

STEPHEN CREAUGH

1994  
(?)

195 FINAL PROJECT

Excellent  
Paper!

The Calogero hamiltonian

$$H = \frac{1}{2} \sum_i p_i^2 + \frac{1}{2} \sum_{i \neq j} 1/(x_i - x_j)^2$$

is shown to be integrable by showing that it is a reduction of the motion on  $T^*u(n)^*$  due to the hamiltonian  $H = \frac{1}{2} \text{TR } B^2$  (where  $B$  is momentum on  $T^*u(n)^*$ ). The group action in question is the lift of the coadjoint action to  $T^*u(n)^*$ .

The work is based on the paper

Hamiltonian Group Actions and Dynamical Systems  
of Calogero Type

by Kazhdan Kostant and Shuberg

STEPHEN CREAGH

- 195 PROJECT

Consider  $U(1)$ .  $\forall U \in U(1)$  we can write

$$U = e^{iH} \quad H \text{ hermitian}$$

In particular we can represent curves near  $I$  as

$$U(t) = e^{iHt}$$

which give the tangent vectors

$$U'(0) = iH$$

$\therefore \mathfrak{g} = U(1)$  consists of skew hermitian matrices  $iH$  which can be identified with the space of hermitian matrices  $H$ .  $U(1)^*$  can similarly be identified with the hermitian matrices using the scalar product

$$\langle A, B \rangle = \text{Tr } A^+ B$$

$\downarrow \quad \downarrow$   
 $U(1)^* \quad U(1)$

Then  $U(1)$  acts on  $U(1)^*$  according to

$$\text{Ad}_U H = U H U^{-1} = U H U^+$$

To find the action on  $U(1)^*$  consider

$$\langle A, \text{Ad}_{U^{-1}} B \rangle = \text{Tr } A^+ (U^+ B U)$$

$$= \text{Tr } u A^\dagger u^\dagger B$$

$$= \text{Tr } ((u A u^\dagger)^\dagger B)$$

$$= \langle u A u^\dagger, B \rangle$$

$$= \langle \text{Ad}_{u^{-1}}^* A, B \rangle$$

hence  $\text{Ad}_{u^{-1}}^* A = u A u^\dagger$   $A \in \mathfrak{u}(n)^*$   
which is the same action as on  $\mathfrak{u}(n)$

We can form  $T^* \mathfrak{u}(n)^* \cong \mathfrak{u}(n)^* \oplus \mathfrak{u}(n)$   
identifying  $\mathfrak{u}(n)^{**} \cong \mathfrak{u}(n)$  we regard  $\mathfrak{u}(n)^*$  as  
the configuration space. This can then be given the  
standard symplectic form. The action of  $\mathfrak{u}(n)$  on  
 $\mathfrak{u}(n)^*$  can then be lifted to  $T^* \mathfrak{u}(n)^*$  by the  
cotangent lift

since  $\Phi_u A = \text{Ad}_{u^{-1}} A = u A u^\dagger$  is linear in  
 $A$ ,  $T \text{Ad}_{u^{-1}}$  is given by the same expression

$$\text{This } \langle \xi, T^* \Phi_{u^{-1}} \eta \rangle = \langle T \Phi_{u^{-1}} \xi, \eta \rangle$$

$$= \langle u^\dagger \xi u, \eta \rangle = \langle \xi, u \eta u^\dagger \rangle$$

hence the lifted action is

$$(A, B) \xrightarrow{T^*\Phi_2} (uAu^{-1}, uBu^{-1}) \quad (1)$$

$u(A)^* \oplus u(A)$

### SYMPLECTIC FORM

The canonical 1-form  $\theta$  is defined by 1-4-2 of the notes

$$\theta_{(A,B)}(g, \eta) = \langle Tz_{g^*} \cdot (g, \eta), B \rangle$$

$$(A, B) \in g^* \oplus g \quad \left( \begin{array}{l} \text{here - path 1 wide} \\ g^* \text{ for } u(A)^* \text{ etc} \end{array} \right)$$

$$g, \eta \in T_{(A,B)} g^* \oplus g \cong g^* \oplus g$$

(note: because of the identification  $g^{**} \cong g$  the brackets  $\langle, \rangle$  have backwards entries)

$$= \langle g, B \rangle$$

$$\therefore \theta_{(A,B)}(g_{(A,B)}, \eta_{(A,B)}) = \langle g, B \rangle \quad (2)$$

differentiating gives

$$\Omega_{(A,B)} \left( (g_{(A,B)}^1, \eta_{(A,B)}^1), (g_{(A,B)}^2, \eta_{(A,B)}^2) \right)$$

