

# Hopf Bifurcation

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Consider the planar system

$$\begin{aligned}\dot{x} &= -y + x(\mu - x^2 - y^2) \\ \dot{y} &= x + y(\mu - x^2 - y^2)\end{aligned}$$

The only critical point is at the origin and

$$D\mathbf{f}(\mathbf{0}, \mu) = \begin{bmatrix} \mu & -1 \\ 1 & \mu \end{bmatrix}$$

The origin is a stable or an unstable focus of this nonlinear system if  $\mu < 0$  or if  $\mu > 0$  respectively. To uncover the structure at  $\mu = 0$ , we rewrite the system in polar coordinates using  $x = r \cos \theta$ ,  $y = r \sin \theta$ ,  $\dot{r} = \frac{1}{r}(x\dot{x} + y\dot{y})$  and  $\dot{\theta} = \frac{1}{r^2}(x\dot{y} - y\dot{x})$  to find that

$$\begin{aligned}\dot{r} &= r(\mu - r^2) \\ \dot{\theta} &= 1\end{aligned}$$

We see that at  $\mu = 0$  the origin is a stable focus and for  $\mu > 0$  there is a stable invariant orbit

$$\Gamma_\mu : \gamma_\mu(t) = \sqrt{\mu}(\cos t, \sin t)^T$$

The curves  $\Gamma_\mu$  represent a one-parameter family of invariant orbits of this system.

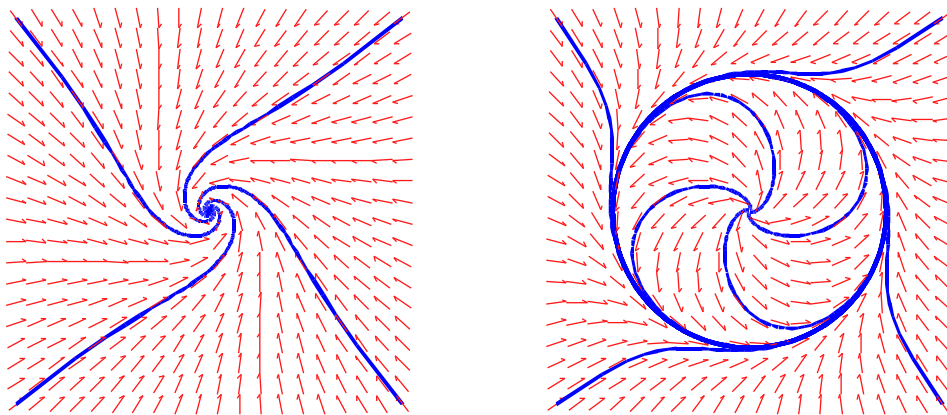


Figure 1: *Left: Phase portrait with  $\mu < 0$  illustrating a stable node at the origin. Right: A Hopf bifurcation occurs when  $\mu > 0$ , and an invariant stable orbit is born with radius  $\sqrt{\mu}$  as depicted above.*

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