

Dynamical Systems and Space Mission Design

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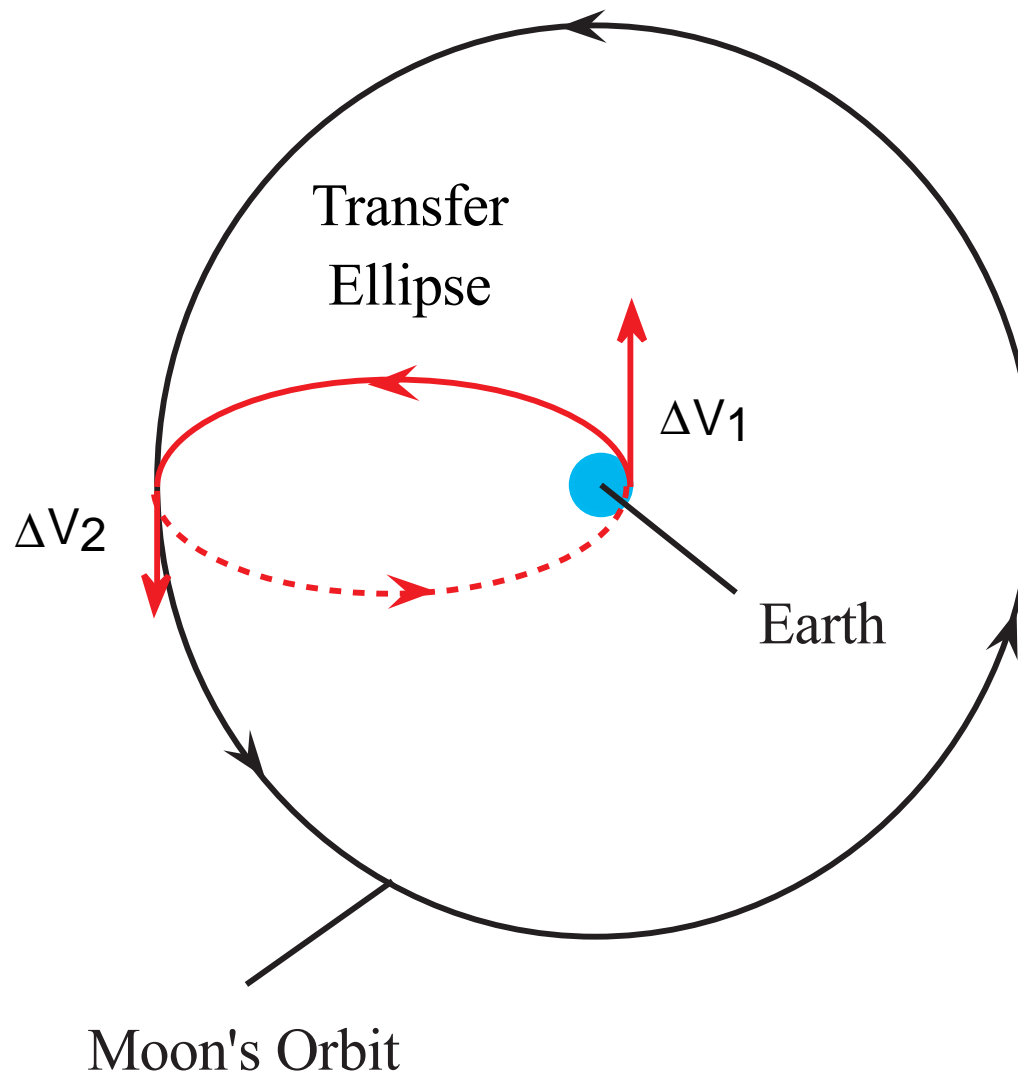
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■ Acknowledgements

- ▶ H. Poincaré, J. Moser
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- ▶ C. Simó, J. Llibre, R. Martinez
- ▶ E. Belbruno, B. Marsden, J. Miller
- ▶ G. Gómez, J. Masdemont
- ▶ K. Howell and the Purdue group

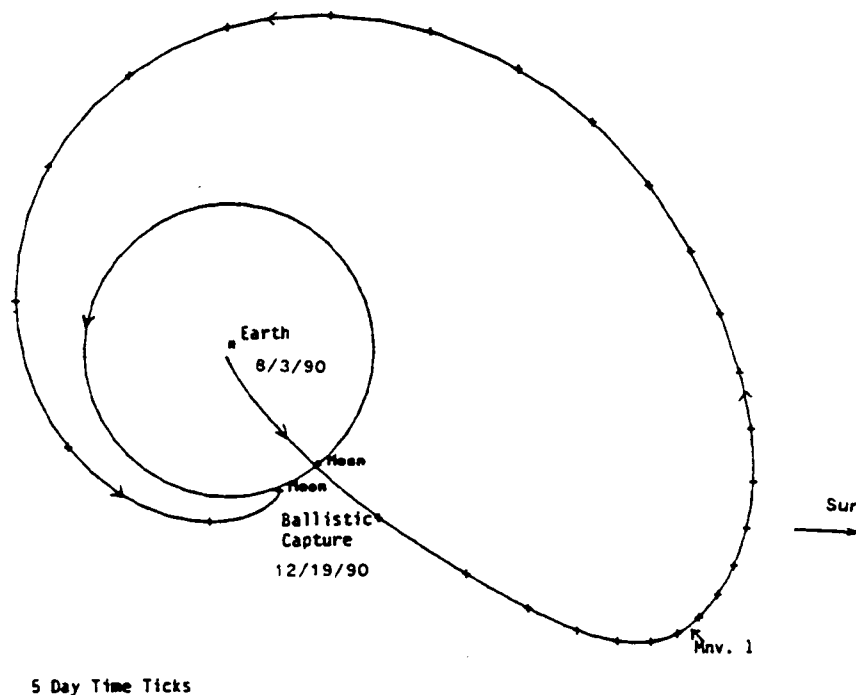
■ Introduction: Hohmann Transfer

- ▶ Traditional transfer from Earth to Moon is by **Hohmann transfer**.
- ▶ 2 body Keplerian **ellipse** from Earth to Moon. Need 2 ΔV s.



