

Overview of CDS 140B: Introduction to Dynamics

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■ Textbook, Other Book and Papers

▶ **Textbook**

- Stephen Wiggins [2003]:
Introduction to Applied Nonlinear Dynamical Systems and Chaos, Second Edition.

▶ **Other Books and Paper**

- Ferdinand Verhulst:
Nonlinear Differential Equations and Dynamical Systems.
- Lawrence Perko:
Differential Equations and Dynamical Systems.
- Koon, W.S., M.W. Lo, J.E. Marsden and S.D. Ross [2000]:
Heteroclinic Connections between Periodic Orbits and Resonance Transitions in Celestial Mechanics, *Chaos*, 10, 427-469.

■ Goals and Description of CDS 140B

- ▶ A continuation of CDS 140A.
80% covers basic tools from nonlinear dynamics
 - perturbation theory and method of averaging;
 - bifurcation theory;
 - global bifurcation and chaos;
 - Hamiltonian systems.
- ▶ Besides standard examples
(van der Pol, Duffing, and Lorenz equations),
20% applies dynamical system tools in space mission design
 - periodic and quasi-periodic orbits,
 - invariant manifolds,
 - homoclinic and heteroclinic connections,
 - symbolic dynamics and chaos.
- ▶ Examples: Genesis Discovery Mission and
Low Energy Tour of Multiple Moons of Jupiter

■ Outline of Presentation

▶ **Main Theme**

- how to use dynamical systems theory of 3-body problem in space mission design.

▶ **Background and Motivation:**

- NASA's Genesis Discovery Mission.
- Jupiter Comets.

▶ **Planar Circular Restricted 3-Body Problem.**

▶ **Major Results on Tube Dynamics.**

▶ **Lobe Dynamics & Navigating in Phase Space.**

- A Low Energy Tour of Jupiter's Moons.

▶ **Conclusion and Ongoing Work.**

- Two Full Body Problem and Astroid Pairs.
- Looking into Chemical Reaction Dynamics.

■ Acknowledgement

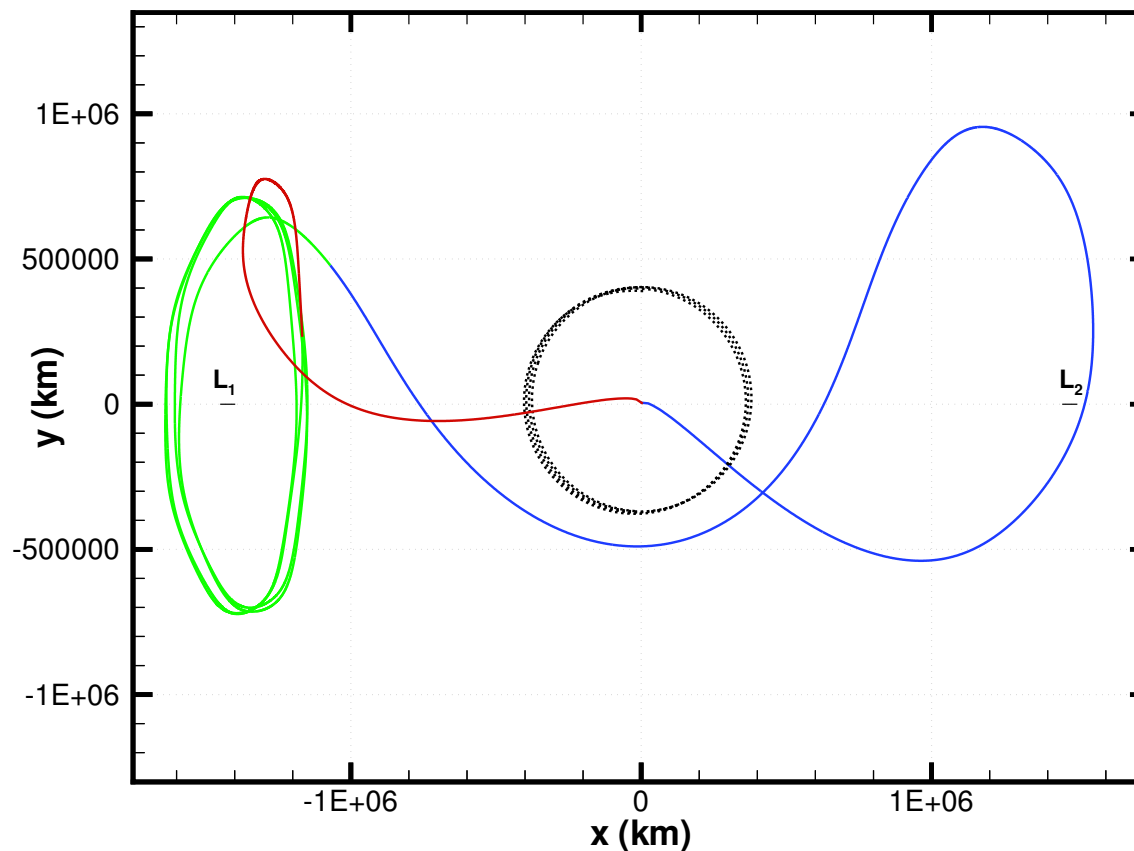
- ▶ H. Poincaré, J. Moser
- ▶ C. Conley, R. McGehee, D. Appleyard
- ▶ C. Simó, J. Llibre, R. Martinez
- ▶ G. Gómez, J. Masdemont
- ▶ B. Farquhar, D. Dunham
- ▶ E. Belbruno, B. Marsden, J. Miller
- ▶ K. Howell, B. Barden, R. Wilson
- ▶ S. Wiggins, L. Wiesenfeld, C. Jaffé, T. Uzer
- ▶ V. Rom-Kedar, F. Lekien, L. Vela-Arevalo
- ▶ M. Dellnitz, O. Junge, and Paderborn group

■ Genesis Discovery Mission

▶ Genesis spacecraft

- is collecting solar wind samples from a L_1 **halo orbit**,
- will **return** them to Earth later this year for analysis.

▶ **Halo orbit**, **transfer**/**return** trajectories in rotating frame.

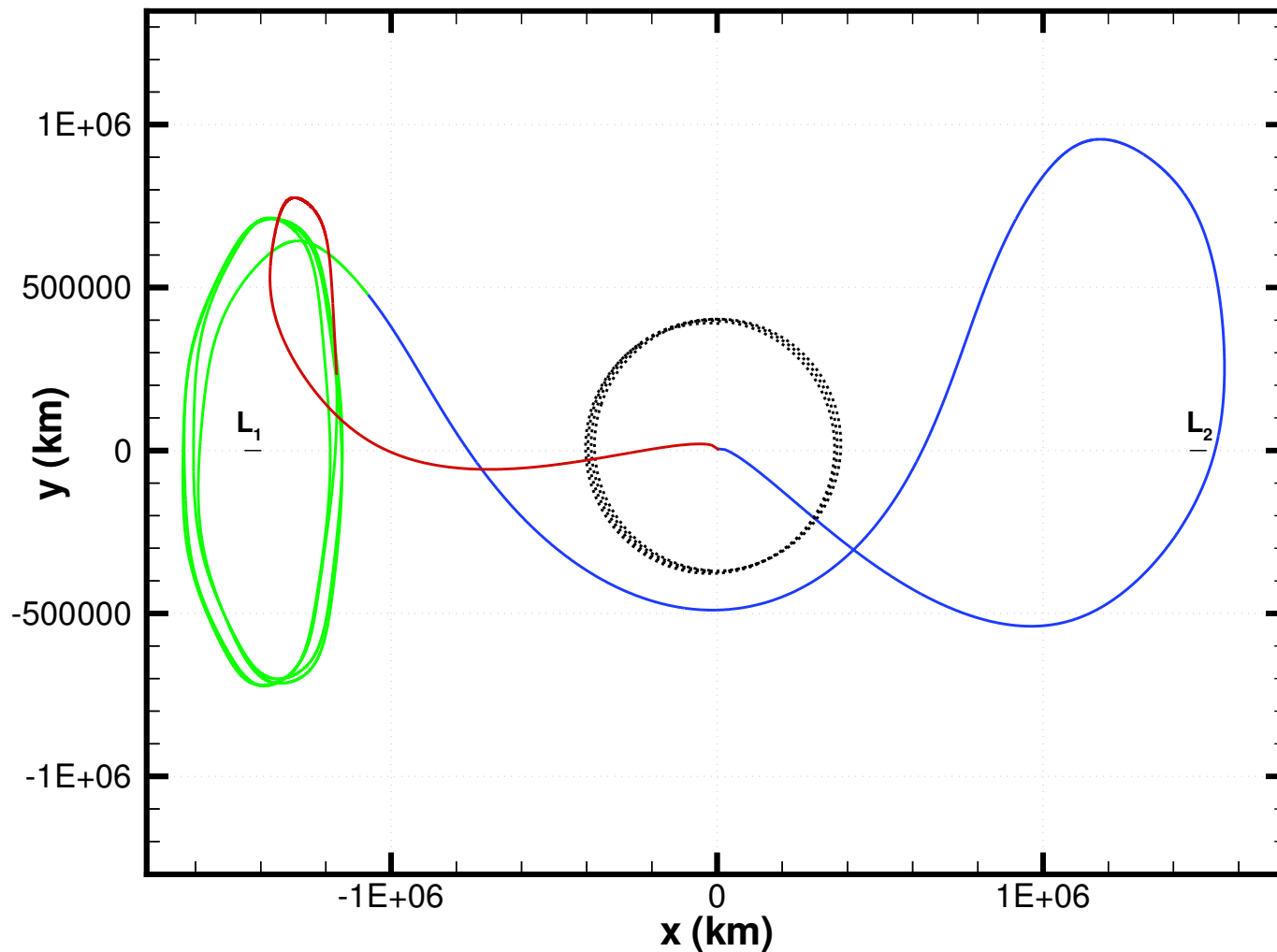


■ Genesis Discovery Mission

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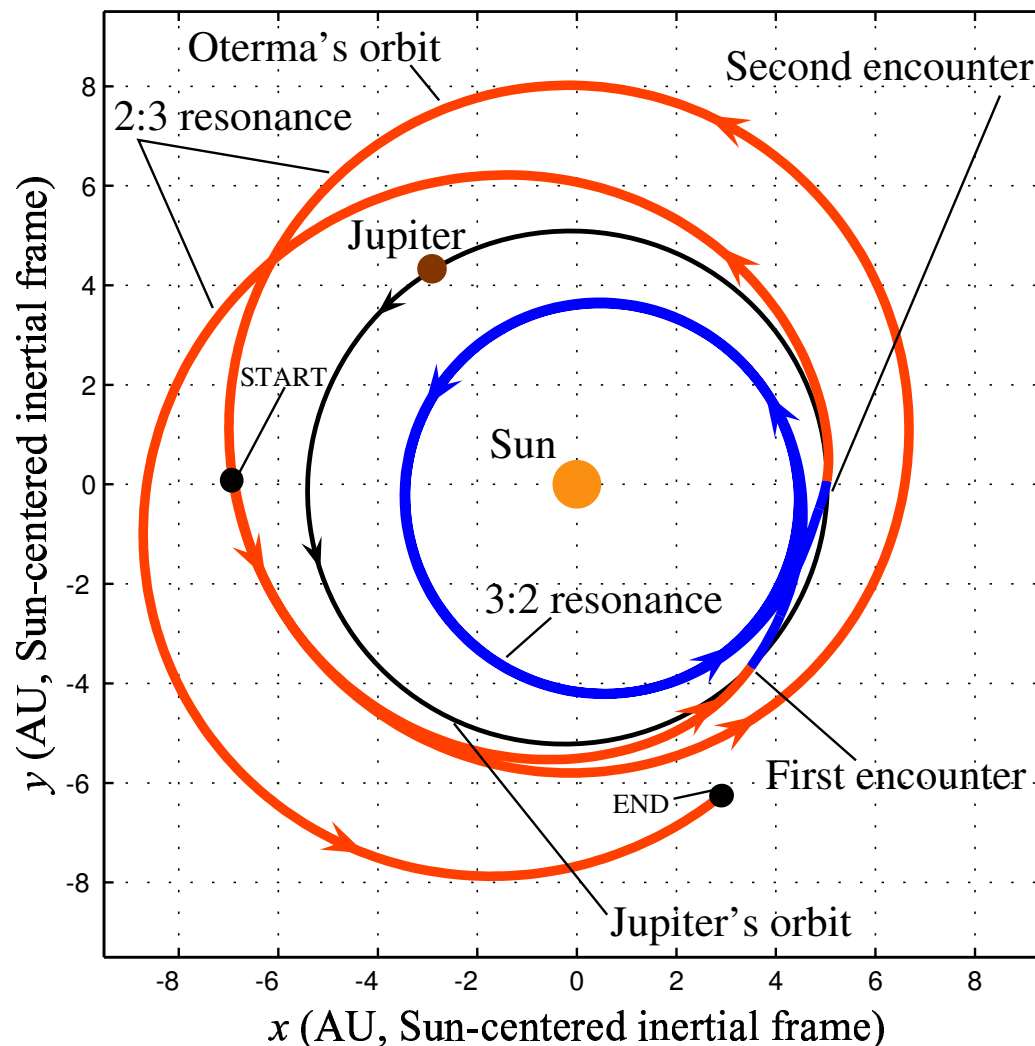
- ▶ Follows natural dynamics, little propulsion after launch.
- ▶ **Return-to-Earth portion** utilizes heteroclinic dynamics.