As in 1-1-2 (2')

$$= \langle g^1, \eta^2 \rangle - \langle g^2, \eta^1 \rangle$$

## INFINITESIMAL GENERATOR

Given  $H \in \mathfrak{g}$  then this corresponds to the curve  $u(t)$   $u'(0) = iH$

From this we get  $\exp Ht = e^{iHt}$ . Then the infinitesimal generator on  $\mathfrak{g}^* \oplus \mathfrak{g}$  is given by corresponding to  $\mathfrak{g} \in \mathfrak{g}$  is

$$\mathfrak{g}_P|_{A,B} = \left. \frac{d}{dt} \exp_{\mathfrak{g}}(A, B) \right|_{t=0}$$

$$= \left. \frac{d}{dt} \left( e^{i\mathfrak{g}t} A e^{-i\mathfrak{g}t}, e^{i\mathfrak{g}t} B e^{-i\mathfrak{g}t} \right) \right|_{t=0}$$

$$\text{Now } e^{i\mathfrak{g}t} A e^{-i\mathfrak{g}t} = A + it[\mathfrak{g}, A] + O(t^2)$$

$\forall \mathfrak{g}, A$  - Baker Hausdorff formula

$$\Rightarrow \left. \frac{d}{dt} \left( e^{i\mathfrak{g}t} A e^{-i\mathfrak{g}t} \right) \right|_{t=0} = i[\mathfrak{g}, A]$$

$$\text{thus } \boxed{\mathfrak{g}_P|_{(A,B)} = (i[\mathfrak{g}, A], i[\mathfrak{g}, B])} \quad (3)$$

Sledge-hammer  
for something  
simple.

MOMENTUM MAP

The momentum map is now determined by

$$\begin{aligned} \mathcal{J}(\mathfrak{g})(A, B) &= \theta(A, B) \cdot \{p\}_{A, B} \\ &= \theta(A, B) \cdot (i(\mathfrak{g}, A), i(\mathfrak{g}, B)) \end{aligned}$$

$$= \langle i(\mathfrak{g}, A), B \rangle \quad \text{by (2)}$$

$$= \text{Tr } i(\mathfrak{g}A - A\mathfrak{g})B$$

$$= \text{Tr } i\mathfrak{g}AB - \text{Tr } iA\mathfrak{g}B$$

$$= \text{Tr } i\mathfrak{g}AB - \text{Tr } i\mathfrak{g}BA$$

$$= \text{Tr } i\mathfrak{g}[A, B]$$

$$= \langle i[A, B], \mathfrak{g} \rangle$$

$$\Rightarrow \boxed{\mathcal{J}(A, B) = i[A, B]} \quad (4)$$

Theory has it that the momentum map  
for a lifted action is equivariant and  
we can immediately see that this is the  
case since

$$u_* \bar{\sigma}(A, B) = u_* (i[A, B]) u^{-1}$$

$$= i[uAu^{-1}, uBu^{-1}]$$

$$= \bar{\sigma}(uAu^{-1}, uBu^{-1})$$

$$= \bar{\sigma}(u_* (A, B))$$

Now we consider reduction to  $\overline{\mathfrak{D}}^{-1}(\mu)/G_\mu$  for a particular  $\mu$  of the form

$$\mu = \lambda I + |\nu\rangle\langle\nu| \in \mathfrak{g}^* \quad \text{where } \nu \in \mathbb{C}^n$$

In this case we get

$$\overline{\mathfrak{D}}^{-1}(\mu) = \{ (A, B) \in \mathfrak{g}^* \oplus \mathfrak{g} \mid i[A, B] = \lambda I + |\nu\rangle\langle\nu| \}$$