■ Sun-Perturbed E-M Transfer with Ballistic Capture

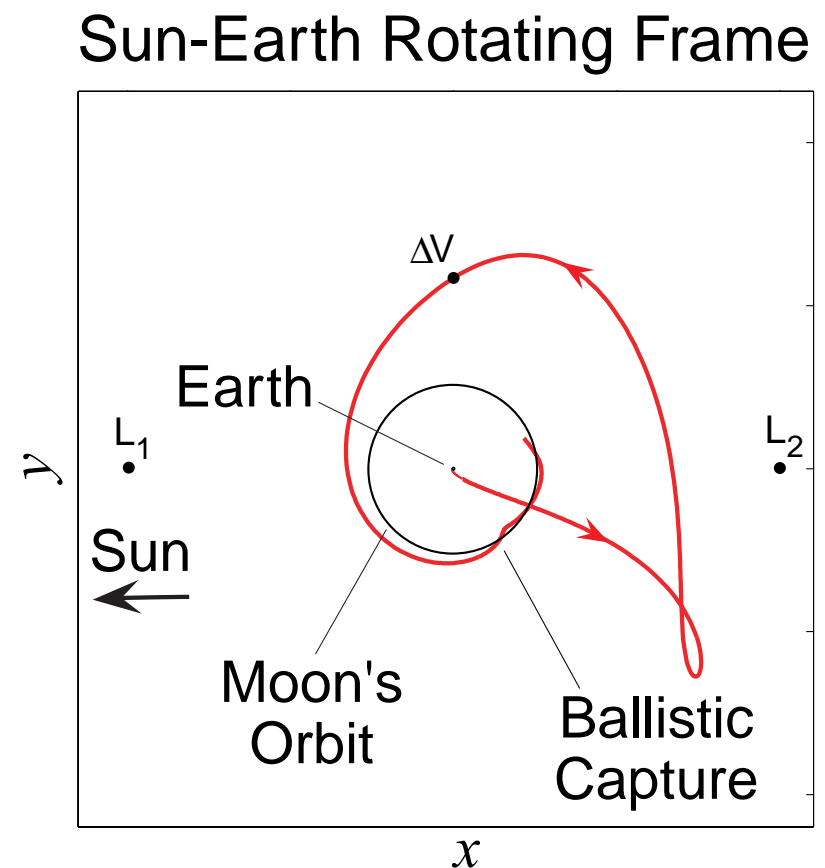
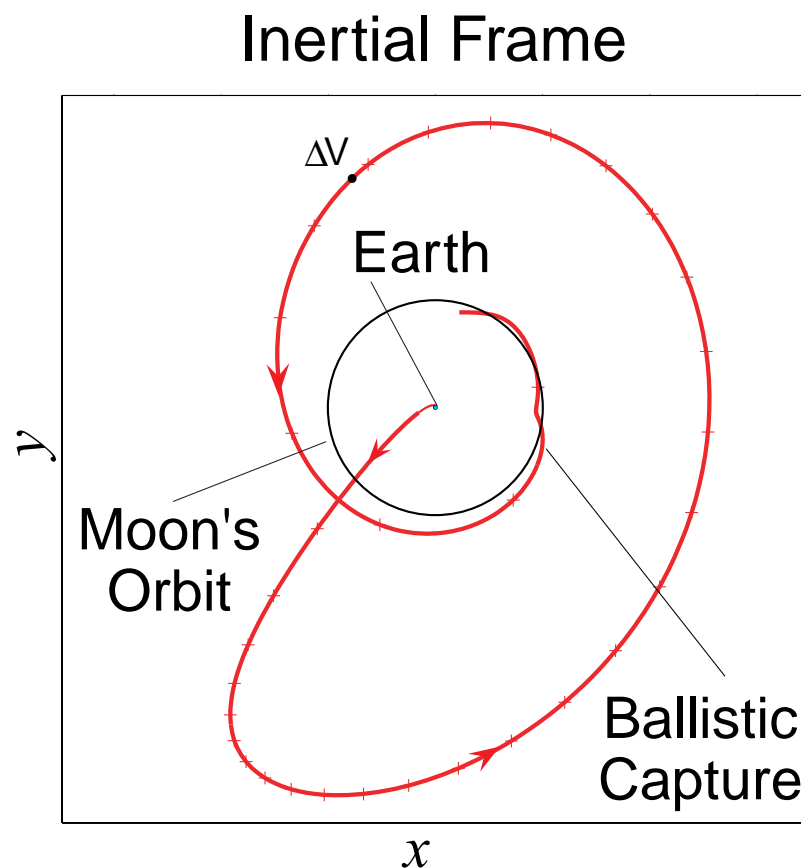
- ▶ In 1991, Muses-A did not have enough propellant to reach Moon by **Hohmann transfer**.
- ▶ Belbruno/Miller designed a **Sun**-perturbed **Earth-to-Moon transfer** with **ballistic capture** at Moon.
- ▶ Similar techniques used by Japanese team to save mission.



Numerical simulation of a ballistic capture transfer trajectory for the Japanese spacecraft Hiten: ecliptic plane projection, sun's direction indicated at Earth injection. (from Belbruno and Miller [1993])

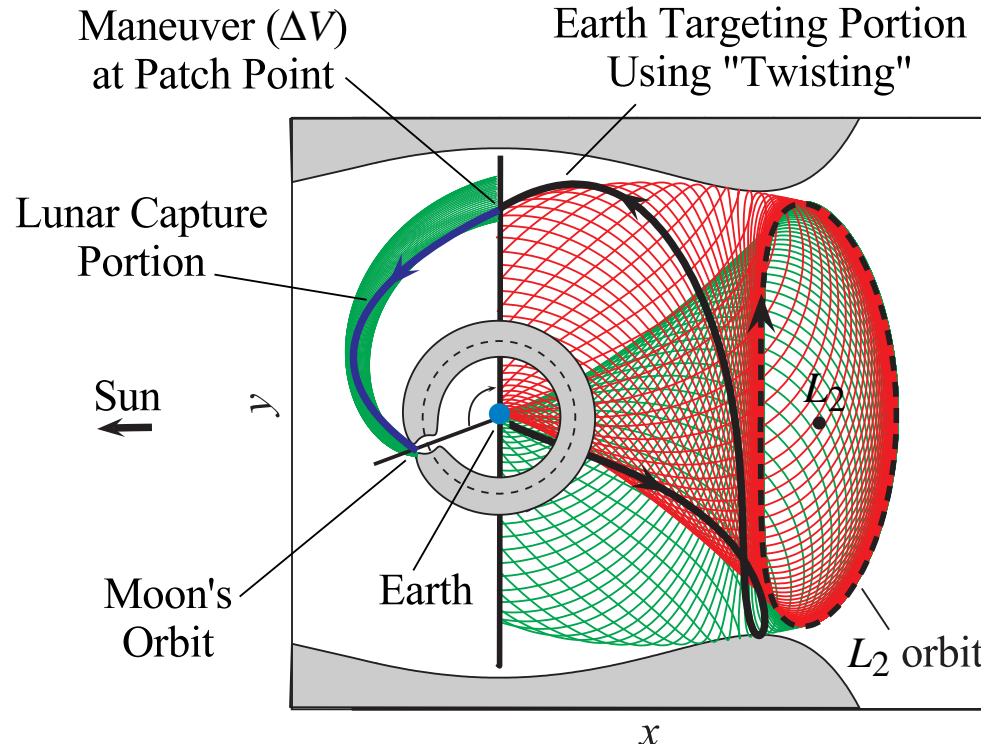
■ Sun-Perturbed E-M Transfer with Ballistic Capture

- ▶ We provide a **theoretical basis** and a **numerical procedure** for constructing such ballistic capture transfer.
- ▶ By considering **Sun-Earth-Moon-SC 4-body system** as **2 coupled 3-body systems**.
- ▶ Better seen in Sun-Earth **rotating frame**.



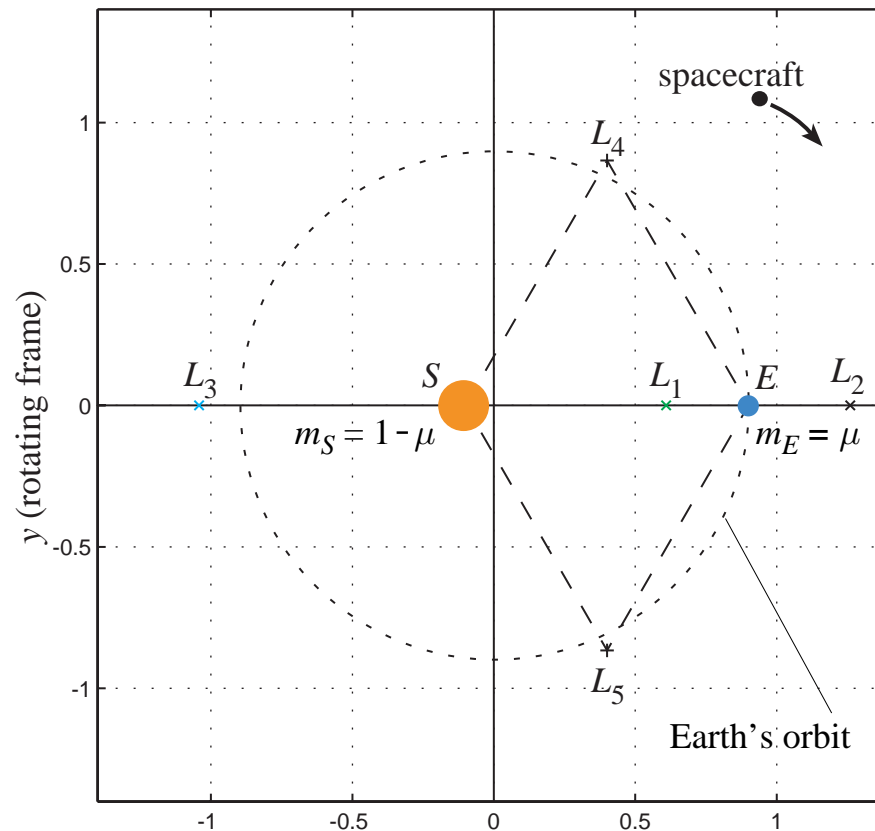
■ Introduction: Coupled 3-Body Systems

- ▶ Find **position/velocity** for spacecraft
 - integrating **forward**, SC guided by **Earth-Moon manifold** and get ballistically captured at Moon;
 - integrating **backward**, SC hugs **Sun-Earth manifolds** with a twist and return to Earth.
- ▶ Based on **Koon, Lo, Marsden and Ross [2000]**.