■ Jupiter Comets

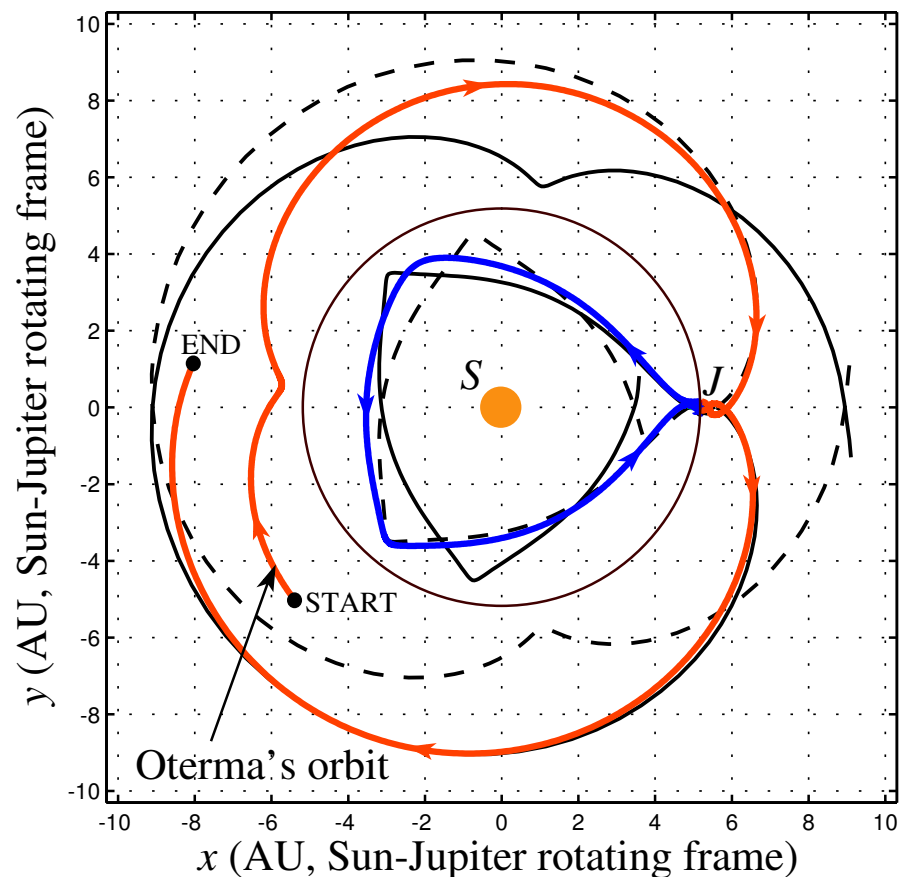
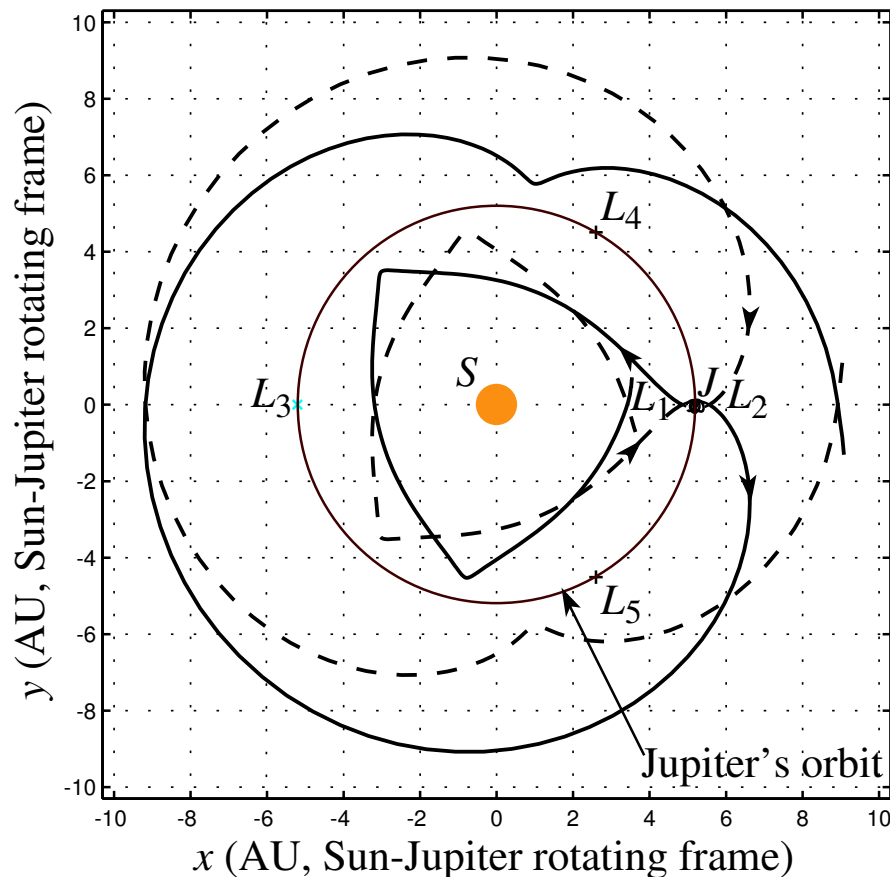
■ Jupiter Comets

- ▶ Rapid transition from **outside** to **inside** Jupiter's orbit.
- ▶ Captured temporarily by Jupiter during transition.
- ▶ **Exterior** (2:3 resonance). **Interior** (3:2 resonance).



■ Jupiter Comets

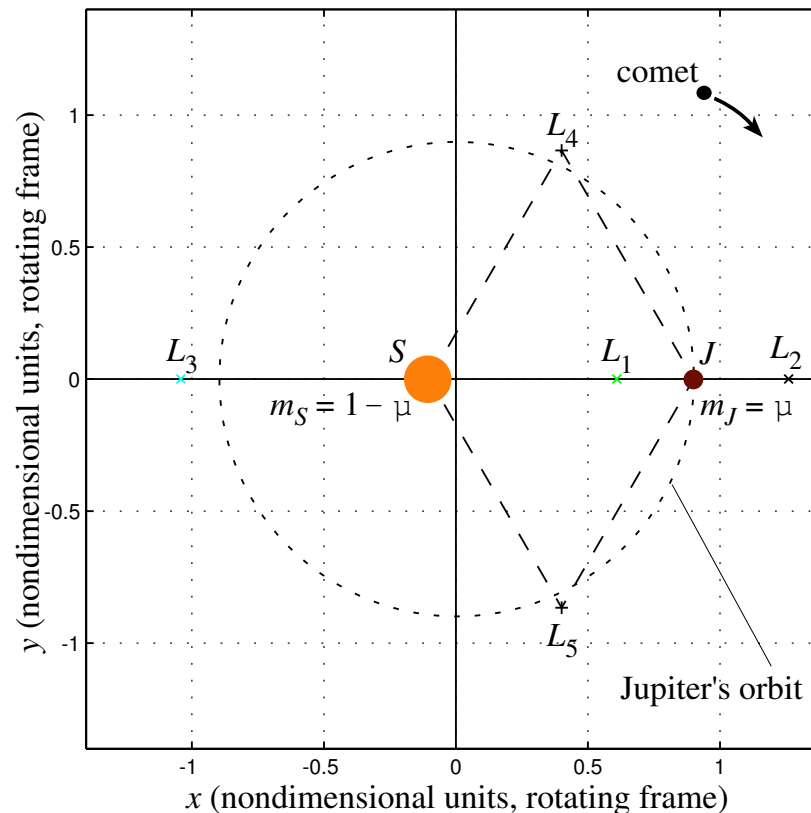
- ▶ Belbruno and B. Marsden [1997]
- ▶ Lo and Ross [1997]
 - Comet in **rotating frame** follows **invariant manifolds**.
- ▶ Jupiter comets make **resonance transition** near L_1 and L_2 .



■ Planar Circular Restricted 3-Body Problem

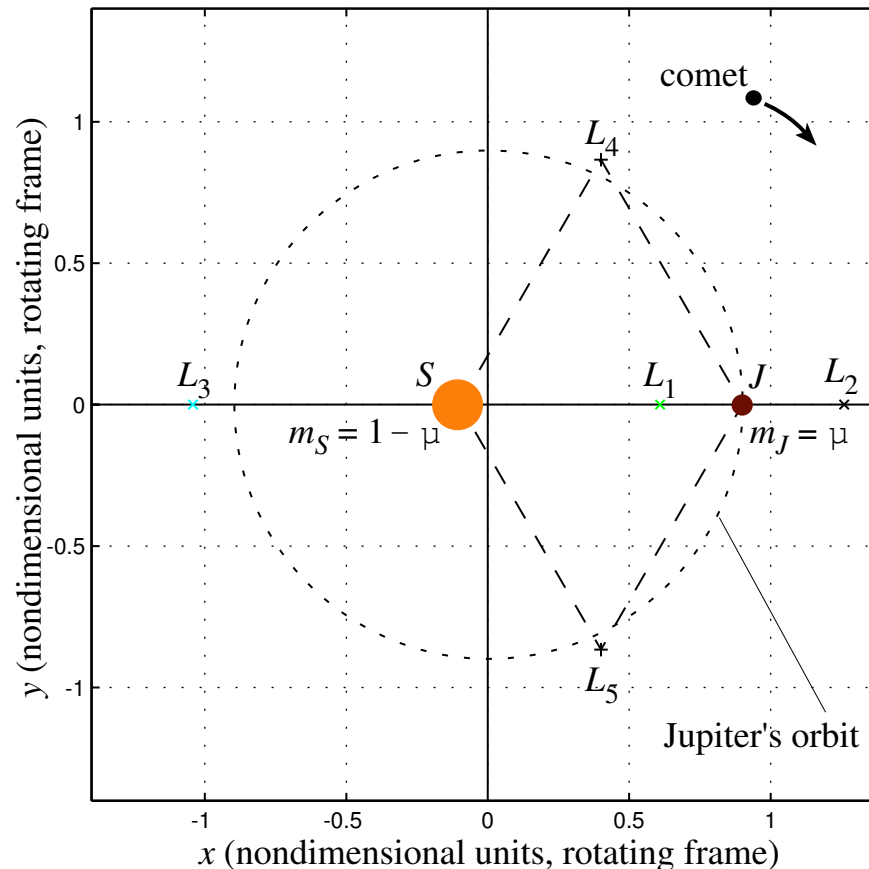
► **PCR3BP** is a good starting model:

- Comets mostly **heliocentric**, but their perturbation dominated by **Jupiter's gravitation**.
- Their motion nearly in Jupiter's **orbital plane**.
- Jupiter's small **eccentricity** plays little role during transition.



■ Planar Circular Restricted 3-Body Problem

- ▶ 2 main bodies: **Sun** and **Jupiter**.
 - Total mass normalized to 1: $m_J = \mu$, $m_S = 1 - \mu$.
 - Rotate about center of mass, angular velocity normalized to 1.
- ▶ Choose a **rotating** coordinate system with $(0, 0)$ at center of mass, **S** and **J** fixed at $(-\mu, 0)$ and $(1 - \mu, 0)$.



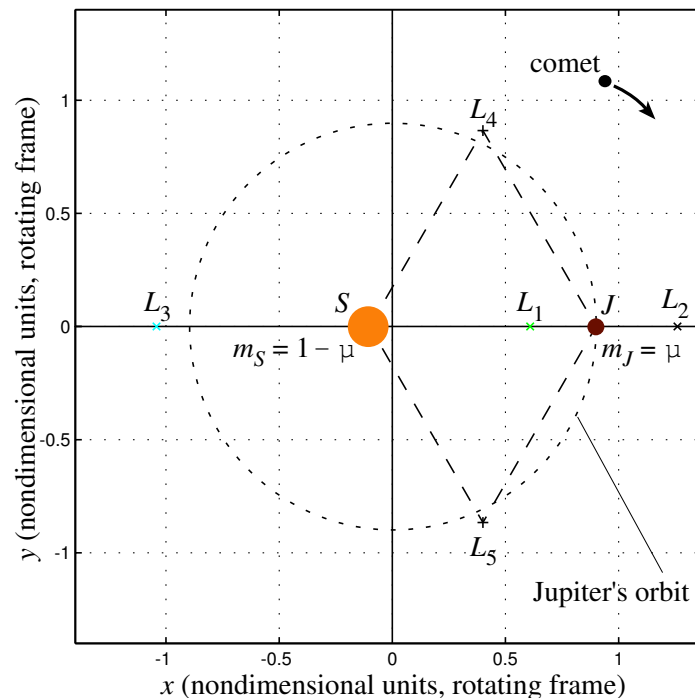
■ Equilibrium Points (PCR3BP)

► Comet's equations of motion are

$$\ddot{x} - 2\dot{y} = -\frac{\partial U}{\partial x} \quad \ddot{y} + 2\dot{x} = -\frac{\partial U}{\partial y} \quad U = -\frac{x^2 + y^2}{2} - \frac{1 - \mu}{r_S} - \frac{\mu}{r_J}$$

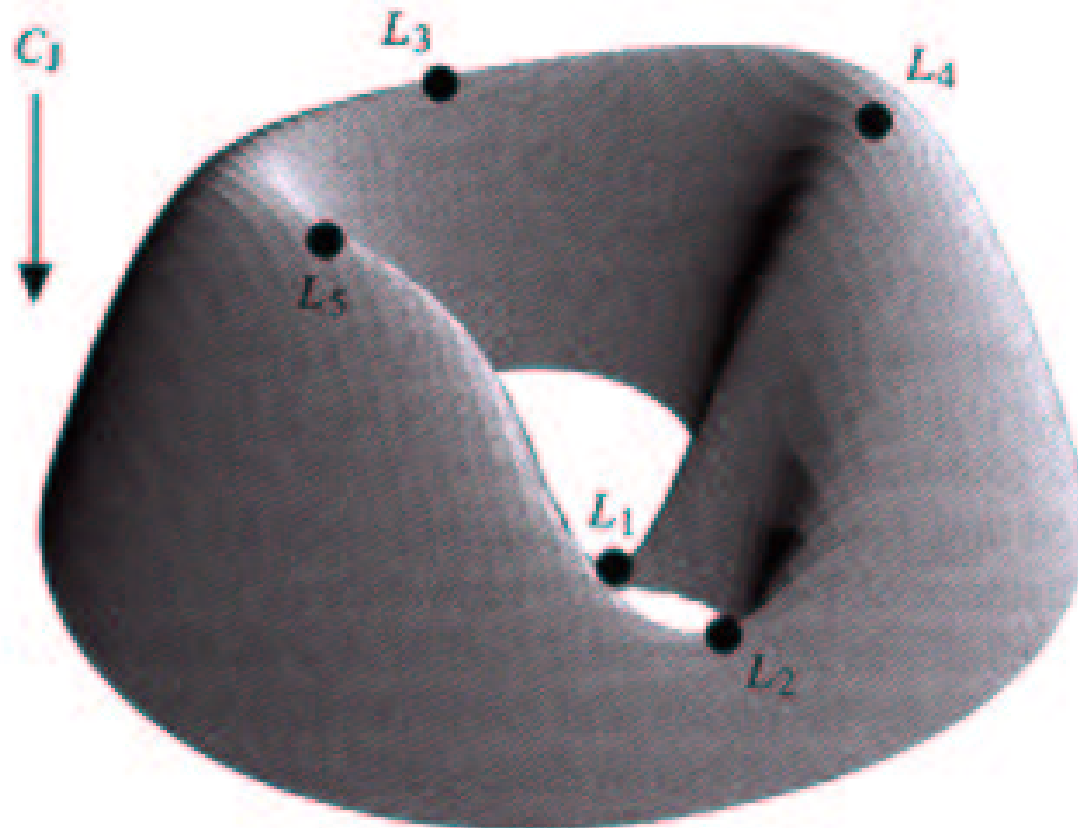
► Five equilibrium points:

- 3 **unstable** equilibrium points on S-J line, L_1, L_2, L_3 .
- 2 equilateral equilibrium points, L_4, L_5 .