The isotropy group  $G_\mu$  is then given by

$$G_\mu = \{ C \in U(n) \mid |C\nu\rangle\langle C\nu| = |\nu\rangle\langle\nu| \}$$

$$\left( \text{where I use } \overline{\mathfrak{D}}_C \circ \mu = C(\lambda I + |\nu\rangle\langle\nu|)C^\dagger = \lambda I + |C\nu\rangle\langle C\nu| \right)$$

$$= \{ C \in U(n) \mid C\nu = e^{i\theta} \nu \}$$

\* Thus, to form  $\overline{\mathfrak{D}}^{-1}(\mu)/G_\mu$  we identify pairs  $(A, B)$  which are unitary equivalent by unitary matrices satisfying

$$C\nu = e^{i\theta} \nu$$



## SPECIALISATION

Now take  $v$  to be of the form

$$v = \begin{pmatrix} 1 \\ \vdots \\ 1 \end{pmatrix} \text{ ie all } 1\text{'s}$$

$$\text{and } \lambda = -1$$

$$\text{so } \mu = |v\rangle\langle v| - I$$

$$= \begin{pmatrix} 0 & & 1 \\ & 0 & \\ 1 & & 0 \end{pmatrix}$$

ie zero's on the diagonal, 1's every where else

Now take  $(A, B) \in \tilde{\mathcal{J}}^{-1}(\mu)$  and diagonalise  $A$  with the unitary matrix  $C$

$$\text{ie } CAC^{-1} = D \text{ diagonal}$$

$$\text{If we write } CBE^{-1} = E \text{ then,}$$

$$i[D, E] = -I + |w\rangle\langle w|$$

$$\text{where } w = Cv$$

The diagonal entries of  $[D, E]$  are zero since

$$\begin{aligned} ([D, E])_{ii} &= \sum_j D_{ij} E_{ji} - E_{ij} D_{ji} \quad \left( \begin{array}{l} D \text{ diagonal} \\ \Rightarrow i=j \text{ term} \\ \text{contributes} \end{array} \right) \\ &= D_{ii} E_{ii} - E_{ii} D_{ii} \\ &= 0 \end{aligned}$$

This implies that  $|w\rangle\langle w| - I$  has zero diagonal entries, but these are just  $v_i^* w_i - 1$ , so,

$$|w_i| = 1$$

$$w_i = e^{i\theta_i}$$

If we conjugate  $A, B$  by  $C' = \text{diag}(e^{-i\theta_i}) C$  rather than  $C$  we get

$$C' A C'^{-1} = D \quad \left( \begin{array}{l} \text{unchanged since } z \text{ diagonal} \\ \text{matrices commute} \end{array} \right)$$

$$C' B C'^{-1} = E'$$

$$\text{But now } C' \dagger = \left( \text{diag } e^{-i\theta_i} \right) \left( e^{i\theta_i} \right) = \dagger!$$

By comparing with  $\star$  we now see that  $(A, B)$  and  $(D, E')$  are in the same equivalence class of  $\bar{\mathbb{R}}^1(\mu)/G_{\mathbb{R}}$  i.e. they both project embed do the same point. If  $\mu$  is

that  $(D, E')$  can be used to represent the class of  $(A, B)$  in which case we can regard  $\mathcal{S}^{-1}(\mu)/G_\mu$  as consisting of elements of the form  $(D, E')$  where  $D$  is diagonal (whose entries consist of the eigenvalues of the  $A$ 's in the class of  $\mathcal{S}^{-1}(\mu)/G_\mu$ ). To find out what  $E'$  is like consider the following.

$$\begin{aligned} ([D, E'])_{ij} &= \sum_k D_{ik} E'_{kj} - E'_{ik} D_{kj} \\ &= x_i E'_{ij} - E'_{ij} x_j \end{aligned}$$

(where  $x_i = D_{ii}$  are the eigenvalues of  $A$ )

Using  $[D, E'] = \mu$  gives  $i E'_{ij} (x_i - x_j) = 1 - \delta_{ij}$

$\Rightarrow$  ①  $i \neq j \Rightarrow x_i \neq x_j$

②  $E'_{ij} = \frac{-1}{x_i - x_j}$

Thus the off diagonal elements depend on  $x_i$ . The diagonal elements however are independent and we can denote these by  $y_i$ . Thus we have

$$D = \begin{pmatrix} x_1 & & 0 \\ & \ddots & \\ 0 & & x_n \end{pmatrix} \quad E' = \begin{pmatrix} y_1 & & \frac{-1}{x_1 - x_2} \\ & \ddots & \\ \frac{-1}{x_i - x_j} & & y_n \end{pmatrix}$$