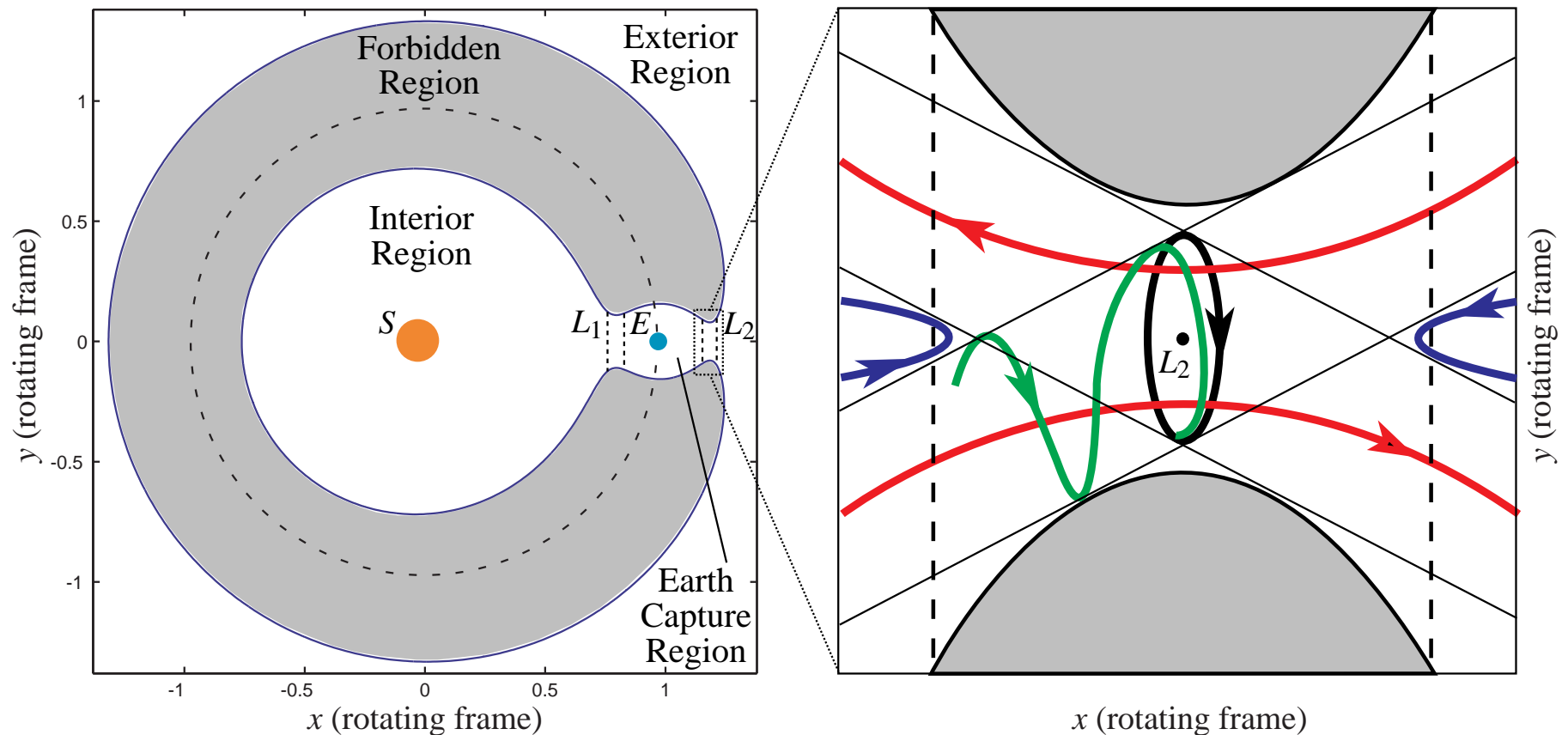
■ Planar Circular Restricted Three-Body Problem

- ▶ Sun and Earth **total mass** normalized to 1;
rotate about center of mass, with **angular velocity** equal to 1.
3rd body has infinitesimal mass.
- ▶ **Rotating coordinate system** with origin at center of mass,
S and E fixed at $(-\mu, 0)$ and $(1 - \mu, 0)$.
- ▶ Has 3 unstable **equilibrium points** on S-E line.



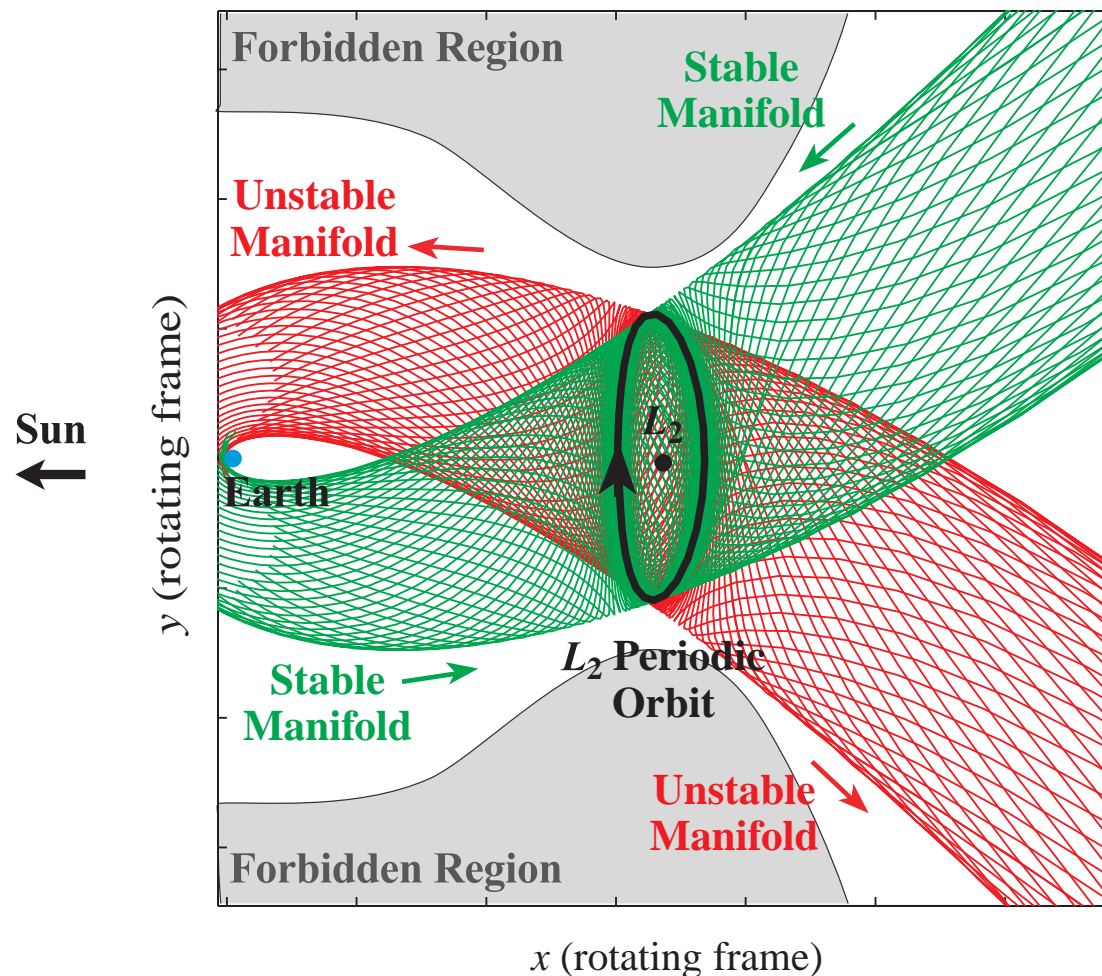
■ PCR3BP: The Flow near L_1 and L_2

- ▶ For **energy value** just above that of L_2 , **Hill's region** contains a “**neck**” about L_1 & L_2 .
- ▶ SC can make **transition** through these equilibrium regions.
- ▶ 4 types of orbits:
periodic, **asymptotic**, **transit** & **nontransit**.



