.

Chapter 6—Cotangent Bundles

- Page 149, In line 8↑: **6.1.6** should be **6.1.1**.
- Page 151, In line 12: α_i should be α_j and three lines below that, B^i should be B^j (twice) and $= p_i^0$ should be p_j^0 .
- Page 152, Exercise 6.6.2: add “ $\circ \mathbf{d}f$ ” to the end of the line.
- Page 154, In line 3: Delete the extra)
- Page 162: Replace the sentence after (6.8.1) “However, one really,...” by “However, at a fixed point, one really wants to use the given symplectic form evaluated at the fixed point, which has the expression $d(\delta q^i) \wedge d(\delta p_i)$, (6.8.2) while (6.8.1) restricts to zero.”
- Page 164: Delete the text from line 9↑ to the third line after (6.8.11) on page 165. Also delete the last sentence of the paragraph including formula (6.8.12).

Chapter 7—Lagrangian Mechanics

- Page 166: the ∂ in the first line of (6.8.16) for dp_i/dt should be a d and in the third line, w^i should be w_i .
- Page 182, line 2↑: add a) before the right hand angle bracket.

- Page 191, Section 7.9 has been rewritten: if you are reading this section, please request a revised copy from the authors.
- Page 198, line 1: **7.8-2** should be **7.9-2**.

Chapter 8—Variational Principles, Constraints, Rotating Systems

- Page 219, In problem 8.1-2: insert a minus sign in front of the right hand side.

Chapter 9—An Introduction to Lie Groups

- Page 244, on the last line: ϕ_2 should be ϕ_{g_2} and ϕ_1 should be ϕ_{g_1} .
- Page 245: the two g 's in the left hand side of the figure should be h 's.
- Page 251, in the first line of Example (b): it should be $\mathfrak{g} = L(\mathbb{R}^n, \mathbb{R}^n)$.
- Page 255, in line 3 \uparrow : $\phi(x)$ should be $\phi^{-1}(x)$ and in the second line of the remark, banach should have a capital B.
- Page 258, in line 3 \uparrow : a_4^2 should be a_3^2 .
- Page 259, in line 3: \mathbb{R} should be \mathbb{R}^3 and in the 4th line of the proof of 9.2.5, $|\lambda|$ should be $|\lambda|^2$.
- Page 261, in the line above (9.2.7): the superscript $2n - 1$, should be $n - 1$.
- Page 262, in the first line of Proposition 9.2.8: “nonconnected” should read “connected”.
- Page 263, line 5 at the end of the line: in the expression for A^T , swap w and z .
- Page 265: the last x in the first display should be z .
- Page 270, in line 2 of (b): delete the redundant “for $\mathbf{x} \in \mathbb{R}^3$ and $A \in SO(3)$ ”.
- Page 274, in line 4: $\Phi_g(\exp t\xi, \Phi_{g^{-1}}(x))$ should be $(\Phi_g \circ \Phi_{\exp t\xi} \circ \Phi_{g^{-1}})(x)$.
- Page 276, in line 5 of Remark 3: the second Ad should be ad.
- Page 277, three lines above part (c): $\mathfrak{l} = \{B \in$ should be $\mathfrak{l} = \{A \in$.
- Page 279, line 3 \uparrow : $\eta(0) = \eta$ should be $\eta(0) = 0$.

Chapter 10—Poisson Manifolds

- Page 289, In (10.2.13): the last \mathbf{a} should be \mathbf{b} .
- Page 290, In the first line of Exercise 10.2-4: change G to H .
- Page 297, line 4 of Proposition 10.5.2: the last $=$ should be \in .
- Page 299–300, 307–308, 313: the symbols \mathcal{L} should be \mathcal{L} (the Lie derivative).
- Page 307, in Exercise 10.6-2: delete the reference to the nonexistent exercise 5.5-4.
- Page 308, line 2: multiply the second term on the right hand side by F and the third by G .
- Page 309, line 8 \uparrow : the sub π should be on line.
- Page 315, in line 9: z should be Z .
- Page 317, at the end of line 4: $T_x M$ should be $T_x^* M$.
- Page 320, in (10.9.13): the second two μ 's should be ν 's.
- Page 321, in line 3 \uparrow : $B(\mu)$ should be $\langle \cdot, \mu \rangle$.
- Page 321, on lines 4 and 8 \uparrow : V should be V^* .