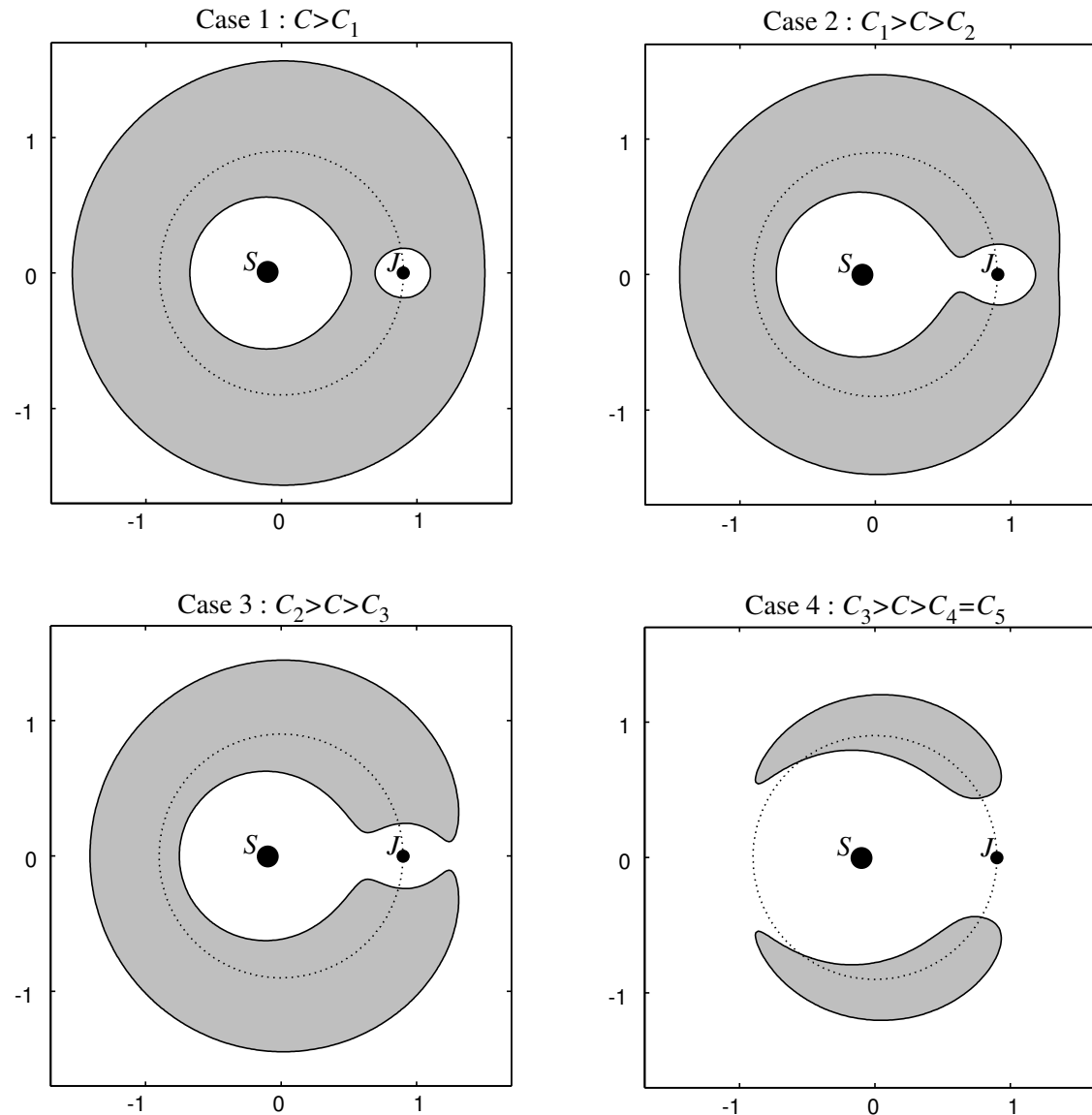
■ Hill's Realm (PCR3BP)

- ▶ **Energy integral:** $E(x, y, \dot{x}, \dot{y}) = (\dot{x}^2 + \dot{y}^2)/2 + U(x, y)$.
- ▶ E can be used to determine (**Hill's**) **realm** in position space where comet is energetically permitted to move.
- ▶ **Effective potential:** $U(x, y) = -\frac{x^2+y^2}{2} - \frac{1-\mu}{r_s} - \frac{\mu}{r_j}$.



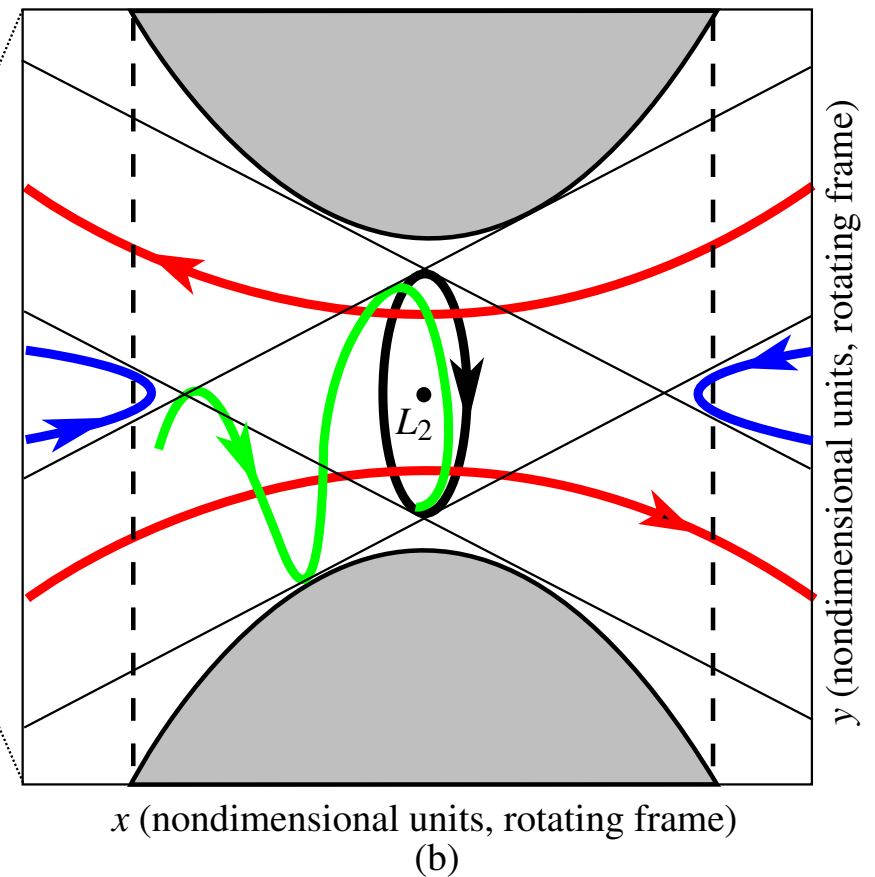
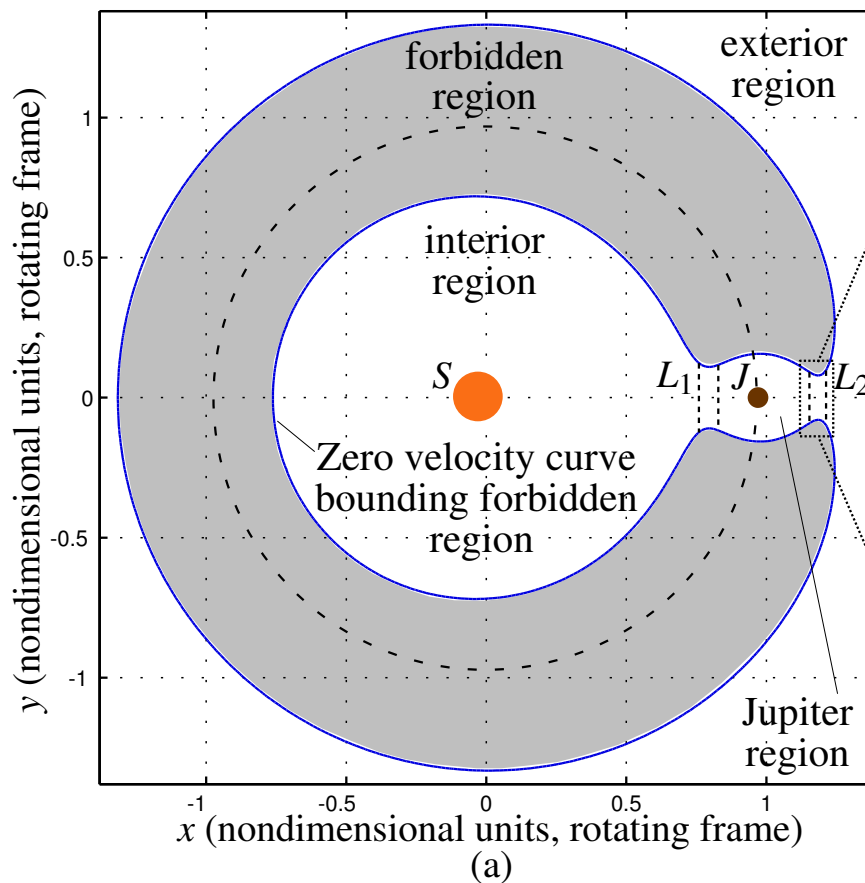
■ Hill's Realm (PCR3BP)

- ▶ To fix energy value E is to fix **height** of plot of $U(x, y)$.
Contour plots give **5** cases of Hill's realm.



■ The Flow near L_1 and L_2

- ▶ For **energy value** just above that of L_2 , **Hill's realm** contains a “**neck**” about L_1 & L_2 .
- ▶ Comet can make **transition** through these equilibrium realms.
- ▶ 4 types of orbits:
periodic, **asymptotic**, **transit** & **nontransit**.



■ The Flow near L_1 and L_2 : Linearization

- ▶ [Moser] All the qualitative results of the linearized equations carry over to the full nonlinear equations.
- ▶ Recall equations of PCR3BP:

$$\begin{aligned} \dot{x} &= v_x, & \dot{v}_x &= 2v_y + U_x, \\ \dot{y} &= v_y, & \dot{v}_y &= -2v_x + U_y. \end{aligned} \quad (1)$$

- ▶ After linearization,

$$\begin{aligned} \dot{x} &= v_x, & \dot{v}_x &= 2v_y + ax, \\ \dot{y} &= v_y, & \dot{v}_y &= -2v_x - by. \end{aligned} \quad (2)$$

- ▶ Eigenvalues have the form $\pm\lambda$ and $\pm i\nu$.
- ▶ Corresponding eigenvectors are

$$\begin{aligned} u_1 &= (1, -\sigma, \lambda, -\lambda\sigma), \\ u_2 &= (1, \sigma, -\lambda, -\lambda\sigma), \\ w_1 &= (1, -i\tau, i\nu, \nu\tau), \\ w_2 &= (1, i\tau, -i\nu, \nu\tau). \end{aligned}$$

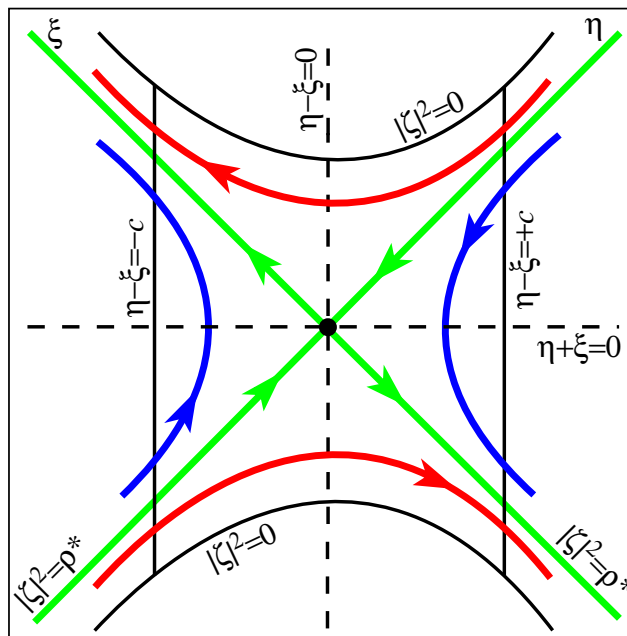
■ The Flow near L_1 and L_2 : Linearization

- ▶ After **linearization** & making **eigenvectors** as new coordinate axes, equations assume simple form

$$\dot{\xi} = \lambda\xi, \quad \dot{\eta} = -\lambda\eta, \quad \dot{\zeta}_1 = \nu\zeta_2, \quad \dot{\zeta}_2 = -\nu\zeta_1,$$

with **energy function** $E_l = \lambda\eta\xi + \frac{\nu}{2}(\zeta_1^2 + \zeta_2^2)$.

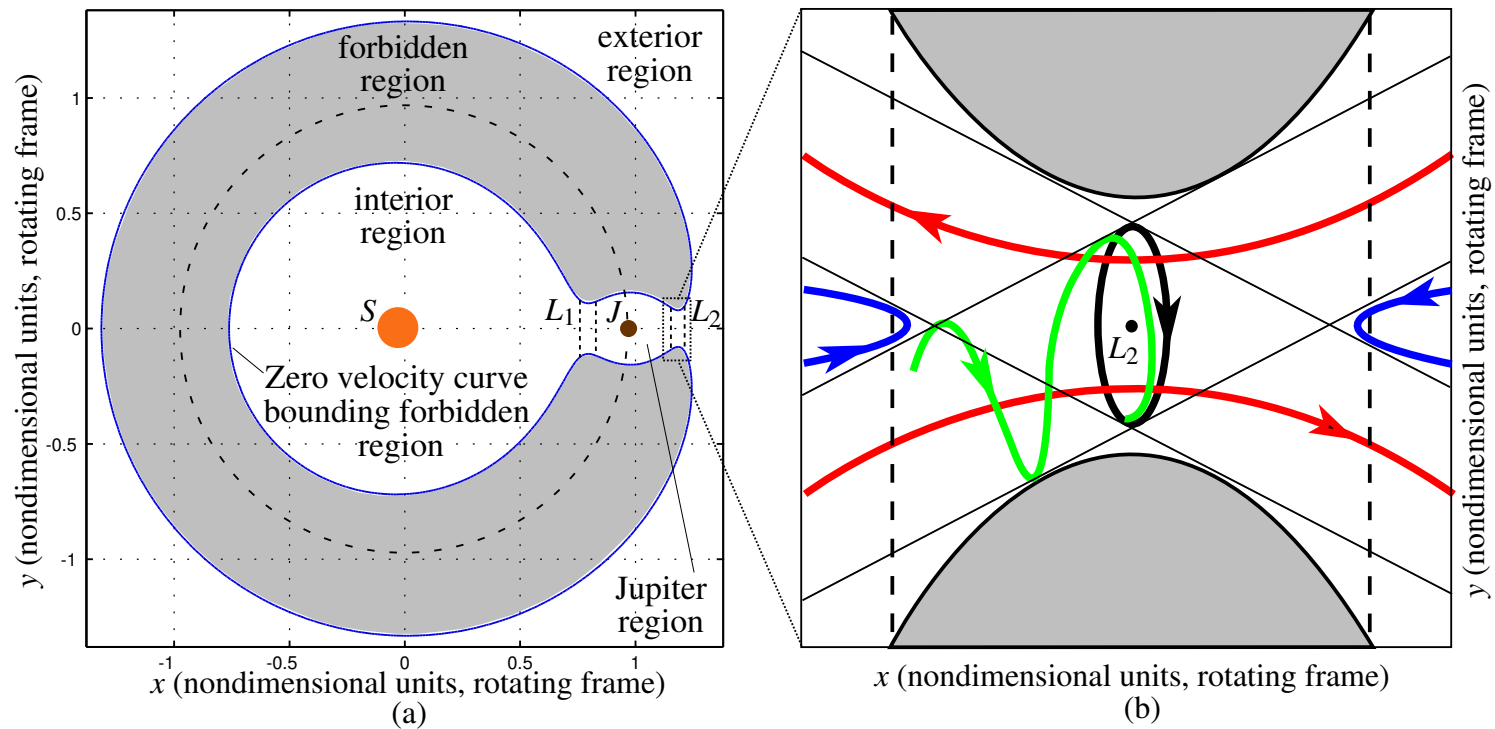
- ▶ The **flow** near L_1, L_2 have the form of **saddle** × **center**.