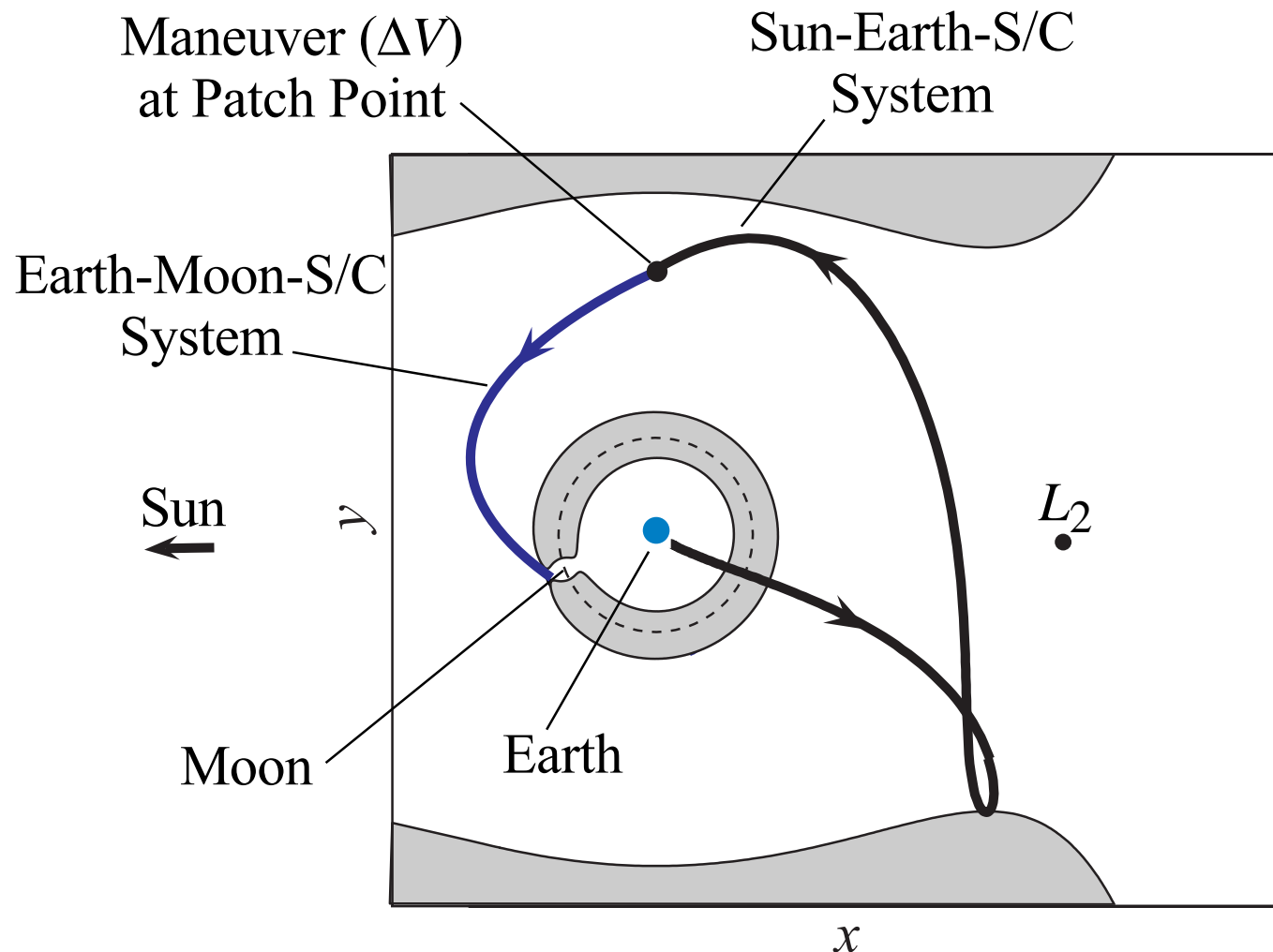
■ PCR3BP: Invariant Manifold as Separatrix

- ▶ **Invariant manifold tubes** act as **separatrices** for the flow in equilibrium regions.
 - Those inside the tubes are **transit** orbits.
 - Those outside the tubes are **non-transit** orbits.



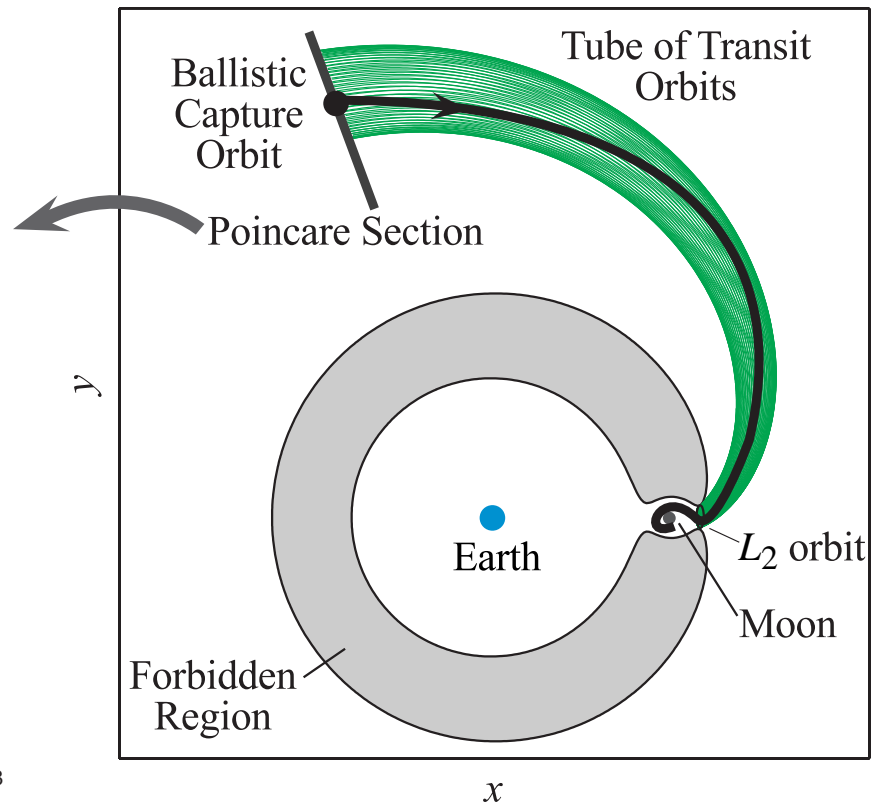
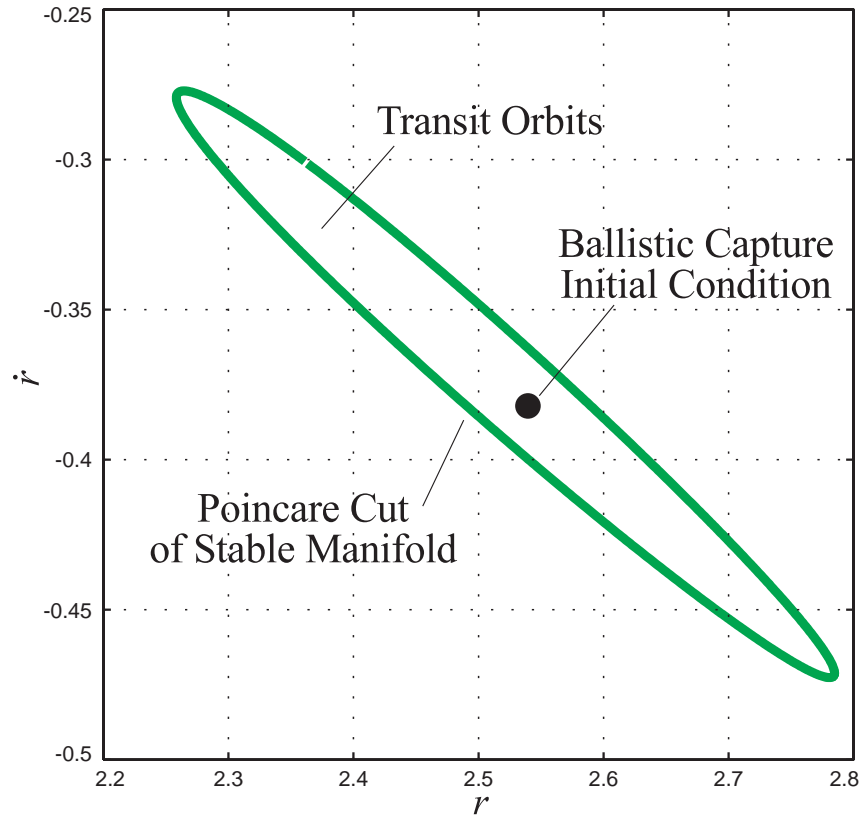
■ Schematic of “Shoot the Moon” Trajectory,

- ▶ 2 portions of the trajectory in **Sun-Earth rotating frame**:
 - Sun-Earth libration point portion.
 - Lunar ballistic capture portion.