From ① it follows we can order the  $x_i$ 's in a unique way

$$x_1 < x_2 < \dots < x_n$$

Hence for a given class we can choose a representative in a unique way namely  $(D, E')$  with the ordering above. Hence we can identify  $\bar{\Sigma}^{-1}(\mu)/G_\mu$  as the space of

$$\left\{ (D, E') \mid D = \begin{pmatrix} x_1 & & 0 \\ & \ddots & \\ 0 & & x_n \end{pmatrix}, E' = \begin{pmatrix} y_1 & & \frac{-i}{x_i - x_j} \\ & \ddots & \\ \frac{-i}{x_i - x_j} & & y_n \end{pmatrix} \right\}$$

$x_1 > x_2 > \dots > x_n$

(It's clear that we can reverse the argument earlier to show any pair of this form is in  $\bar{\Sigma}^{-1}(\mu)/G_\mu$  and so the  $x$ 's and  $y$ 's are all independent)

hence a coordinate system is given on  $\bar{\Sigma}^{-1}(\mu)/G_\mu$  by

$$(x_1, \dots, x_n, y_1, \dots, y_n)$$

Now in the paper it is shown that the coordinates  $(x_1, \dots, x_n, y_1, \dots, y_n)$  are actually canonical. I propose to show this by a different route, namely by using

$$\hat{\pi}_\mu^* \Omega_\mu = i_\mu^* \Omega$$

good!

To use this, first consider the subset of the tangent space to  $\mathbb{R}^n(\mu) / G_\mu$

given curves  $D(t) = \begin{pmatrix} x_1(t) & 0 \\ 0 & \ddots & 0 \\ 0 & & x_n(t) \end{pmatrix}$

$$E(t) = \begin{pmatrix} y_1(t) & \frac{-i}{x_i(t) - x_j(t)} \\ \vdots & \vdots \\ \frac{-i}{x_i(t) - x_j(t)} & y_n(t) \end{pmatrix}$$

we get

$$D'(0) = \begin{pmatrix} x_1'(0) & 0 \\ 0 & \ddots & 0 \\ 0 & & x_n'(0) \end{pmatrix}$$

$$E^1(0) = \begin{pmatrix} y_1'(0) & \frac{+i}{(x_i - x_j)^2} (x_i'(0) - x_j'(0)) \\ \vdots & \vdots \\ \frac{i}{(x_i - x_j)^2} (x_i'(0) - x_j'(0)) & y_n'(0) \end{pmatrix}$$

Thus we can identify tangent vectors  $(\xi_1, \dots, \xi_n, \eta_1, \dots, \eta_n)$  in  $T_{x, \mu} \mathbb{R}^n(\mu) / G_\mu$  with the tangent vectors to  $\mathfrak{g}^* \oplus \mathfrak{g}$  of the form

$$\left( \begin{pmatrix} \xi_1 & 0 \\ 0 & \ddots & 0 \\ 0 & & \xi_n \end{pmatrix}, \begin{pmatrix} \eta_1 & \vdots & \frac{\xi_i - \xi_j}{(x_i - x_j)^2} \\ \vdots & \ddots & \vdots \\ \frac{\xi_i - \xi_j}{(x_i - x_j)^2} & \eta_n \end{pmatrix} \right)$$

Writing out  $\hat{\pi}_\mu^* \Omega_\mu = i_\mu^* \Omega$  explicitly, we find

$$\begin{aligned} \Omega_\mu \left( T_{(A,B)} \hat{\pi}_\mu (q^1, \eta^1)_{(A,B)}, T_{(A,B)} \hat{\pi}_\mu (q^2, \eta^2)_{(A,B)} \right) \\ = \Omega \left( (q^1, \eta^1)_{(A,B)}, (q^2, \eta^2)_{(A,B)} \right) \\ = \langle q^1, \eta^2 \rangle - \langle q^2, \eta^1 \rangle \end{aligned}$$

In particular we can take  $(A,B) = (D,E)$  as constructed earlier in which case

$$\begin{aligned} q^\alpha &= \begin{pmatrix} q_1^\alpha & & 0 \\ & \ddots & \\ 0 & & q_n^\alpha \end{pmatrix} \\ \eta^\alpha &= \begin{pmatrix} \eta_1^\alpha & & i \frac{q_1^\alpha - q_n^\alpha}{(x_1 - x_n)^2} \\ & \ddots & \\ & & \eta_n^\alpha \end{pmatrix} \end{aligned} \quad \alpha = 1, 2$$

$$\begin{aligned} \text{in which case } T_{(A,B)} \hat{\pi}_\mu (q^\alpha, \eta^\alpha)_{(D,E)} &\sim (q_1^\alpha, \dots, q_n^\alpha, \eta_1^\alpha, \dots, \eta_n^\alpha) \\ \text{so } \Omega_\mu \left( (q^1, \eta^1), (q^2, \eta^2) \right) &= \text{Tr}(q^1 \eta^2) - \text{Tr}(q^2 \eta^1) \end{aligned}$$