■ Appearance of Orbits in Position Space

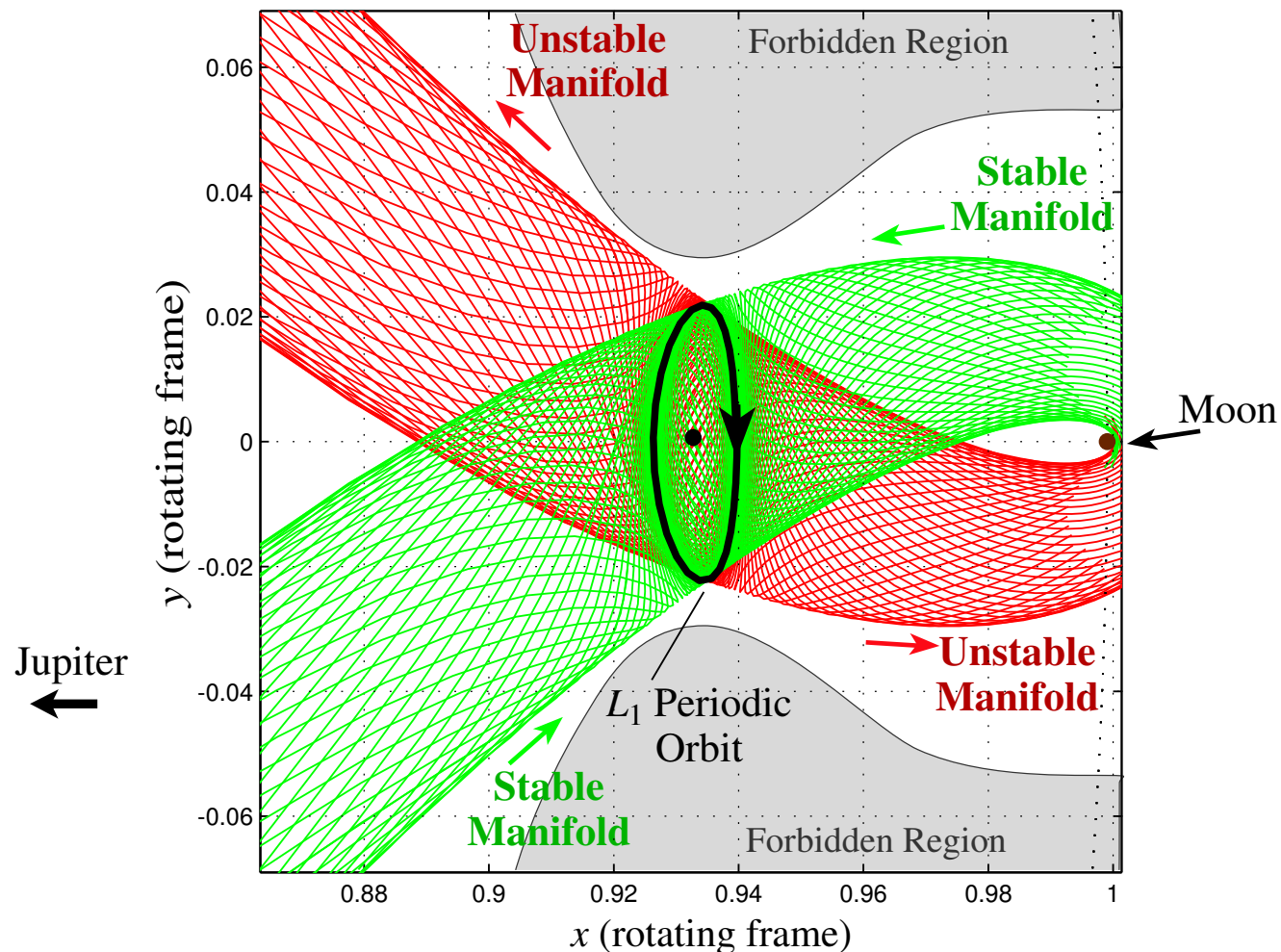
► 4 types of orbits: Shown are

- A **periodic** orbit.
- A typical **aymptotic** orbit.
- 2 **transit** orbits.
- 2 **non-transit** orbits.



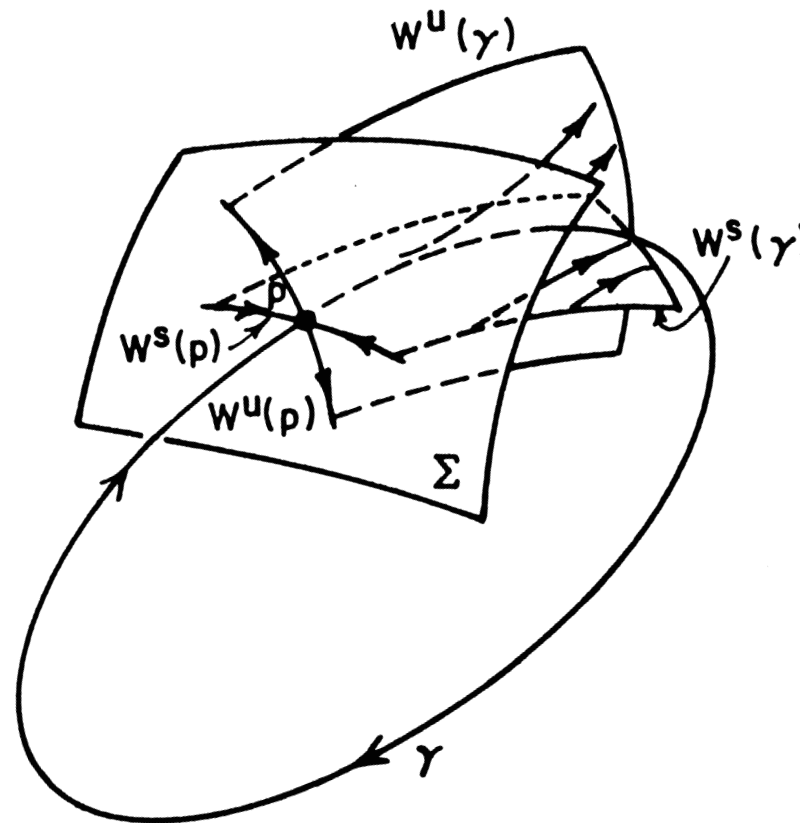
■ Invariant Manifolds as Separatrix

- ▶ **Stable** and **unstable** manifold tubes act as **separatrices** for the flow in \mathcal{R} :
 - Those inside the tubes are **transit** orbits.
 - Those outside of the tubes are **non-transit** orbits.



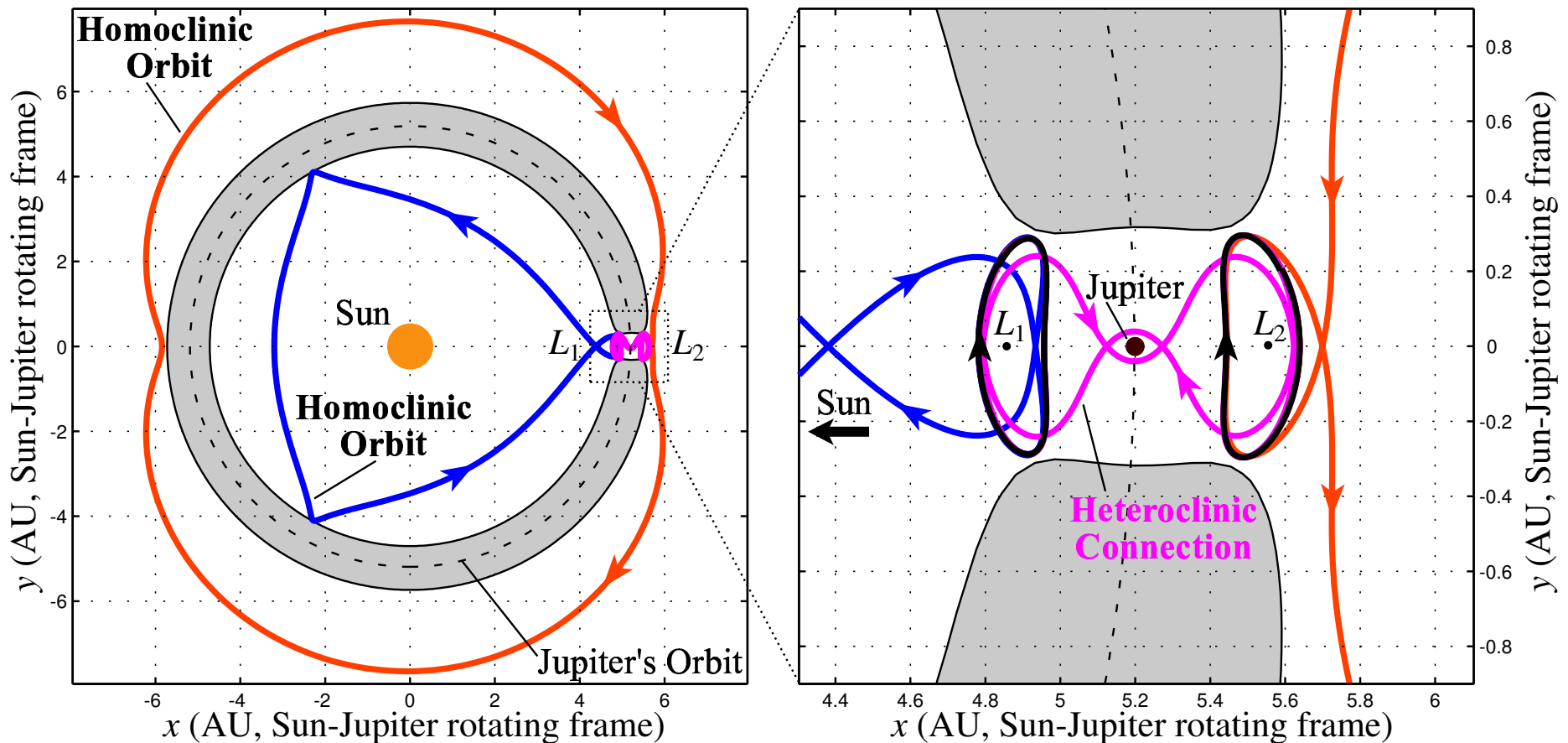
■ Computation of Periodic Orbit & Invariant Manifolds

- ▶ Periodic orbit can be computed by Lindstedt-Poincaré method.
- ▶ Invariant manifold can be computed by finding eigenvectors of monodromy matrix.



Major Result (A): Heteroclinic Connection

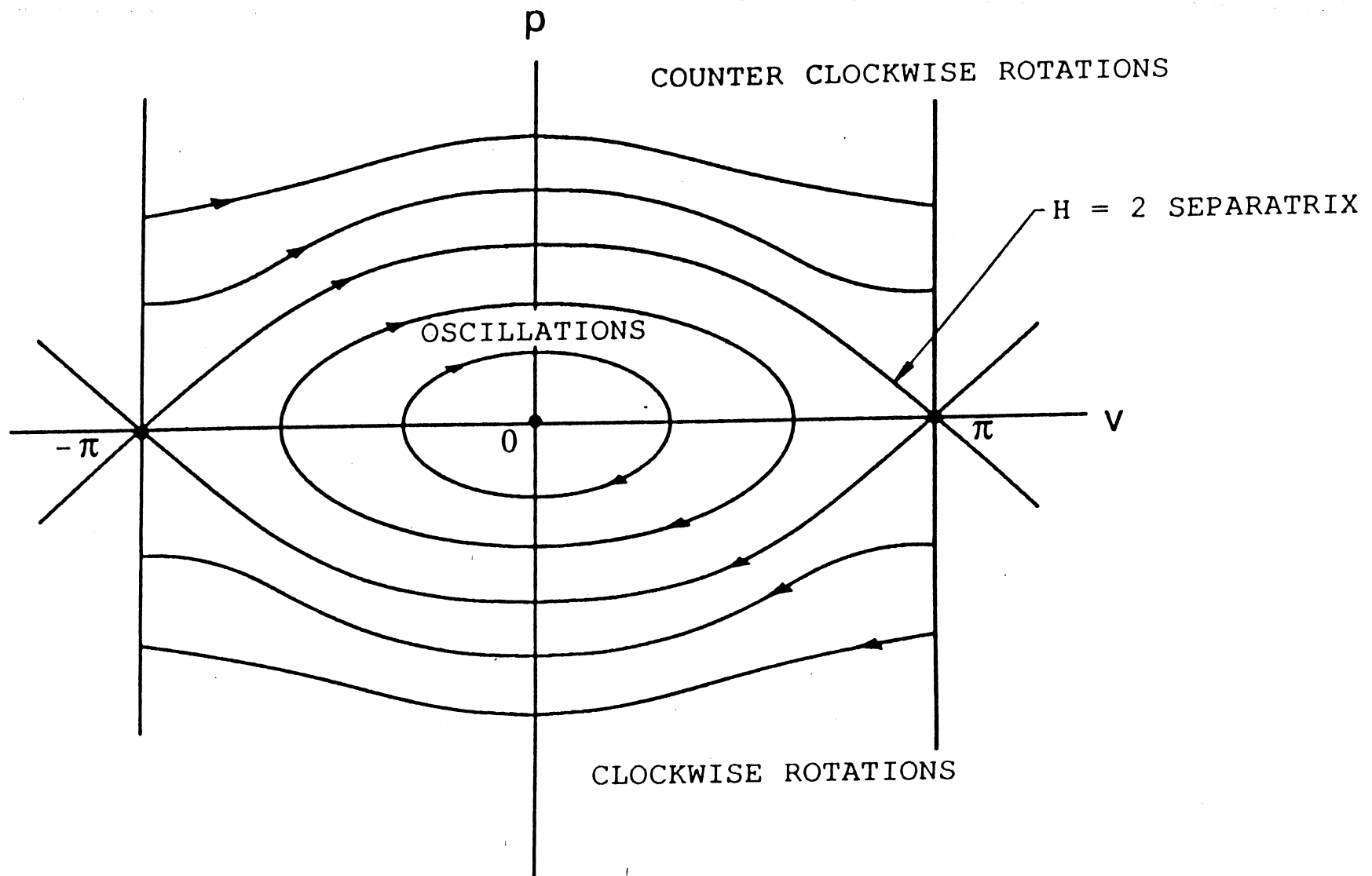
- ▶ Found **heteroclinic connection** between pair of periodic orbits.
- ▶ Found a large class of **orbits** near this (homo/heteroclinic) **chain**.
- ▶ Comet can follow these **channels** in rapid transition.