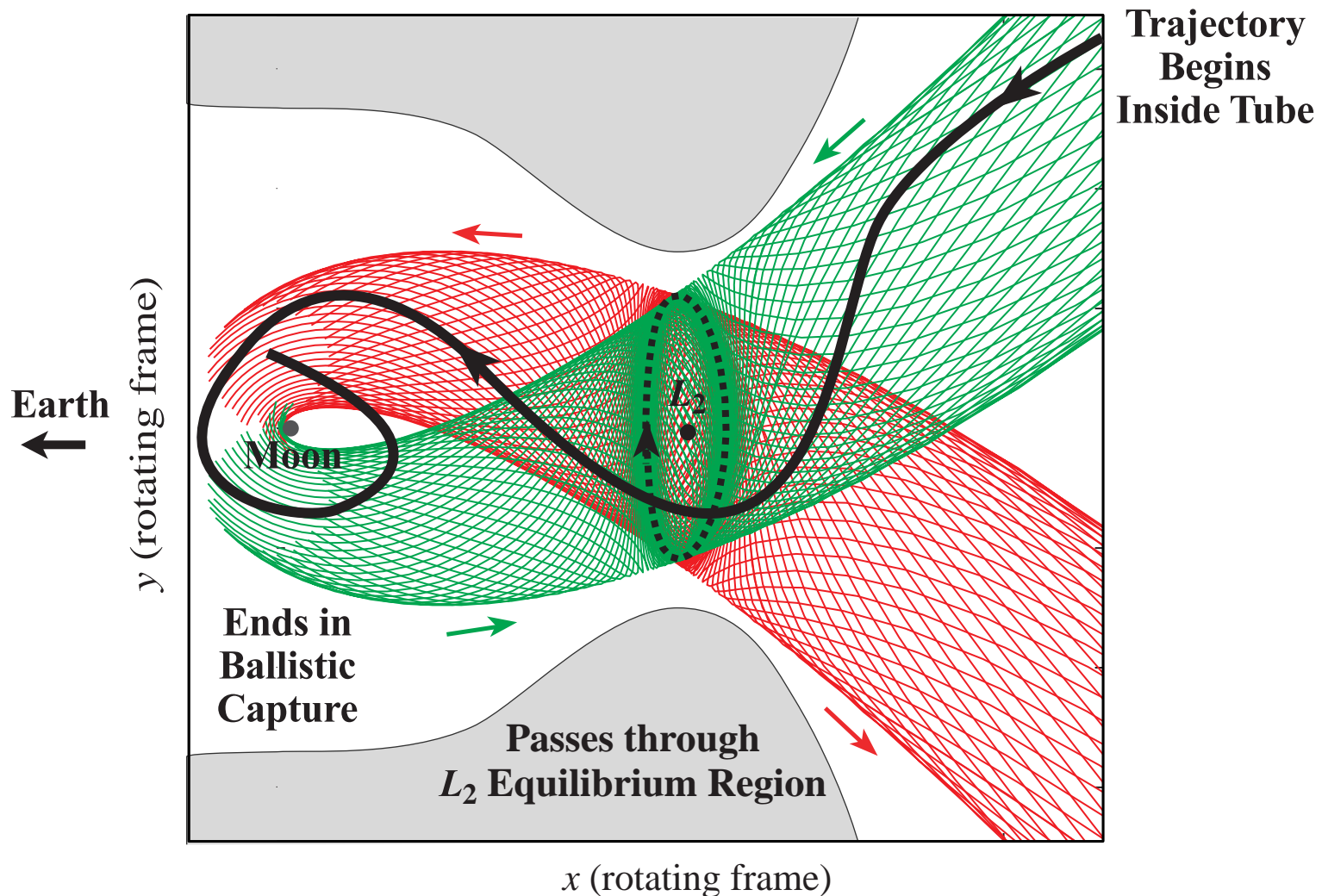
■ Lunar Ballistic Capture Portion

- ▶ **Stable manifold tube** provides temporary capture mechanism by second primary.
- ▶ **Stable manifold tube** of periodic orbit around L_2 guides spacecraft towards **ballistic capture** by Moon.



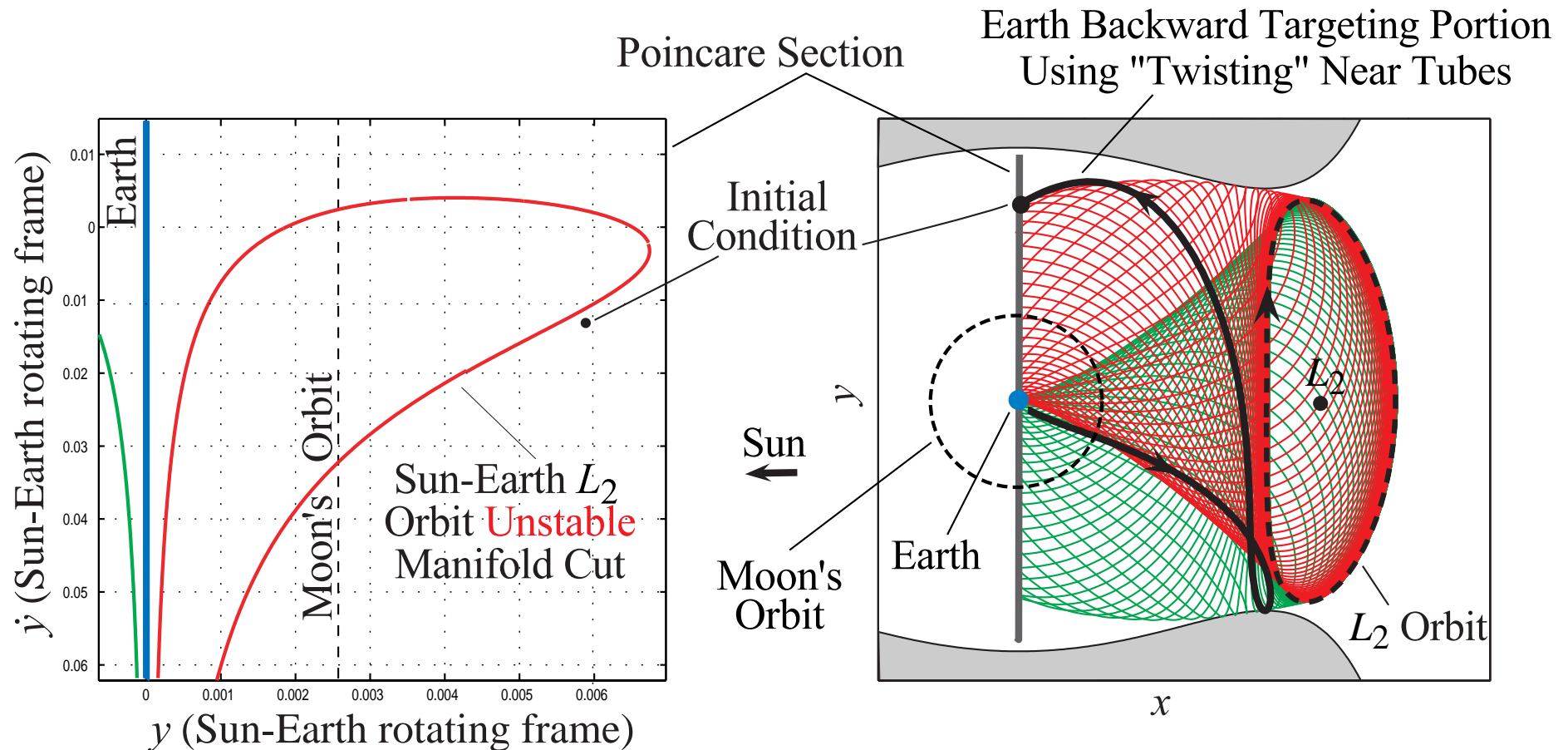
■ Lunar Ballistic Capture Portion

- ▶ By saving (on-board) fuel for lunar **ballistic capture** portion, this design uses **less** fuel than Earth-to-Moon **Hohmann transfer**.