Since  $q^\alpha$  is diagonal only the diagonal elements of  $\eta^\alpha$  contribute (ie the  $\eta_i^\alpha$ ) giving

$$\Omega_{\mu}((\underline{q}^1, \underline{q}^1), (\underline{q}^2, \underline{q}^1)) = \sum_i (\underline{q}^1_i \underline{q}^2_i - \underline{q}^2_i \underline{q}^1_i)$$

$$= \langle \underline{q}^1 | \underline{q}^2 \rangle - \langle \underline{q}^2 | \underline{q}^1 \rangle \quad (\because x, y \text{ canonical coordinates!})$$

OK There is a confusion here between the matrices  $g, \eta$  and the vectors  $\underline{q}, \underline{q}$  which I try to eliminate by writing bars under the vectors. Also I distinguish the innerproducts in each case by

$$\langle g, \eta \rangle = \text{Tr } g \eta$$

$$\langle \underline{q} | \underline{q} \rangle = \sum_i \eta_i q_i$$

↑  
central bar

From this we see that the coordinates  $(x, \dots, x_n, y, \dots, y_n)$  are in fact canonical as claimed!  $\Rightarrow \Rightarrow$

$$\Omega_{\mu} = dx^i \wedge dy_i$$

Now consider the function  $\wedge^n \mathfrak{g}^* \oplus \mathfrak{g}$  defined by

$$(A, B) \longmapsto \frac{1}{2} \text{Tr } B^2 = H \quad \text{say}$$

This is a  $\mathfrak{g}$  invariant function since conjugation by a unitary matrix does not change the trace. While we didn't do this in class your 1972 paper on reduction (Corollary 3) shows that since  $H$  is  $\mathfrak{g}$  invariant its flow on  $\mathfrak{g} \oplus \mathfrak{g}^*$  projects to the flow on  $\mathfrak{g}^*(\mu)/G_\mu$  which corresponds to the hamiltonian  $\tilde{H}$  on it defined by  $\tilde{H} \circ \pi_\mu = H|_{\mathfrak{g}^*(\mu)}$ . Specially

$$\begin{aligned} \tilde{H}(x_1, \dots, x_n, y_1, \dots, y_n) &= H[(D(x, y), E(x, y))] \\ &= \frac{1}{2} \text{Tr } E^2 \\ &= \frac{1}{2} \sum y_i^2 + \frac{1}{2} \sum_{i \neq j} \frac{1}{(x_i - x_j)^2} \end{aligned}$$

which is the Calogero Hamiltonian!

The point is that the flow of  $\frac{1}{2} \text{Tr } B^2 = \frac{1}{2} \langle B, B \rangle$  on  $\mathfrak{g}^* \oplus \mathfrak{g}$  is easier to integrate than the flow on the reduced system given by the Calogero hamiltonian! For this "free particle" hamiltonian we get the flow

$$(A, B) \longmapsto (A + tB, B)$$



To make the relationship between this flow and the Calogero flow more transparent consider putting coordinates on  $\mathfrak{S}^{-1}(\mu) / G_\mu$  as before except now by diagonalising  $B$  not  $A$ . The procedure is exactly the same except that the roles of  $A, D$  and  $B, E$  are reversed. In particular this leads to a change of sign in the off diagonal elements of  $D$  since they are determined by the relationship

$$[D, E] = \mu$$

with  $D, E$  reversed. Now we identify  $\mathfrak{S}^{-1}(\mu) / G_\mu$  with the points

$$\left\{ (\omega, \varepsilon) \mid D = \begin{pmatrix} \mu_1 & & \\ & \ddots & \\ & & \lambda_i - \lambda_j \\ & & & \mu_n \end{pmatrix}, \varepsilon = \begin{pmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{pmatrix} \right\}$$

Exactly the same reasoning as before gives

$$d\mathcal{H}_\mu = \sum_i \mu_i \wedge d\lambda_i$$

But now in these coordinates we get

$$\tilde{\mathcal{H}} = \frac{1}{2} \text{Tr } \varepsilon^2 = \frac{1}{2} \sum \lambda_i^2$$

which gives the flow  $\begin{cases} \mu_i \rightarrow \mu_i + \dot{\lambda}_i \\ \lambda_i \rightarrow \lambda_i \end{cases}$

Thus the relation-ship between the Calogero system and  $g + g^*$  has led us to the canonical transformation

$$x_i, y_i \rightarrow \mu_i, \lambda_i$$

for which  $H = \frac{1}{2} \sum y_i^2 + \frac{1}{2} \sum_{i \neq j} \frac{1}{(x_i - x_j)^2} \rightarrow \frac{1}{2} \sum \lambda_i^2$

which demonstrates the integrability of the Calogero system!