■ Major Result (A): Heteroclinic Connection

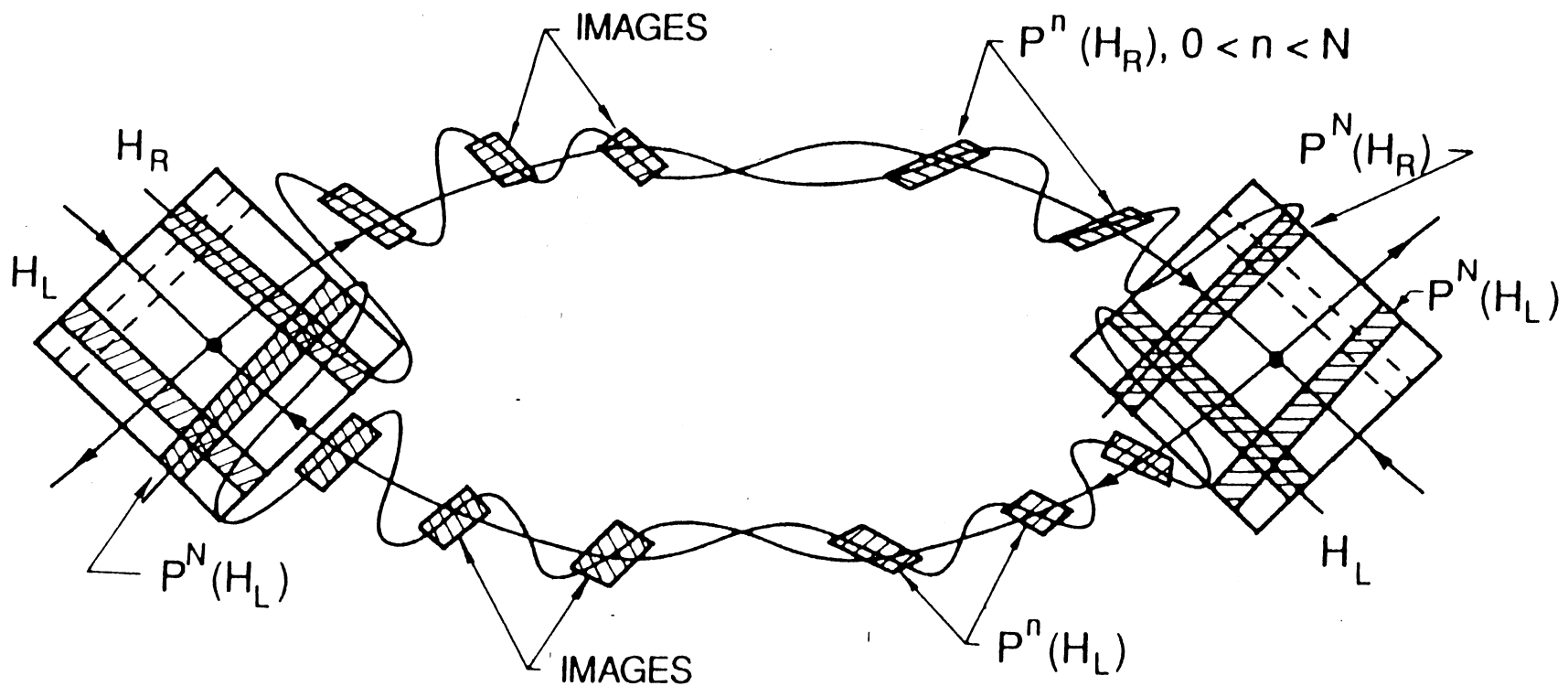
■ Review of Horseshoe Dynamics: Pendulum

- ▶ Homoclinic orbits separate librational motion from rotational motion.



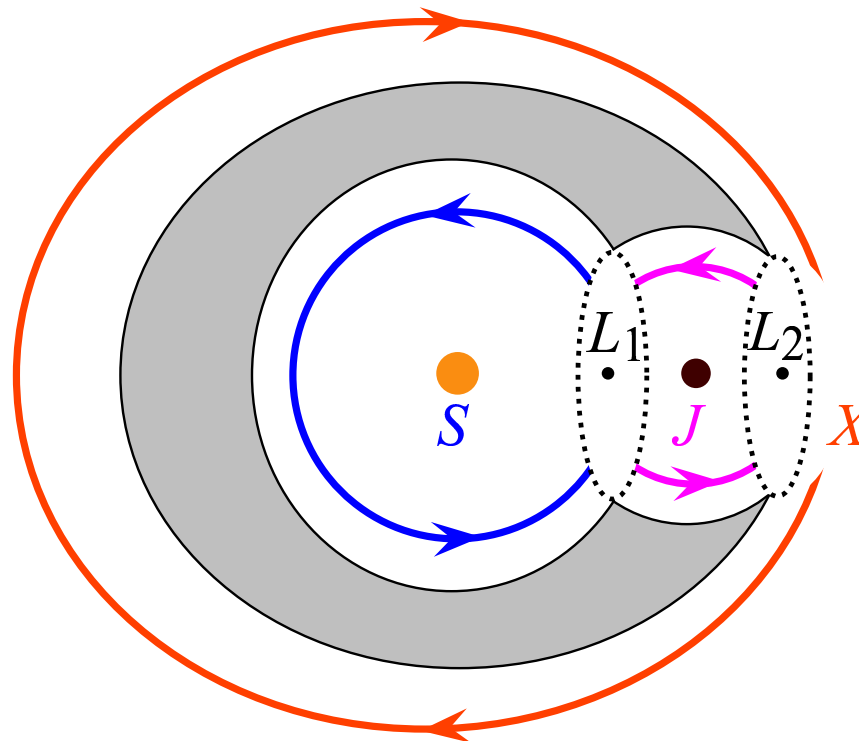
■ Review of Horseshoe Dynamics: Forced Pendulum

- ▶ Periodic forcing leads to transversal intersection and chaotic dynamics.
- ▶ For any bi-infinite sequence of itenarary $(\dots, R, L; R, R, \dots)$, there is an orbit whose whereabouts matches the sequence.



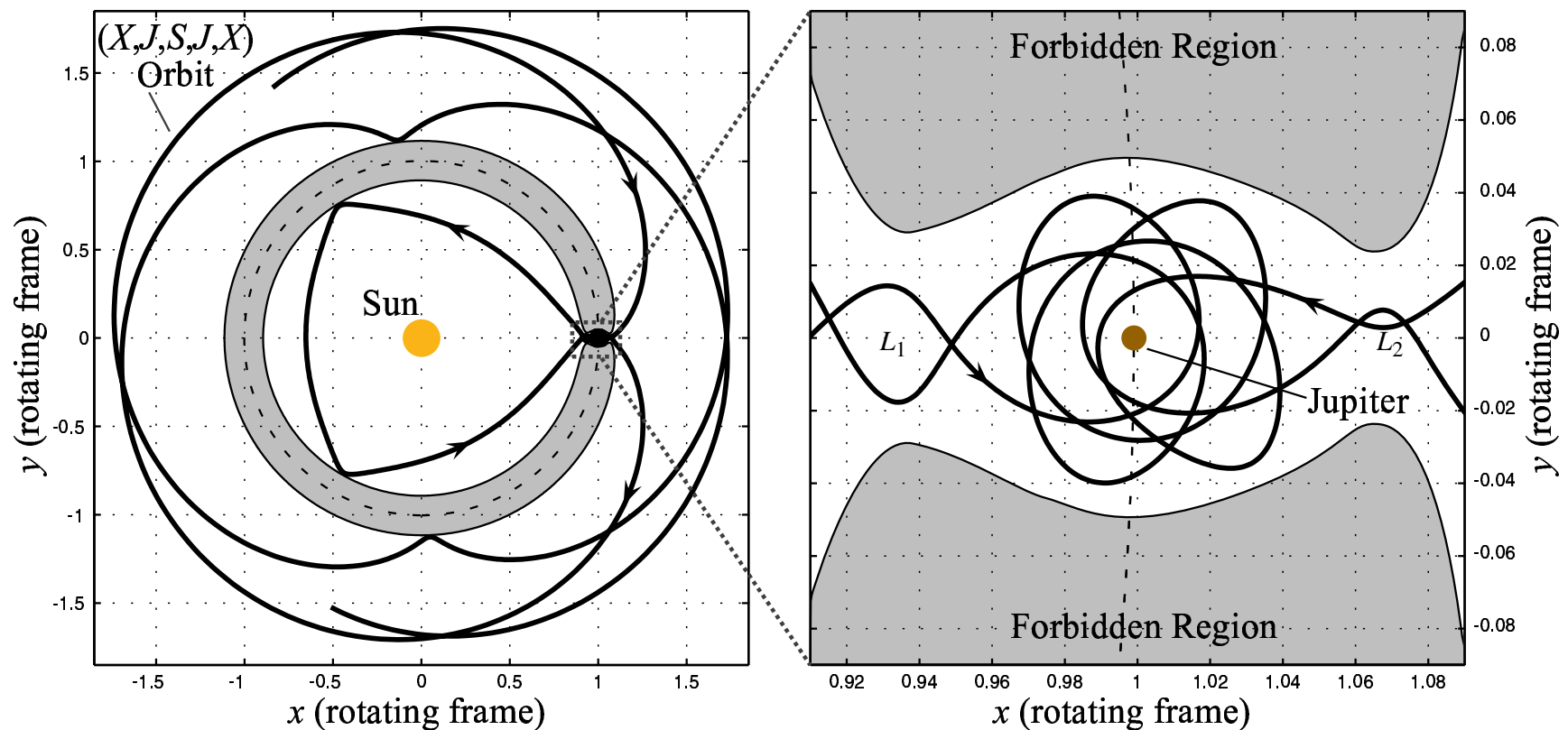
■ Major Result (B): Existence of Transitional Orbits

- ▶ **Symbolic sequence** used to label itinerary of each comet orbit.
- ▶ **Main Theorem:** For any admissible **itinerary**, e.g., $(\dots, \mathbf{X}, \mathbf{J}; \mathbf{S}, \mathbf{J}, \mathbf{X}, \dots)$, there exists an orbit whose **whereabouts** matches this **itinerary**.
- ▶ Can even specify **number of revolutions** the comet makes around Sun & Jupiter (plus L_1 & L_2).



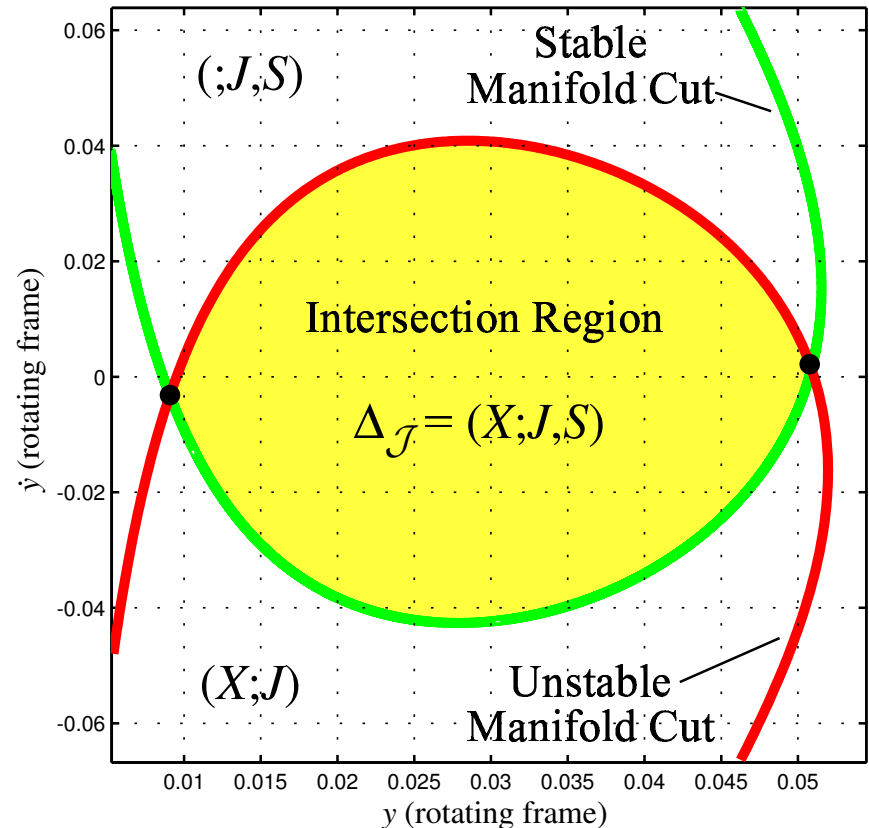
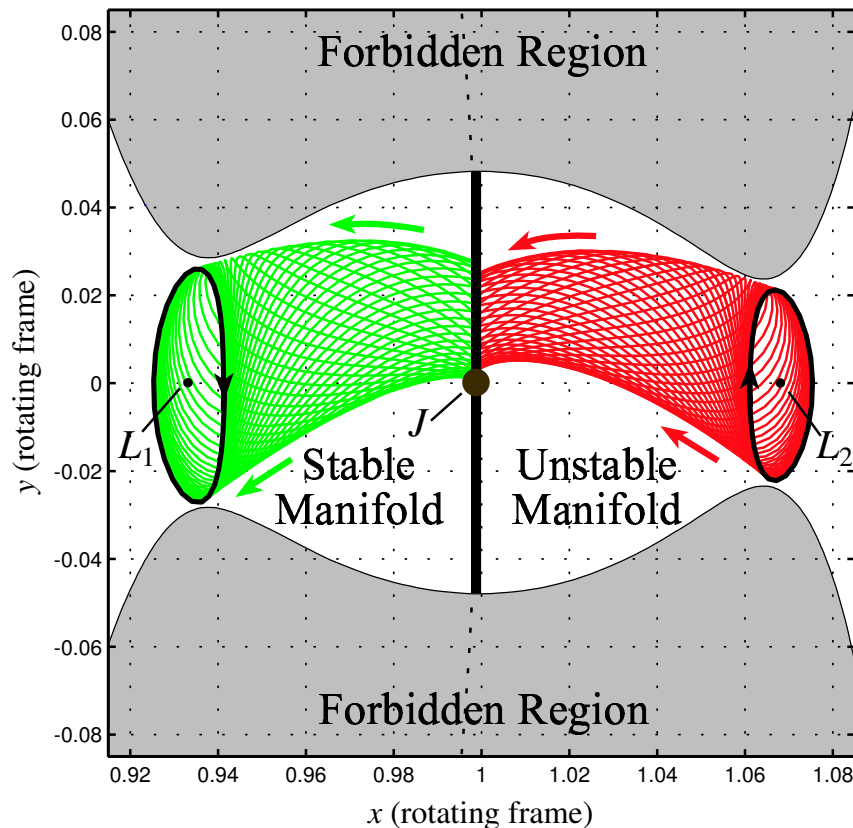
Major Result (C): Numerical Construction of Orbits

- ▶ Developed procedure to construct orbit with **prescribed itinerary**.
- ▶ Example: An orbit with itinerary $(X, J; S, J, X)$.



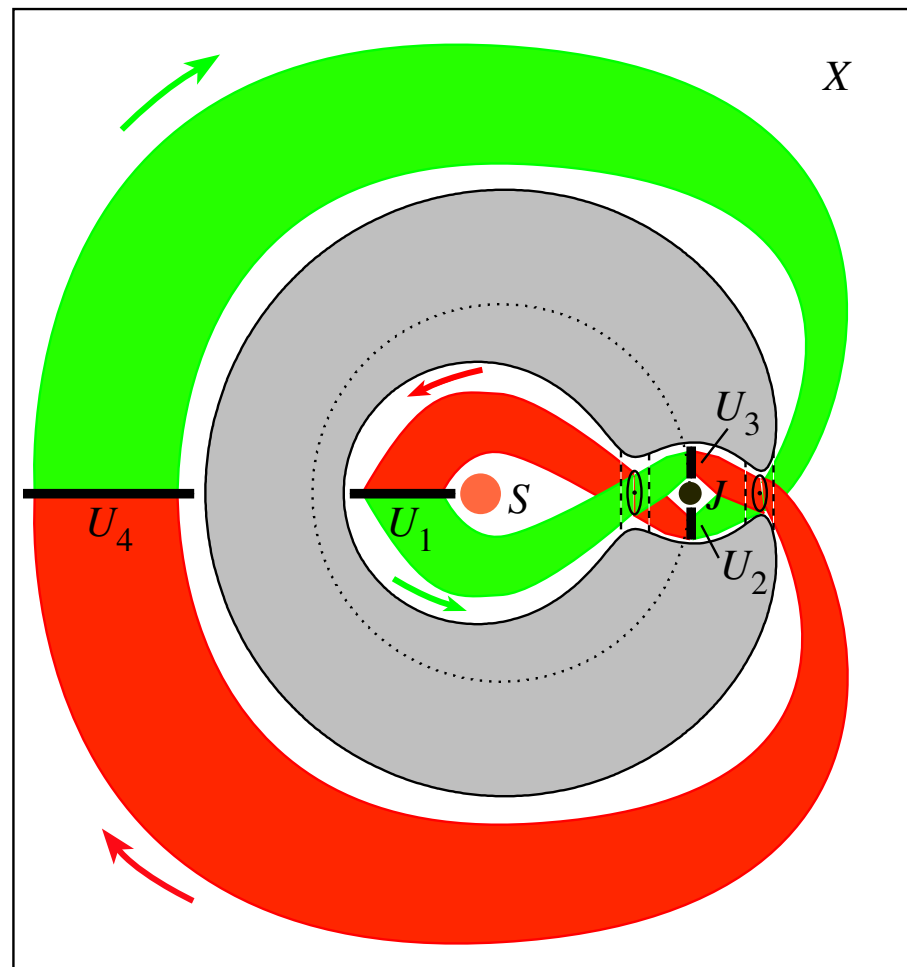
■ Details: Construction of $(\mathbf{J}, \mathbf{X}; \mathbf{J}, \mathbf{S}, \mathbf{J})$ Orbits

- ▶ Invariant manifold **tubes** separate transit from nontransit orbits.
- ▶ **Green curve** (Poincaré cut of L_1 **stable manifold**).
- ▶ **Red curve** (cut of L_2 **unstable manifold**).
- ▶ Any point inside the intersection region Δ_J is a $(\mathbf{X}; \mathbf{J}, \mathbf{S})$ orbit.