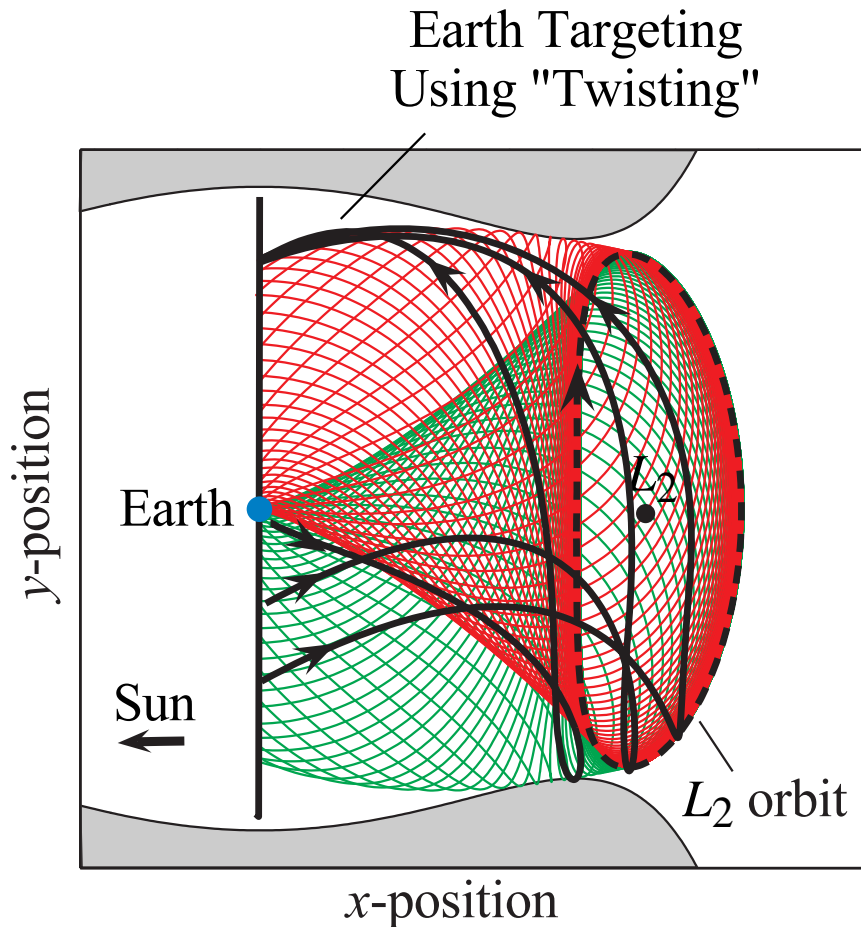
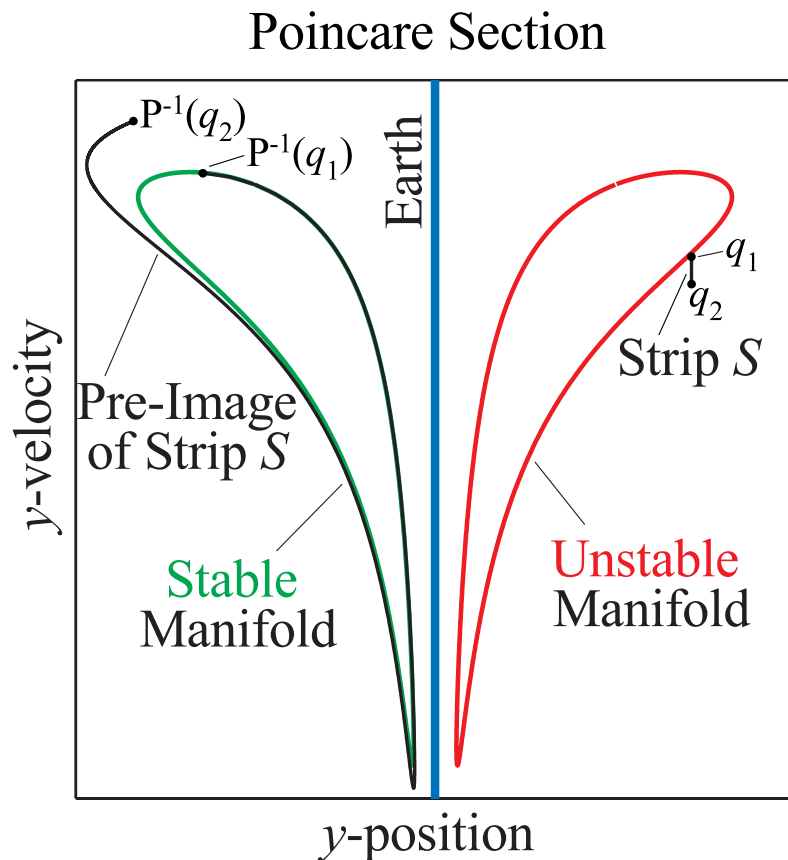
■ Sun-Earth Libration Point Portion

- ▶ Pick **initial condition** outside **Poincaré cut**, backward integrate to produce a trajectory:
 - hugs **unstable** manifold back to L_2 region with a **twist**,
 - hugs **stable** manifold back towards Earth.



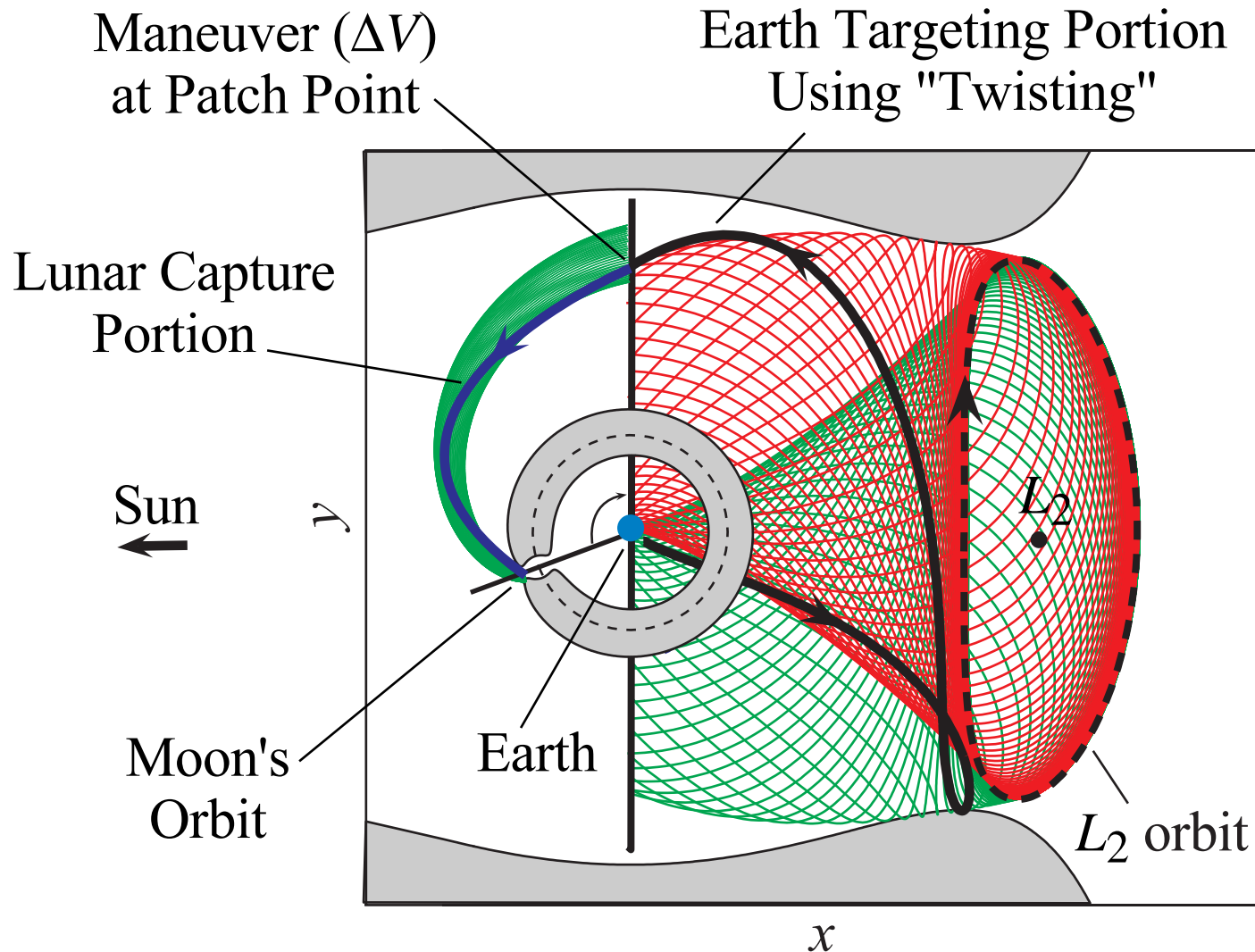
■ Sun-Earth Libration Point Portion

- ▶ Amount of **twist** depends sensitively on **distance** from manifold, can change dramatically with small ΔV .
- ▶ With small ΔV , can target back to (200 km) Earth **parking orbit**.