To relate the  $\mu_i$ 's to the  $\lambda_i$ 's a little further we note that the potential  $\sum 1/(x_i - x_j)^2$  is repulsive and so the particles fly apart. We thus expect  $1/(x_i - x_j) \rightarrow 0$  as  $t \rightarrow \infty$  and hence

$$E \rightarrow \begin{pmatrix} y_1 & & 0 \\ & \ddots & \\ 0 & & y_n \end{pmatrix} \text{ as } t \rightarrow \infty$$

Now from the construction of  $(D, E)$  and  $(D, \varepsilon)$  it is clear that they are simultaneously unitary equivalent. I.e.  $\forall t$  there is a  $U$  such that

$$D = U D U^{-1}, \quad \varepsilon = U E U^{-1}$$

From this we see that we must have

$$E \rightarrow \varepsilon, \quad U \rightarrow \text{diag } e^{i\lambda_i t} \text{ as } t \rightarrow \infty$$

From  $E \rightarrow \varepsilon$  we get  $\lambda_i = \gamma_i(\infty)$ .

Now if  $u = (u_{ij})_{ij}$  then

$$\begin{aligned} (D)_{ii} = \mu_i &= \sum u_{ij} D_{jk} u_{ik}^* \\ &= \sum u_{ij} x_j u_{ij}^* \\ &= \sum |u_{ij}|^2 x_j \end{aligned}$$

hence since  $|u_{ij}| \rightarrow \delta_{ij} \neq \infty$   
we see that

$$\mu_i \sim x_i \text{ as } t \rightarrow \infty$$

$\therefore$  we have the interpretations

$$\lambda_i = \gamma_i(\infty)$$

$$x_j \sim \mu_j \sim \mu_i + t \lambda_j \sim t \gamma_j(\infty)$$

Then  $\mu_i, \lambda_i$  can be thought of as the asymptotic forms of  $x_i, \gamma_i$  as  $t \rightarrow \infty$

## A note on the Sutherland system

In a similar way it is shown in the paper that the hamiltonian

$$H = \sum_i v_i^2 + \sum_{j \neq k} \frac{1}{\sin^2 \theta_j - \theta_k}$$

is completely integrable. This time the pre-reduced dynamics takes place on the configuration space  $U(n)$  with conjugation as the action. This time a momentum map

$$\bar{J}(g, \alpha) = g \alpha g^{-1} - \alpha$$

where we identify  $T^*U(n) \simeq U(n) \times u(n)^*$  but do not identify  $u(n)^*$  with hermitian matrices this time but leave them as skew-hermitian

As before we represent the classes  $\bar{J}^{-1}(k)/G_\mu$  (new  $\mu = -$  old  $\mu$ ) by particular matrices,  $(e, \beta)$   $e \in U(n)$   $\beta \in u(n)^*$  this time of the form

$$e = \begin{pmatrix} e^{i\theta_1} & & 0 \\ & e^{i\theta_2} & \\ 0 & & e^{i\theta_n} \end{pmatrix}, \quad \beta = \begin{pmatrix} \gamma_1 & & \\ & \ddots & \\ & & \gamma_n \end{pmatrix} \begin{matrix} \swarrow \\ \searrow \end{matrix} \begin{matrix} \frac{1}{e^{i(\theta_i - \theta_j)} - 1} \\ \vdots \end{matrix}$$

and as before we find that  $(\theta_1, \dots, \theta_n, \gamma_1, \dots, \gamma_n)$  are canonical variables. Then the Sutherland hamiltonian arises from the hamiltonian  $H = T_e \beta^* \beta$

The corresponding flow on  $T^*(U(n))$  as determined by the Hamiltonian

$$H(g, \alpha) = -\text{Tr } \alpha^t \alpha$$

is then trivially integrable being just momentum dependant and so we find that the Sutherland system is integrable.