■ Details: Construction of $(J, X; J, S, J)$ Orbits

- ▶ The desired orbit can be constructed by
 - Choosing appropriate **Poincaré sections** and
 - linking invariant **manifold tubes** in right order.



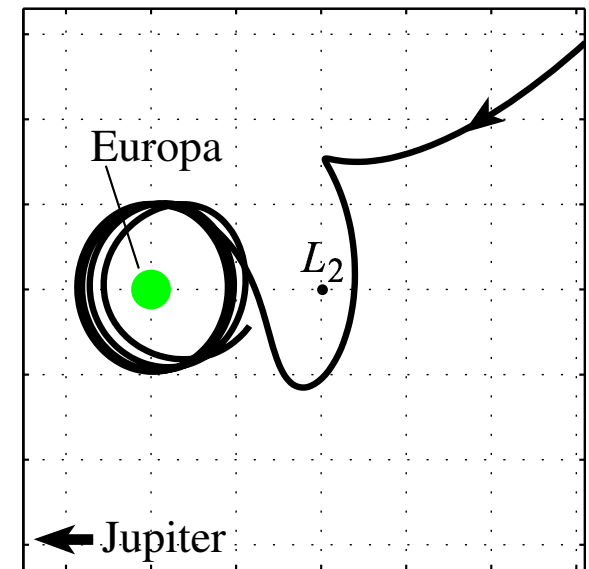
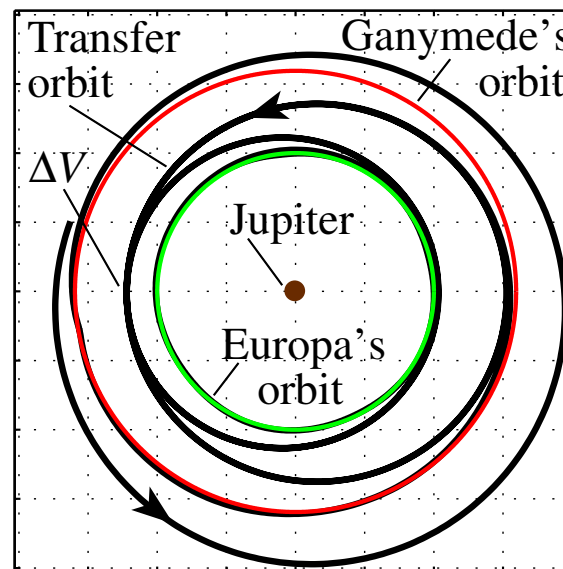
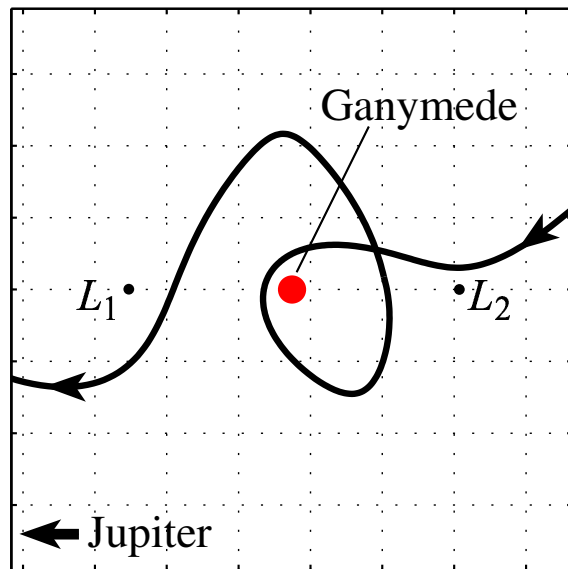
■ Petit Grand Tour of Jupiter's Moons

▶ Used **invariant manifolds**

to construct trajectories with interesting characteristics:

- Petit Grand Tour of Jupiter's moons.
1 orbit around **Ganymede**. 4 orbits around **Europa**.
- A ΔV nudges the SC from **Jupiter-Ganymede** system to **Jupiter-Europa** system.

▶ Instead of **flybys**, can orbit several moons for **any duration**.

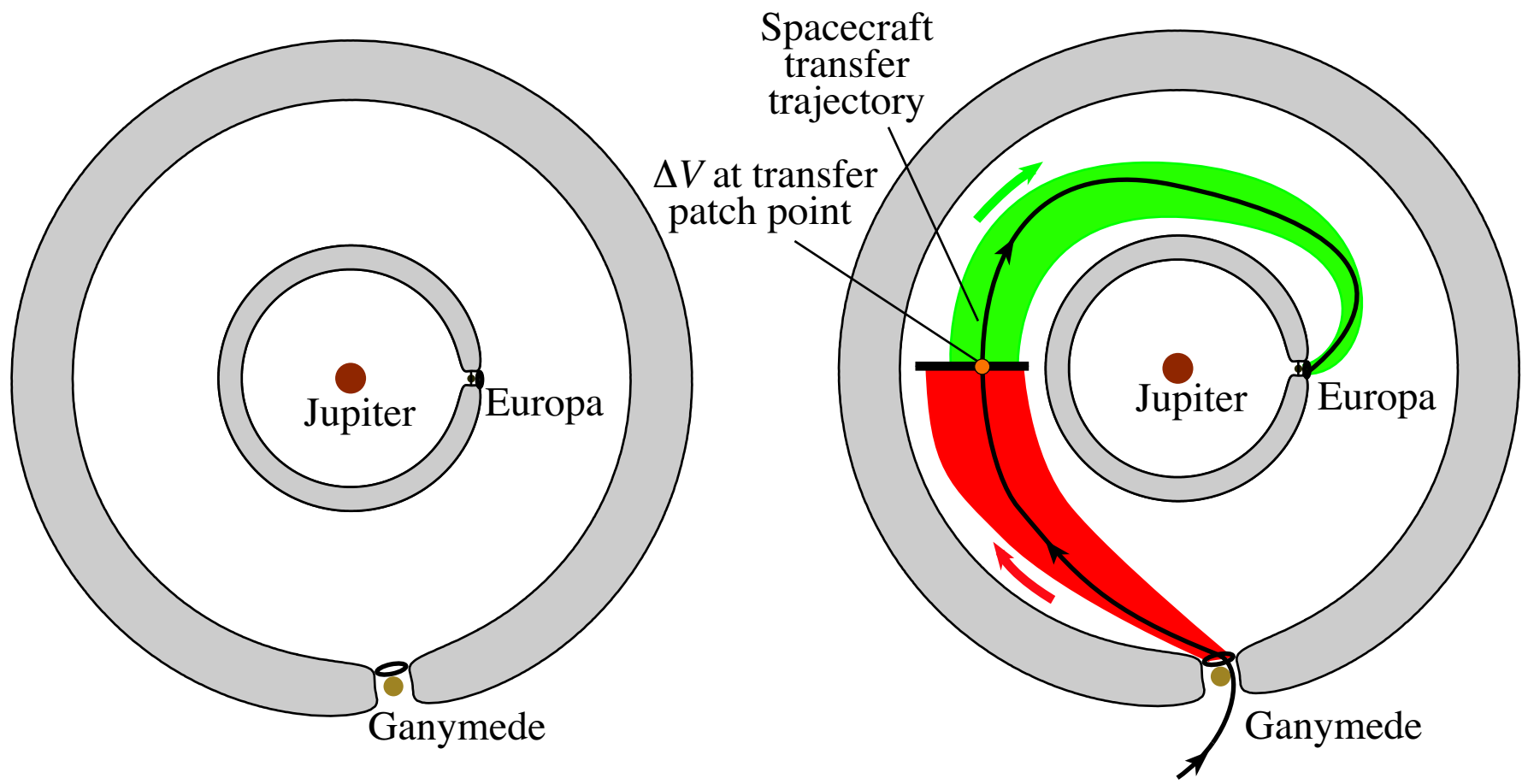


■ Petit Grand Tour of Jupiter's Moons

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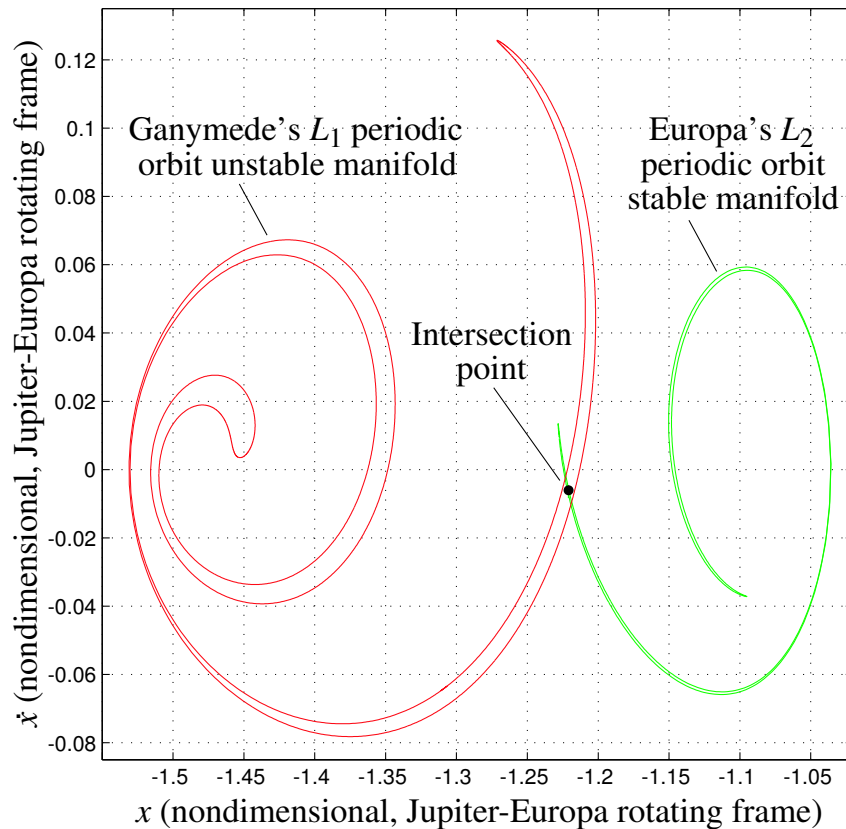
■ Petit Grand Tour of Jupiter's Moons

- ▶ Jupiter-Ganymede-Europa-SC 4-body system approximated as 2 **coupled 3-body systems**
- ▶ **Invariant manifold tubes** of **spatial 3-body systems** are linked in right order to construct orbit with desired itinerary.
- ▶ Initial solution refined in **4-body model**.

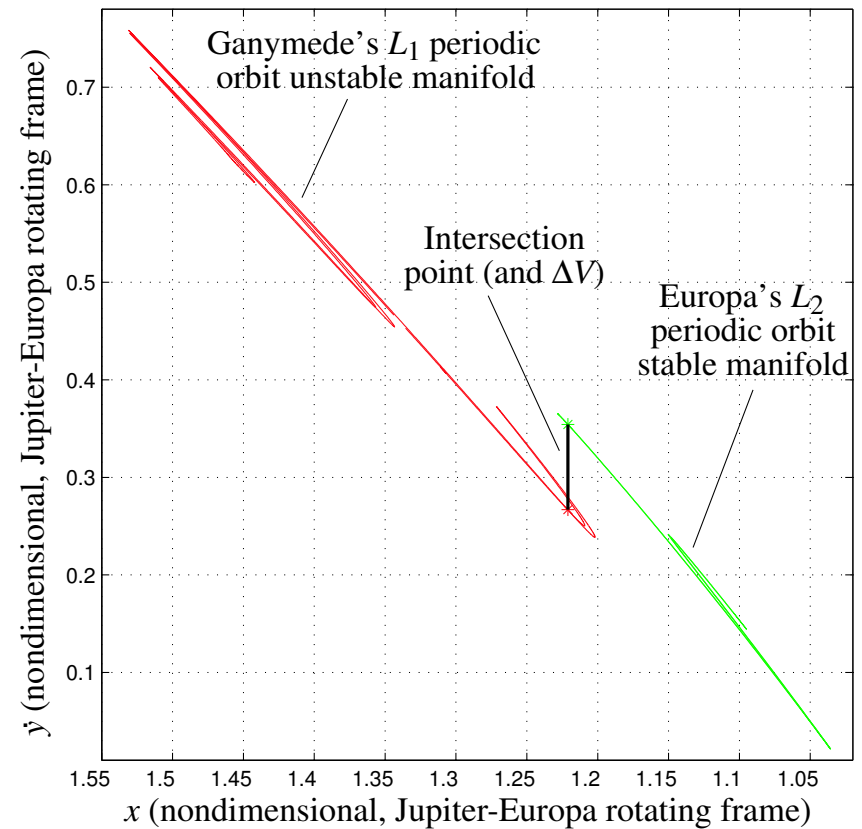


Intersection of Tubes: Poincaré Section

- ▶ Poincaré section: Vary configuration of the moons until,
 - (x, \dot{x}) -plane: Intersection found!
 - (x, \dot{y}) -plane: Velocity discontinuity since energies are different.
 - A rocket burn ΔV of this magnitude will make transfer trajectory “jump” from one tube to the other.