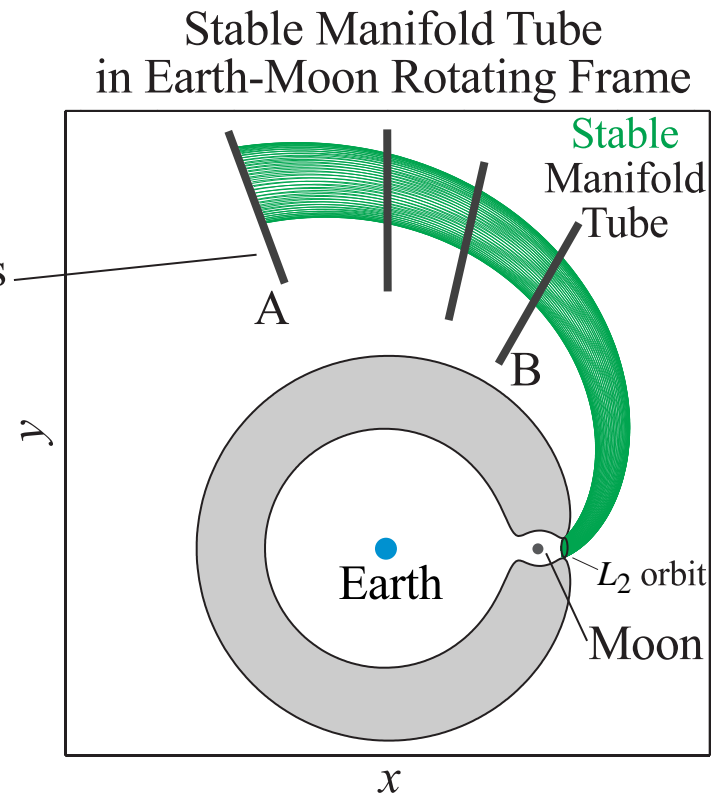
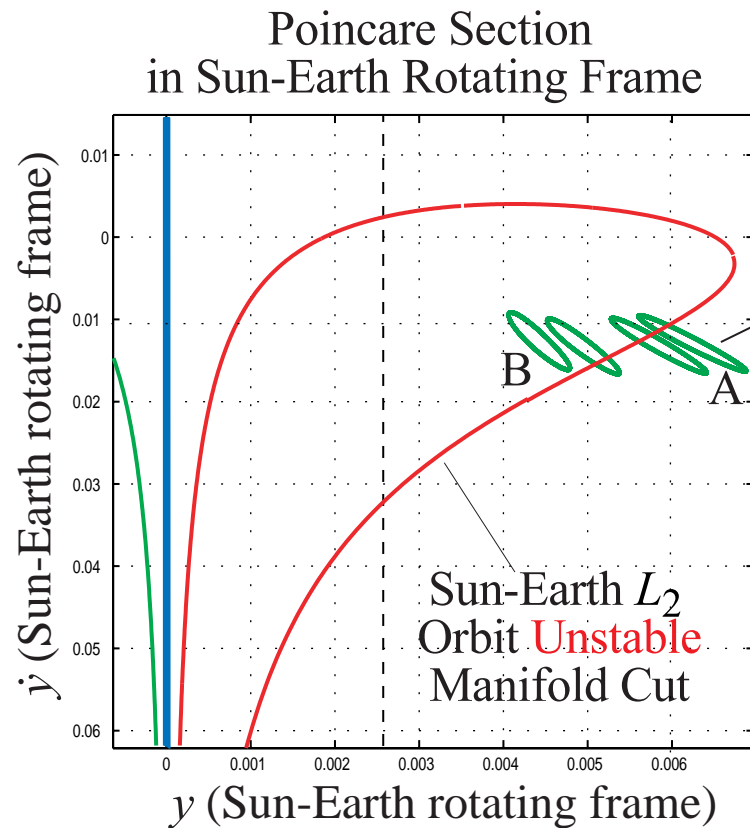
■ Connecting Two Portions

- Recall: Sun-Earth-Moon-SC 4-body system as **2 coupled 3-body systems**.



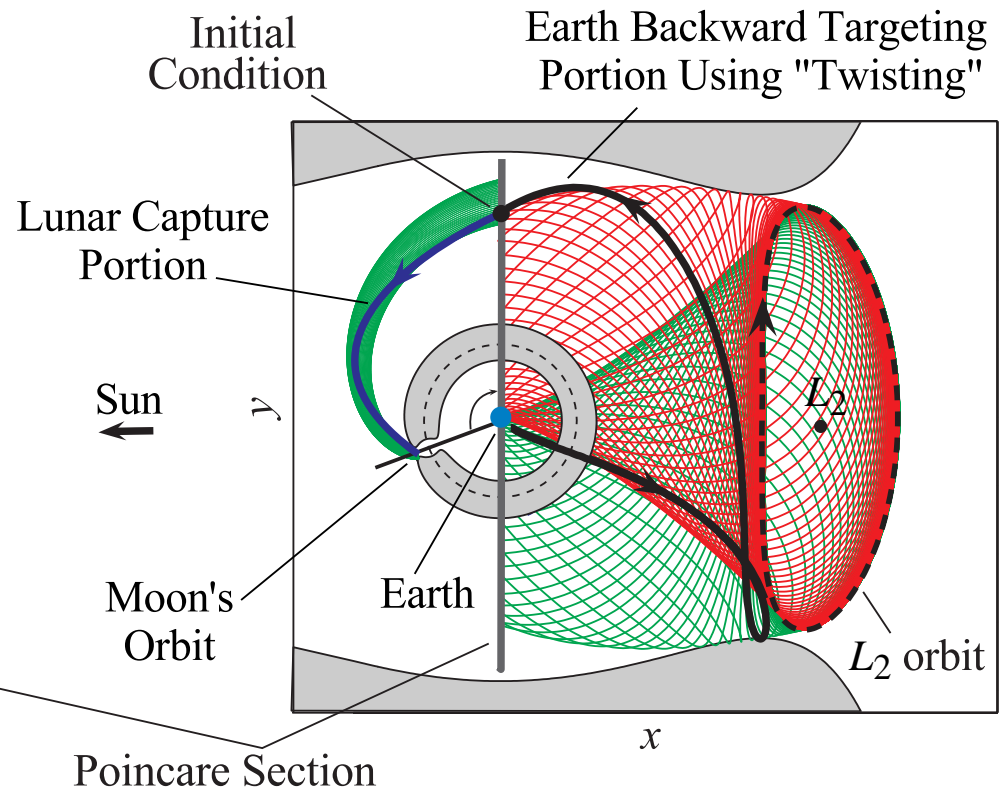
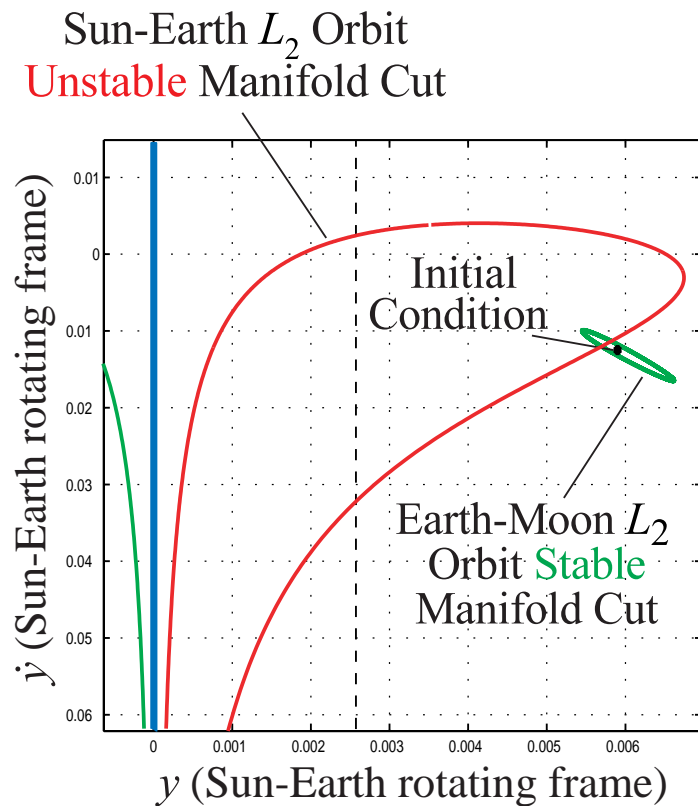
■ Connecting Two Portions