Chapter 11—Momentum Maps

- Page 328: J should be \mathbf{J} .
- Page 330, in Exercise 11.4-1: the reference should be to equation (10.7.3).
- Page 331: insert a minus after the last $=$ in (11.5.6) and in line 5 \uparrow , (\mathbf{p}) should be (\mathbf{q}, \mathbf{p}) .
- Page 333, second line after (11.5.16): \mathfrak{g}^* should be \mathfrak{g} .

Chapter 12—Computation and Properties of Momentum Maps

- Page 340, line 8 \uparrow : add $($ at the beginning of the line.
- Page 342, line 2 \uparrow : the last $g \cdot \alpha_q$ should be $g \cdot q$.
- Page 344, line 12: $\xi_P(p) = d/dt|_{t=0} T_p \varphi_t$ should be $\xi_P(v_q) = d/dt|_{t=0} T_q \varphi_t(v_q)$.
- Page 345, in (12.3.1): N should be $3N$.
- Page 351, in Exercise 12.3-4: in the integral, the J should be bold.

- Page 352, line 7: the (after the second = should be \langle .
- Page 356, on the line after (12.4.26): the \mathfrak{g} should have a prime on it.
- Page 360, in Exercise 12.5-3: $F_{F \circ J}$ should be $X_{F \circ J}$ and the last J on the line should be bold.

Chapter 13—Euler-Poincaré and Lie-Poisson Reduction

- Page 371, line 10 \uparrow : ξ_Q should be ξ_G .
- Page 379, line 8 \uparrow : $T_{g(t)}^* L$ should be $T_e^* L_{g(t)}$.
- Page 380, the proof of 13.6.2 is incomplete: please ask the authors for the complete proof if needed.
- Page 392, line 6 \uparrow : ∂x^b should be $\partial \xi^b$.
- Page 395, three lines after (13.8.22): delete the minus sign in $u_t = -\dots$

Chapter 14—Coadjoint Orbits

- Page 400, in the first line of (14.1.1): $\mathbf{A}^{-1}\hat{\mathbf{v}}$ should be $(\mathbf{A}^{-1}\mathbf{v})$.
- Page 401, in the line above Example (c): β -axis should be α -axis.
- Page 413, at the end of Example (b): the expression for the orbit symplectic structure should be $\omega^- = (1/\beta)d\alpha \wedge d\beta$ and on the preceding line, “in coordinates (q, p) ” should be “in coordinates (α, β) .”
- Page 421, in line 8: “ ab ” should be “ ad ”.
- Page 423, in (14.8.12): the matrix associated with \mathbf{X}_2 should be $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ and in the right hand part of figure 14.8.1, the axes should be relabeled: a should be c , c should be $a - b$ and b should be $a + b$. In the caption, $\mathfrak{se}(3)^*$ should be $\mathfrak{se}(2)^*$.
- Page 430, in Exercise 14.9-3: on the last row of the matrix g , interchange a and b and add the condition $|a|^2 - |b|^2 = 1$.

Chapter 15—The Free Rigid Body

- Page 437: Figure 15.3.1 (and on the cover) shows the case $I_1 < I_2 < I_3$. Add this to the figure caption.
- Page 438, in equation (15.4.6): delete the stray apostrophe.
- Page 450: The sum preceding (15.9.4) should start at $i = 1$.

- Page 451, on line 9: longest should be shortest.
- Page 451, on line 16: short should be long.
- Page 455, in the expression for a_{66} on the line following (15.10.7): there should be a factor of 2 in front of the last term, $\Pi_3^0 d$.
- Page 456, in the second displayed equation: the second factor (multiplying the big squared term) should be

$$\left[a_{66} \left(\frac{1}{I_3} + a + c \right) - a_{36}^2 \right]$$

- Page 456: equation (15.10.10) should read

$$a_{66} \left(\frac{1}{I_3} + a + c \right) - \left(\dot{\Phi}(\Pi_3^0, 1) + \Pi_3^0 c + d \right)^2 > 0$$

- Add the following to the references: Bloch, A.M., H. Flaschka, and T.S. Ratiu [1993] A Schur-Horn-Kostant convexity theorem for the diffeomorphism group of the annulus. *Inv. Math.* **113**, 511–529.