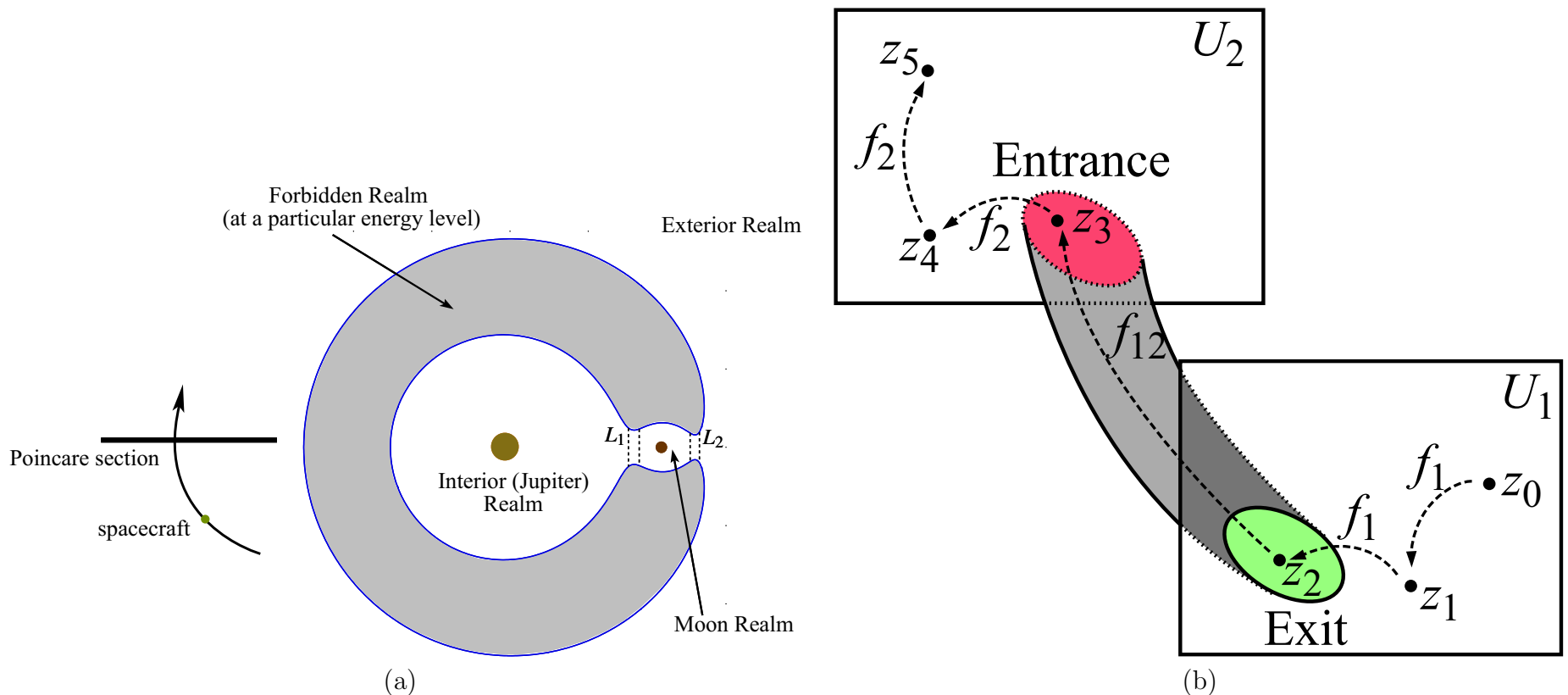
(a)



(b)

Look for Natural Pathways to Bridge the Gap

- ▶ **Tubes** of two 3-body systems **may not intersect** for awhile. May need large ΔV to “jump” from one tube to another.
- ▶ Look for **natural pathways** to bridge the gap
 - between z_0 where tube of one system **enters** and z_2 where tube of another system **exits** (into Europa realm) by “hopping” through **phase space**.



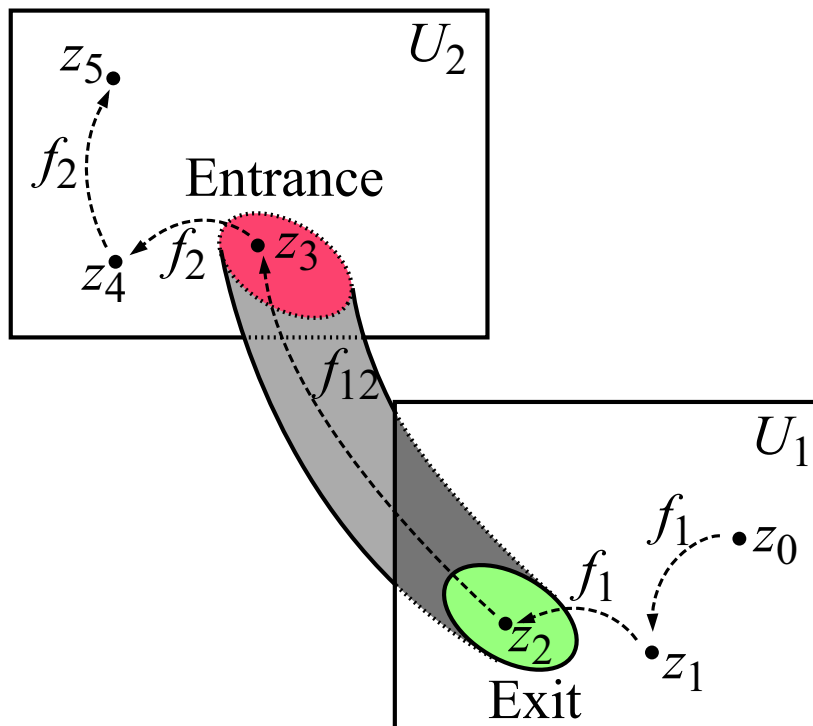
Transport in Phase Space via Tube & Lobe Dynamics

► By using

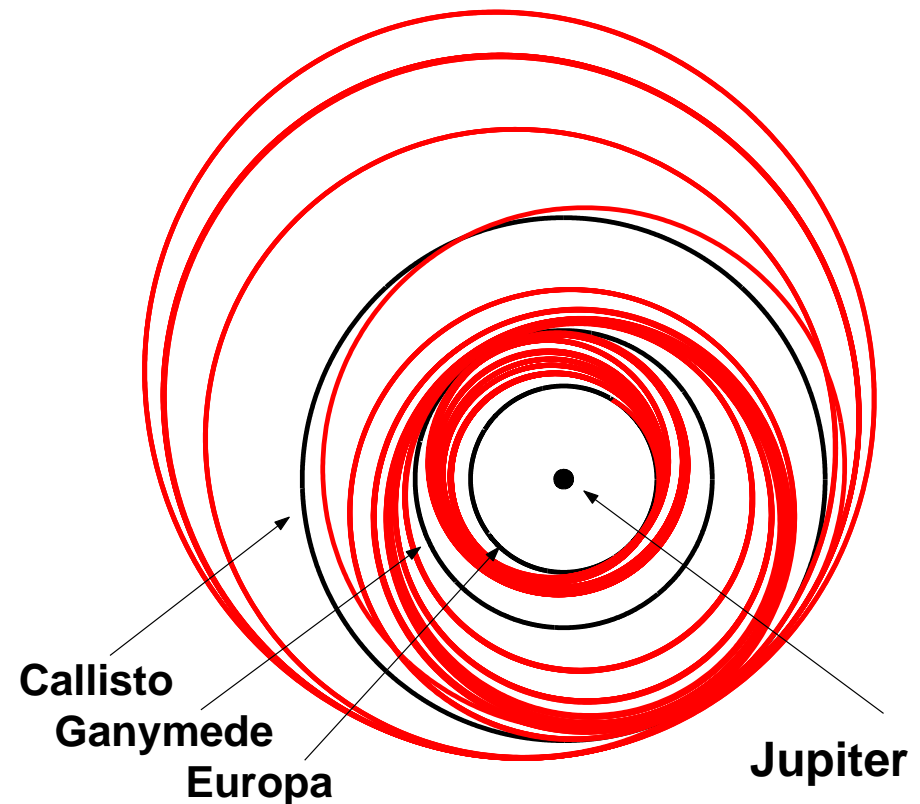
- **tubes** of rapid transition that connect realms
- **lobe dynamics** to hop through phase space,

New tour only needs $\Delta V = 20\text{m/s}$ (50 times less).

Low Energy Tour of Jupiter's Moons Seen in Jovicentric Inertial Frame



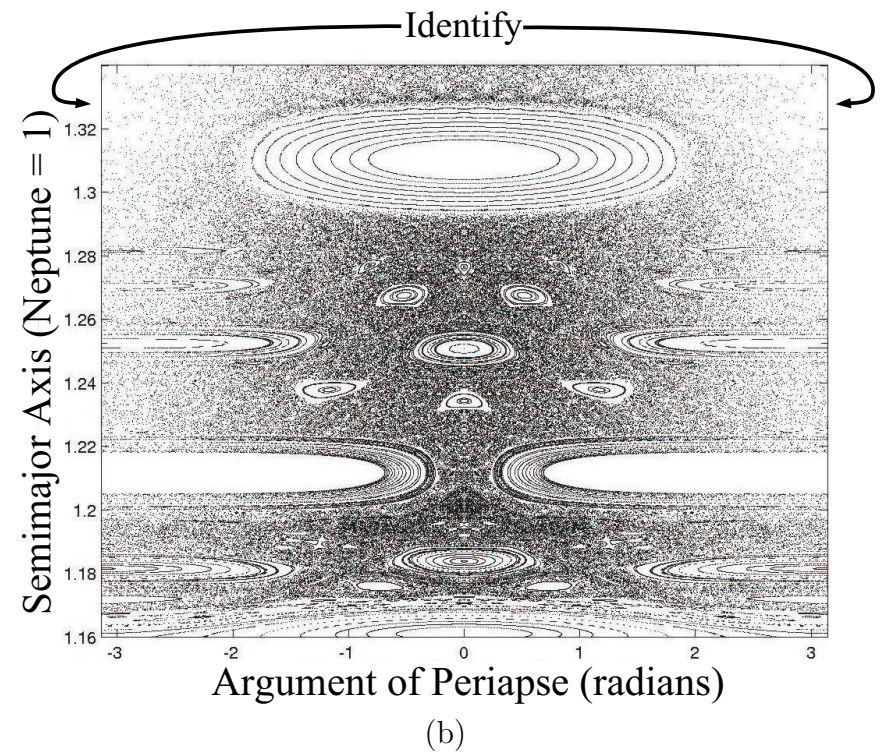
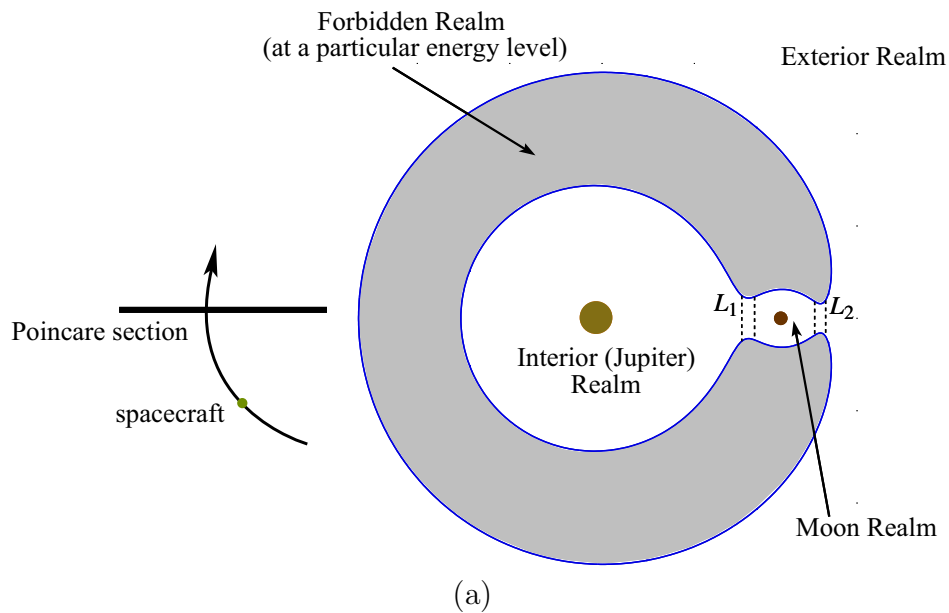
(a)



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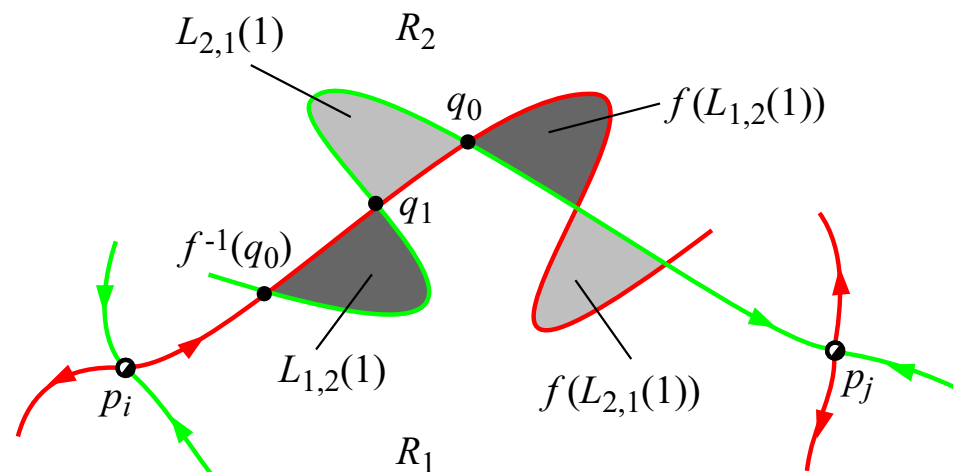
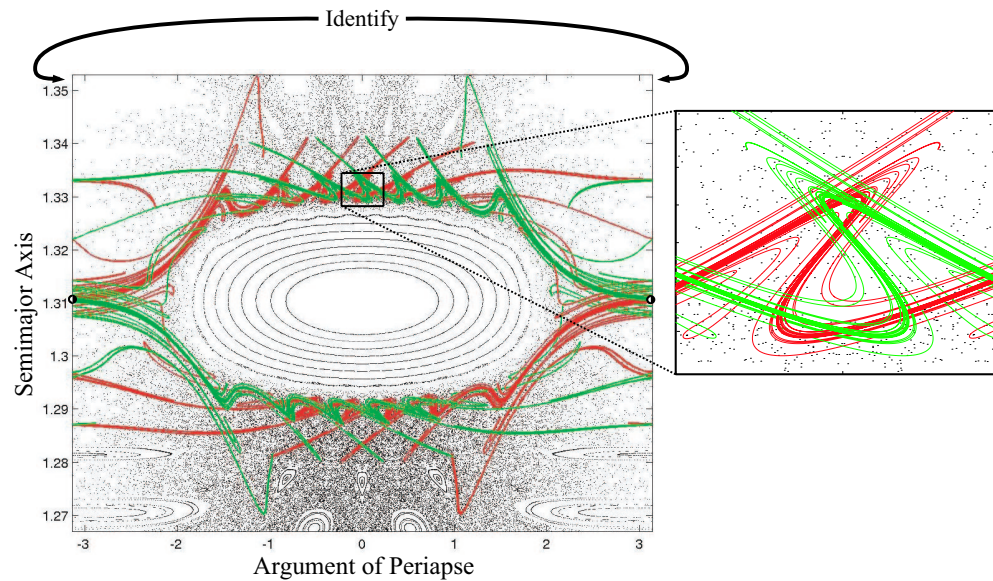
■ Tube Dynamics: Mixed Phase Space

- ▶ Poincaré section reveals **mixed phase space**:
 - resonance regions and
 - “chaotic sea”.