- Vary phase of Moon until **Earth-Moon L_2 manifold cut** intersects **Sun-Earth L_2 manifold curve**.



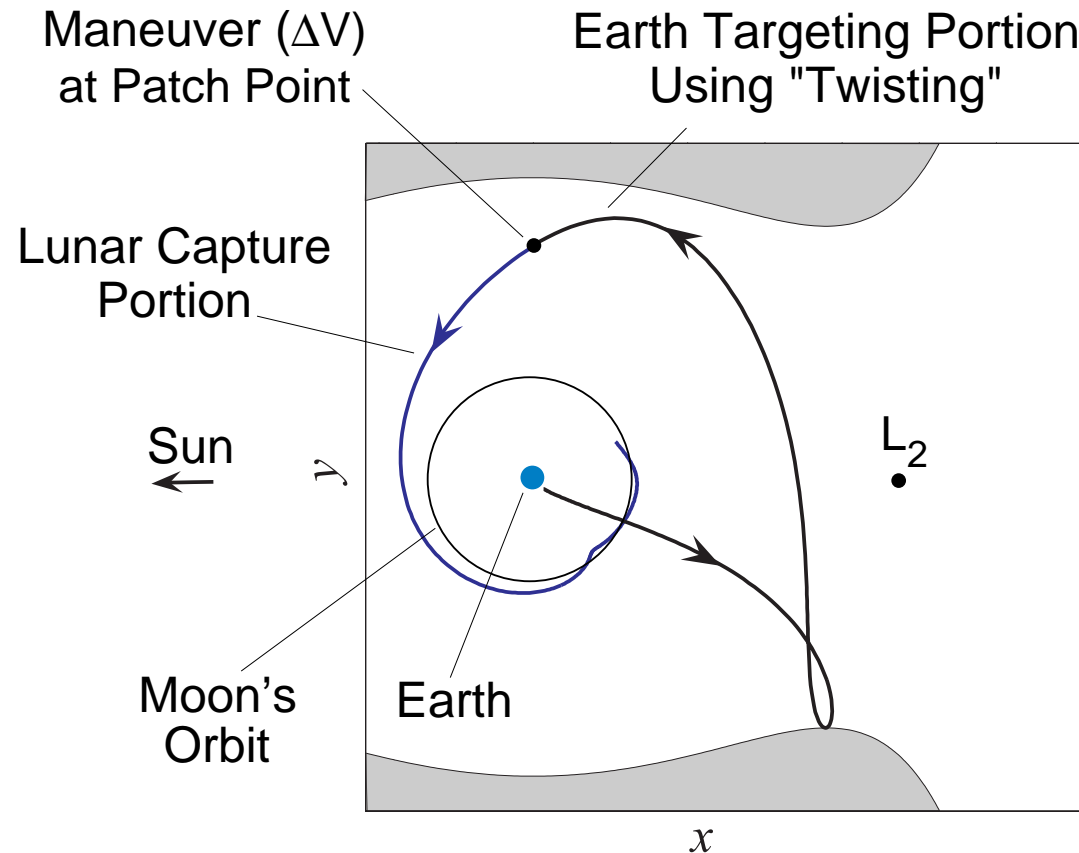
■ Connecting Two Portions

- ▶ Pick **initial condition** in region
 - in interior of **green curve**
 - but in exterior of **red curves**.



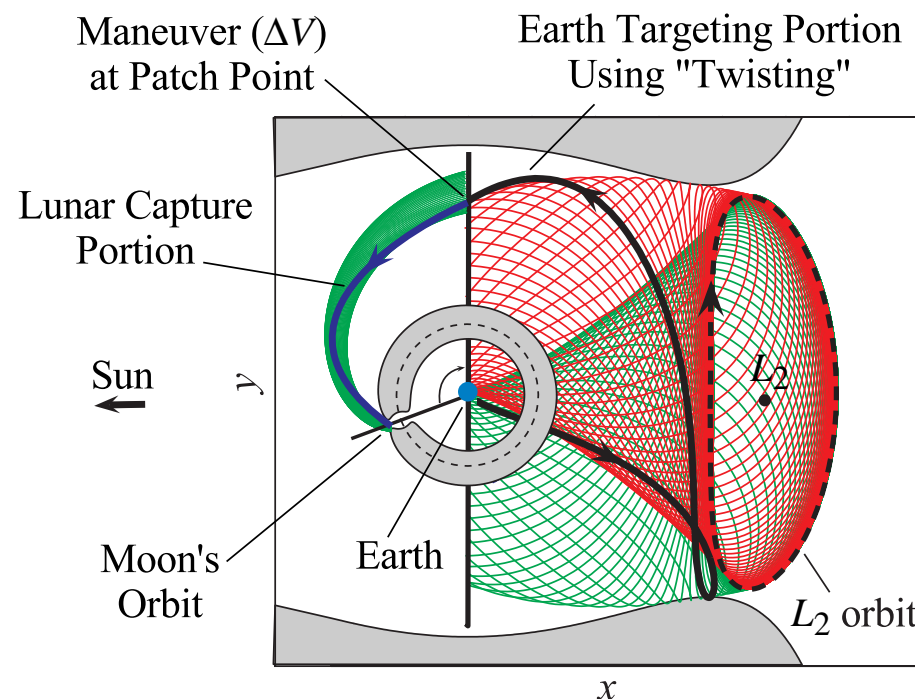
■ Connecting Two Portions

- ▶ With slight modification (a 34 m/s ΔV at patch point), this produces a solution in **bicircular 4-body problem**.
- ▶ Since capture at Moon is **natural** (zero ΔV), amount of on-board fuel needed is lowered (by about 20%).



■ Arguments for Coupled 3-Body Model

- ▶ Outside **Moon's sphere of influence** (20,000 km),
 - can neglect **Moon's perturbation** on S-E-SC 3-body system,
 - can use **Sun-Earth invariant manifold structure**.
- ▶ Midcourse ΔV is performed as SC is entering **Earth's sphere of influence** (900,000 km),
 - can neglect **Sun's perturbation** on E-M-SC 3-body system,
 - can use **Earth-Moon manifold structure** for capture.



■ Future Work

- ▶ Using **differential correction**,
can utilize this trajectory as initial guess
 - to find **3-dimensional** “Shoot the Moon” trajectory,
 - with full solar system model.
- ▶ **Optimize trajectory**
 - by applying optimal control (e.g., COOPT),
 - with continuous (low) thrust.
- ▶ Develop procedure for **coupling multiple 3-body systems**,
which will aid
 - in design of innovative **space missions**
 - in understanding
subtle non-Keplerian **transport** throughout solar system.

■ References and Other Informations

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Chaos, vol. 10, (2000) pp. 427-469.
 - <http://www.cds.caltech.edu/~marsden/>
 - Clip on “current issue” of
<http://ojps.aip.org/chaos/>
- ▶ Koon, W.S., M.W. Lo, J.E. Marsden and S.D. Ross
“Shoot the Moon.”
- ▶ Email: koon@cds.caltech.edu