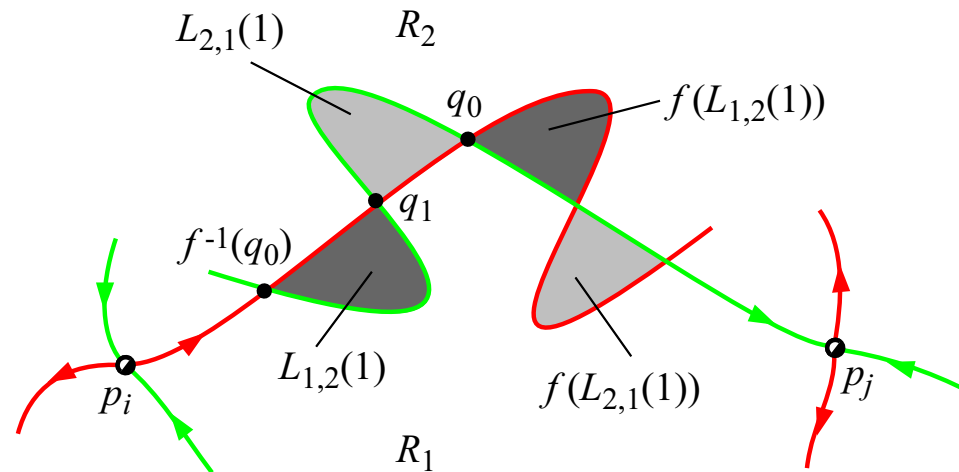
■ Transport between Regions via Lobe Dynamics

- ▶ **Invariant manifolds** divide phase space into resonance regions.
- ▶ Transport between regions can be studied via **lobe dynamics**.



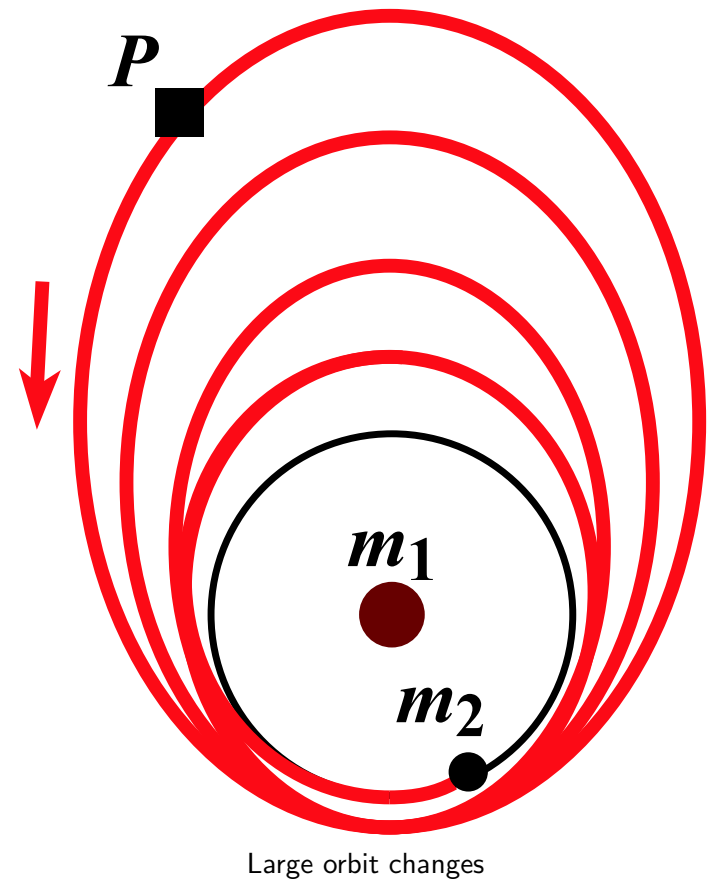
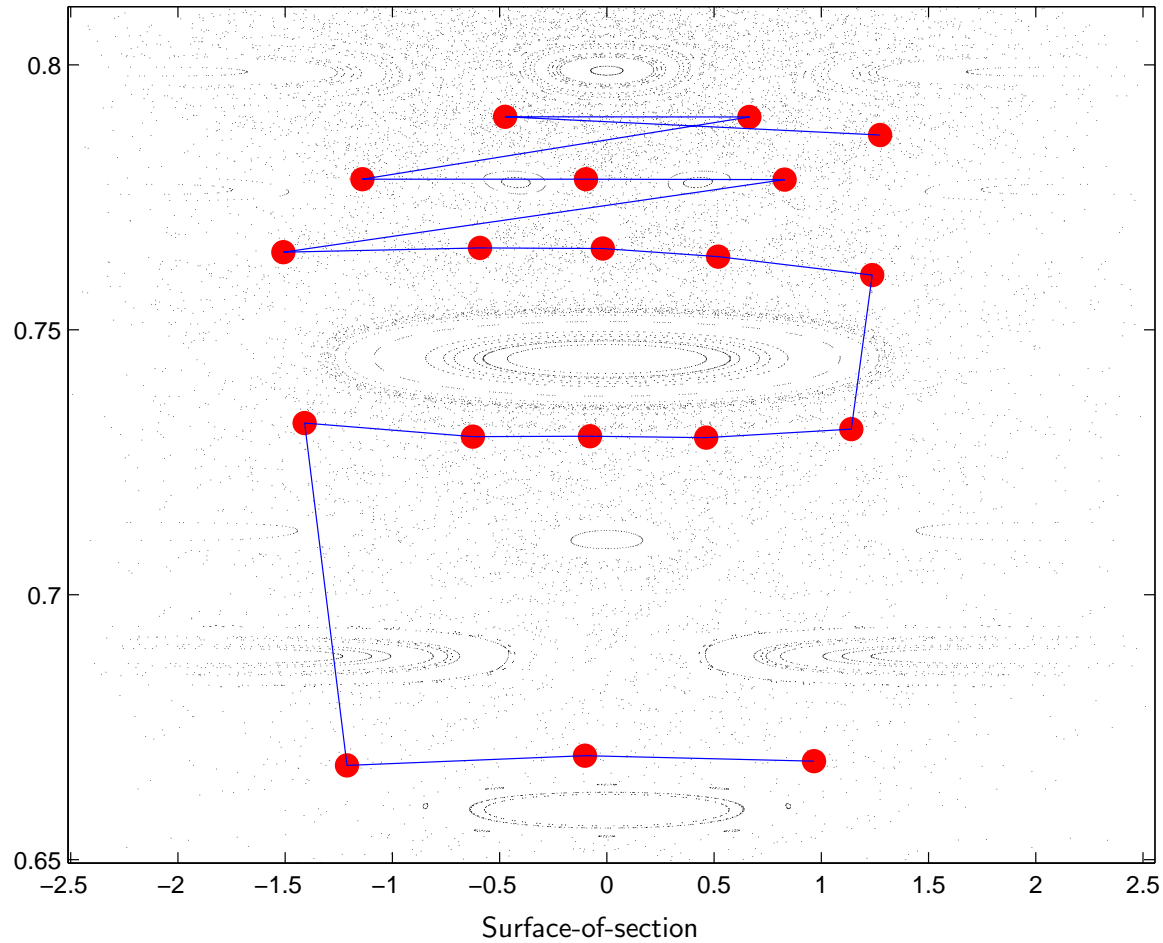
■ Transport between Regions via Lobe Dynamics

- ▶ Segments of **unstable** and **stable** manifolds form **partial barriers** between regions R_1 and R_2 .
- ▶ $L_{1,2}(1), L_{2,1}(1)$ are **lobes**; they form a **turnstile**.
 - In one iteration, only points from R_1 to R_2 are in $L_{1,2}$
 - only points from R_2 to R_1 are in $L_{2,1}(1)$.
- ▶ By studying pre-images of $L_{1,2}(1)$, one can find efficient way from R_1 to R_2 .



■ Hopping through Resonances in Low Energy Tour

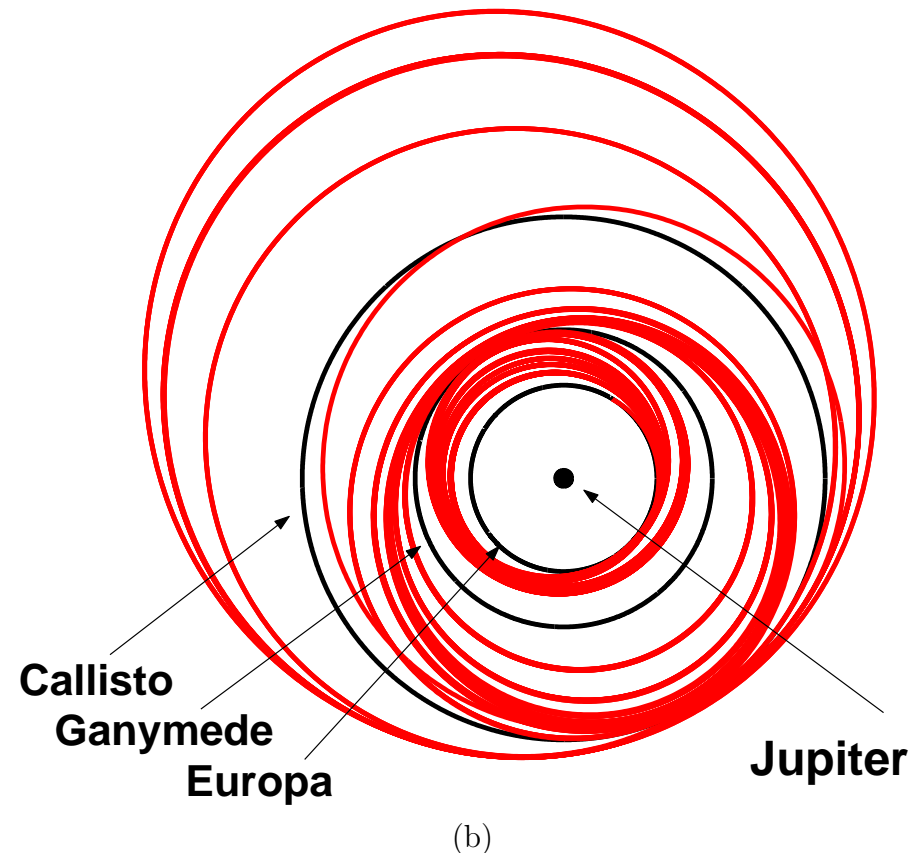
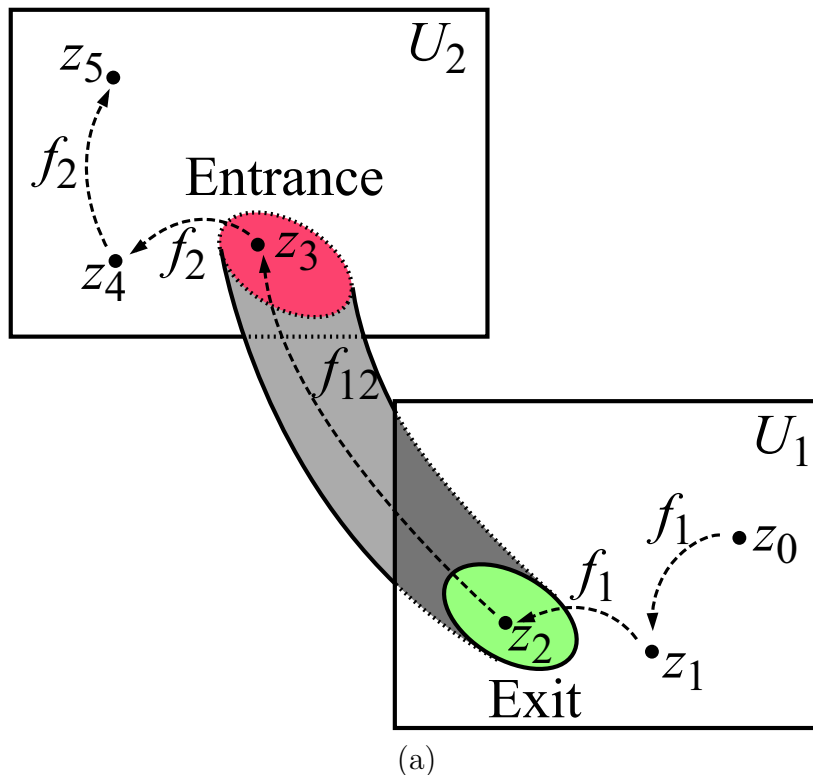
- ▶ Guided by lobe dynamics, **hopping** through resonances (essential for low energy tour) can be performed.



■ Tube/Lobe Dynamics: Transport in Solar System

- ▶ To use **tube** dynamics/**lobe** dynamics of **spatial** 3-body problem to **systematically** design low-fuel trajectory.
- ▶ Part of our program to study transport in solar system using **tube** and **lobe dynamics**.

Low Energy Tour of Jupiter's Moons Seen in Jovicentric Inertial Frame

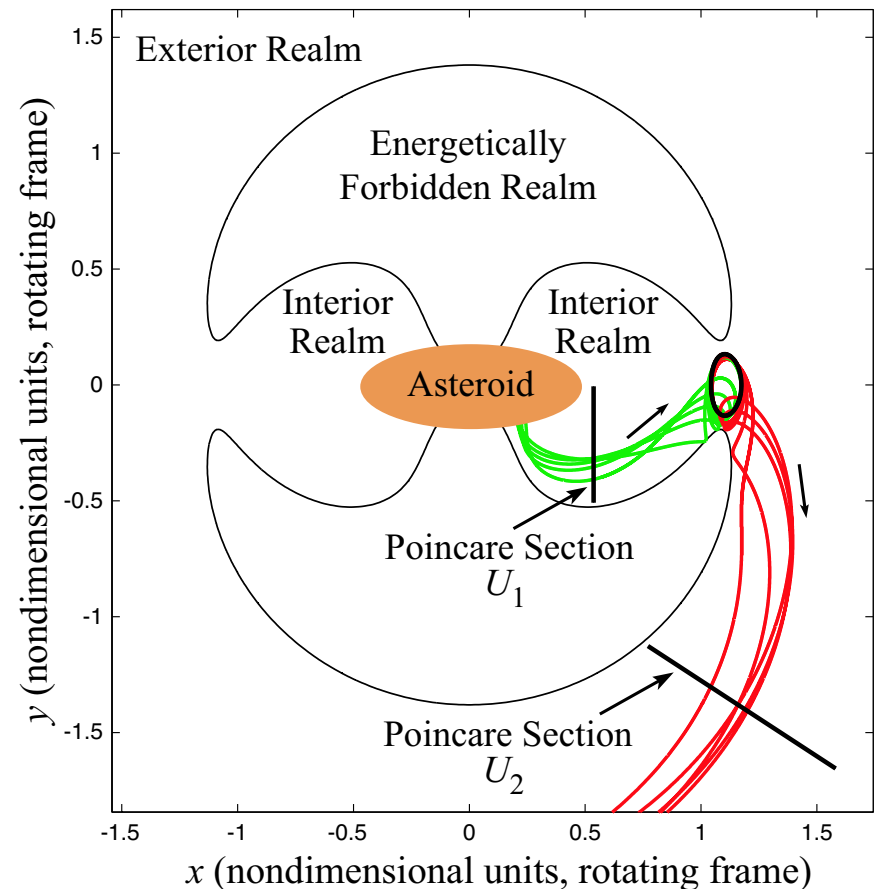


■ Tube/Lobe Dynamics: 2FBP/Asteroid Pairs

- ▶ To study dynamical interaction between 2 rigid bodies where their **rotational** and **translational** motions are coupled.
 - formation of binary asteroids (shown below are Ida and Dactyl)
 - evolution of asteroid rotational states



(a)



(b)

■ Multi-scale Dynamics of Biomolecules (ICB)

- ▶ Carry out **model reduction** (POD) for simple biomolecules, keeping chains of molecules and more complex systems in view.
- ▶ Identify **conformations** in simple molecular models using techniques of *AIS* and **set oriented** methods.
- ▶ Compute **transport rates** between different conformations by both **lobe dynamics** and **set oriented methods**.
- ▶ Collaborate with Institute of Collaborative Bio-Technology (ICB).

